



Center for Alternative Fuels, Engines & Emissions
West Virginia University

Final Report

In-Use Emissions Testing of Light-Duty Diesel Vehicles in the United States

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CAFFE Center for Alternative Fuels, Engines and Emissions

EXECUTIVE SUMMARY

The Center for Alternative Fuels, Engines and Emissions (CAFEE) at West Virginia University (WVU) was contracted by the International Council on Clean Transportation (ICCT) to conducted in-use testing of three light-duty diesel vehicles of European make, using a portable emissions measurement system (PEMS), over a variety of pre-defined test routes exhibiting diverse driving conditions pertinent to major United States population centers located in the state of California. Additionally, one vehicle was operated over an extended distance of nearly 4000km predominantly composed of highway driving conditions between California and Washington State. Also, two out of the three test vehicles were selected for chassis dynamometer testing at California Air Resources Board's (CARB) El Monte, CA vehicle certification test facility; however, a detailed discussion of these results is not part of this report.

The test vehicles were certified to US-EPA Tier2-Bin5 and California LEV-II ULEV emissions limits and were equipped with NO_x after-treatment technologies, including one lean-NO_x trap (LNT) (*Vehicle A*) and two urea-based selective catalytic reduction (SCR) systems (*Vehicles B* and *C*). Furthermore, all three test vehicles were thoroughly checked for possible engine or after-treatment malfunction codes using an ECU scanning tool prior to selecting a vehicle for this on-road measurement campaign, with none of them showing any fault code or other anomalies. The after-treatment system was assumed to be '*de-greened*' as all three vehicles have accumulated more than 3,000 to 4,000 miles, and no reduction in catalytic activity due to aging was expected as the total mileage was relatively low (< 15,000 miles) for all test vehicles. Gaseous emissions of NO_x, CO, THC and CO₂ were measured using the OBS-2200 PEMS from Horiba Ltd., while particulate number and mass concentrations were inferred from real-time particle charge measurements employing a Pegasor particle sensor, model PPS-M, from Pegasor.

Real-world NO_x emissions were found to exceed the US-EPA Tier2-Bin5 (at full useful life) standard by a factor of 15 to 35 for the LNT equipped vehicle, by a factor of 5 to 20 for one and at or below the standard for the second urea-SCR fitted vehicle over five pre-defined routes categorized based on their predominant driving conditions, namely, i) highway, ii) urban/suburban, and iii) rural-up/downhill driving. The second urea-SCR equipped vehicle exceeded the standard only during rural-up/downhill operating conditions by a factor of \sim 10. Most importantly, distance-specific NO_x emissions for the two high_-emitting vehicles were below the US-EPA Tier2-Bin5 standard for the weighted average over the FTP-75 certification

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cycle during chassis dynamometer testing at CARB's El Monte facility, with $0.022g/km \pm 0.006g/km (\pm 1\sigma, 2 \text{ repeats})$ and $0.016g/km \pm 0.002g/km (\pm 1\sigma, 3 \text{ repeats})$ for the LNT and urea-SCR equipped vehicles, respectively. It has to be noted that on-road emissions testing was performed with the engine and after-treatment in warmed-up condition (i.e. warm/hot start). Increased NO_x emissions are usually expected for cold-start as seen during the first portion (i.e. 'Bag-1') of the FTP-75 cycle, however, not for a-hot, running conditions as exhibited during 'Bag-2 and 3' of the FTP-75 cycle or on-road operation of the vehicle.

Generally, NO_x emissions were observed to be highest for rural-up/downhill and lowest for high-speed highway driving conditions with relatively flat terrain. The LNT after-treatment based vehicle was observed to emit significantly (> 19% to 90%) more NO_x emissions during diesel particulate filter (DPF) regeneration events. This was speculated to be due to an extended duration of lean exhaust conditions and a lack of frequent enrichment of the exhaust gas ($\lambda < 1$) while DPF regeneration was ongoing, leading to an inhibition of necessary LNT regeneration (D_eNO_x), and thus, causing the NO_x storage catalyst to become saturated with NO_x emissions that ultimately started to break through. *Vehicles B* and *C* were not observed to exhibit such a predominant increase in NO_x emissions during DPF regeneration events and changes in NO_x emissions rates were generally confounded by driver and traffic pattern influences.

Even though exceeding the US-EPA Tier2-Bin5 standard on average by a factor of 6 (i.e. $0.26g/km \pm 0.21g/km \ (\pm 1\sigma)$) during extended highway driving between California and Washington State, <u>Vehicle B</u>, the first urea-SCR equipped vehicle, was found to emit have NO_x emissions below the regulatory standard for portions of the route characterized by low or negligible changes in altitude (i.e. near zero road grade), and with the vehicle operated in cruise-control mode at highway speeds (i.e. 120km/h).

In general, CO and THC emissions were observed to be well below the regulatory level for all three test vehicles and driving conditions, with exception of two routes for the LNT_equipped vehicle where THC emissions were observed at slightly elevated levels. Interestingly, chassis dynamometer testing of *Vehicles A* and *B* indicated THC emissions to be primarily composed of methane (CH4/THC ratio > 0.95) which is surprising for diesel fueled vehicle and might be attributed to secondary reactions occurring over the surface of the oxidation catalyst or the LNT in case of *Vehicle A*.

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As expected, highway driving showed lowest <u>distance-specific</u> CO₂, whereas urban/suburban driving conditions lead to highest CO₂ emissions factors for all vehicles.

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During PEMS testing, Aaverage fuel economy for highway driving with *Vehicles A* and *B* was 45.3 mpg ± 8.6 mpg ($\pm \sigma 1$) and 43.7mpg ± 5.7 mpg ($\pm \sigma 1$), respectively, and 27.3 mpg (no repetition) for *Vehicle C* which is ~39% lower compared to *Vehicles A* and *B*. On the other hand, urban/suburban driving results in average fuel economies of 30.0mpg ± 2.9 mpg ($\pm \sigma 1$) and 26.6 mpg ± 1.4 mpg ($\pm \sigma 1$) for *Vehicles A* and *B*, respectively, and 18.5mpg ± 4.0 mpg ($\pm \sigma 1$) for *Vehicle C* which is 35% lower compared to *Vehicles A* and *B*. Overall, urban/suburban driving leads to a 32-39% reduction in fuel economy over highway driving.

Particulate number emissions, inferred from PPS measurements, were observed below the Euro 5b/b+ standard except during vehicle operation exhibiting DPF regeneration events where PN emissions significantly increased by two to three orders of magnitude, thereby exceeding the Euro 5b/b+ standard under all driving conditions for the LNT and first urea-SCR vehicles. It is noted that PN is not regulated in the United States. Also, for the latter vehicle DPF regeneration frequencies were found to be predominantly based on distance traveled, occurring after every $756 \text{km} \pm 29 \text{km} \, (\pm 1\sigma)$, corresponding to $\sim 7.07 \text{hours} \pm 0.06 \text{hours}$ for highway driving conditions.

It is noted that only three vehicles were tested as part of this measurement campaign with each vehicle being a different after-treatment technology or vehicle manufacturer; conclusions drawn from the data presented herein are confined to these three vehicles. The limited data set does not necessarily permit drawing more generalized conclusions for a specific vehicle category or after-treatment technology.

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LIST OF ABBREVIATIONS AND UNITS

CAFEE - Center for Alternative Fuels, Engines and Emissions

CARB - California Air Resources Board

CLD - Chemiluminiscence Detector

CO - Carbon Monoxide CO₂ - Carbon Dioxide

CVS - Constant Volume Sampler

DPF - Diesel Particle Filter

EERL - Engines and Emissions Research Laboratory

EFM - Exhaust Flow Meter

EPA - Environmental Protection Agency

EU - European Union

FTP - Federal Test Procedure

GPS - Global Positioning System

FID - Flame Ionization Detector

LNT - Lean NO_x Trap
MPG - Miles per Gallon

NDIR - Non-Dispersive Infrared Spectrometer

NEDC - New European Driving Cycle

NO - Nitrogen Monoxide
NO_x - Oxides of Nitrogen
NTE - Not-to-Exceed
OC - Oxidation Catalyst

PEMS - Portable Emissions Measurement System

PM - Particulate Matter
PN - Particle Number

RPA - Relative Positive Acceleration
SCR - Selective Catalytic Reduction

THC - Total Hydrocarbons

1 INTRODUCTION

Researchers at the Joint Research Centre (JRC) in Europe have identified off-cycle oxides of nitrogen (NO_x) emissions from light-duty diesel vehicles (LDV) to substantially exceed the Euro 3-5 emissions standards on average by a factor of 4 to 7 over specific test routes [[REF _Ref377225805 \r \h]]. Hence, the study concluded that the introduction of tighter emissions limits for the purpose of vehicle/engine certification has not necessarily translated into effective on-road NO_x reductions of the same magnitude [[REF _Ref377225805 \r \h]]. Furthermore, work conducted by other researchers has highlighted the thermodynamic conditions of the exhaust gas and after-treatment components to be a primary limiting factor for achieving high NO_x conversion efficiencies using the aqueous-urea based selective catalytic reduction (SCR) system, especially during low-load, low-speed operation such as frequently encountered during urban driving and stop-and-go traffic on congested highways.

Sparked by these findings, the International Council on Clean Transportation (ICCT) contracted West Virginia University (WVU) to perform on-road emissions measurements in order to study off-cycle emissions performance and fuel economy from three diesel light-duty vehicles (LDVs) of European make under typical United States (US) driving conditions using a portable emissions measurement system (PEMS). The PEMS testing aided in comparing the performance of different NO_x control technologies under off-cycle conditions against United States Environmental Protection Agency (US-EPA) Tier2-Bin5 and California Air Resources Board (CARB) LEV-II ULEV emissions standards.

The test plan covered a wide variety of topological, road and ambient conditions as well as traffic densities over three major urban areas along the West coast, namely, San Diego, Los Angeles as well as and San Francisco metropolitan areas in(California). Additionally, one vehicle, specifically one equipped with urea-SCR after-treatment technology, was operated over a total distance of ~4000km between Los Angeles, CA and Seattle, WA to investigate emissions reduction characteristics over extended highway driving conditions. Furthermore, two out of the three test vehicles were selected for chassis dynamometer testing over standardized test cycles at CARB's vehicle certification laboratory in El Monte, CA. This also allowed for comparison of the PEMS against laboratory grade instruments to verify measurement accuracy of the on-board system.

1.1 Objectives

The primary objective of this study was to gain insight into the real-world emissions of NOx and other regulated gaseous pollutants from diesel LDVs certified to US-EPA Tier 2-Bin 5 and CARB LEV-II ULEV (CA) standards. Emissions were measured during typical driving conditions pertinent to major US population centers using on-board instrumentation (PEMS). For a subset of vehicles and test routes, particulate matter mass emissions (PM) and particle number (PN) emission concentrations were also measured on-board.

The primary objective of this study was to gain insight into real-world regulated gaseous pollutant emissions from diesel LDVs that are certified to US-EPA Tier 2-Bin 5 and CARB LEV-II ULEV (CA) emissions standards. Emissions were measured during typical driving conditions pertinent to major US population centers, with specific interest in quantifying NO_x emissions. Additionally, particulate matter mass emissions (PM) and particle number (PN) emission concentrations were measured for a subset of vehicles and test routes.

To that aim, the Center for Alternative Fuels, Engines and Emissions (CAFEE) at WVU conducted light-duty PEMS testing on twohree 2012 model year (MY) vehicles and one MY 2013, of European make and equipped with two different NO_x after-treatment technologies, including, lean NO_x trap (LNT) and aqueous urea-based selective catalytic reduction (SCR) system. Gaseous exhaust emissions, including NO_x, carbon monoxide (CO), carbon dioxide (CO₂) and total hydrocarbons (THC) were measured on a continuous basis utilizing a Horiba OBS-2200 portable emissions measurement system, whereas particle number concentrations and particulate mass emissions were inferred from real-time measurements performed using a Pegasor particle sensor, model PPS-M from Pegasor.

Specifically, the data collected during the course of this study allowed for following analysis and comparisons:

- i. comparison of off-cycle NO_x emissions against US-EPA Tier 2-Bin 5 and CARB LEV-II ULEV emissions standards;
- ii. evaluation of fuel economy in comparison to standardized chassis dynamometer test cycles and EPA evaluated fuel economy ratings as published on window stickers for new cars sold in the United States [[REF Ref382820770 \r \h]];

Commented [VF4]: Paragraph edited. Original read: The primary objective of this study was aimed at gaining insight into real-world regulated gaseous pollutants with specific interest of quantifying NO₃ emissions, from diesel engine powered LDV's that are certified to US-EPA Tier 2-Bin 5 and CARB LEV-II ULEV (CA) emissions standards, during typical driving conditions pertinent to major US population centers. Additionally, particulate matter mass (PM) and particle number (PN) concentrations were

measured for a subset of vehicles and test routes.

- iii. calculation of in-use emissions factors based on the 'Averaging Windows Method' (AWM) [[REF _Ref382820874 \r \h]] using CO₂ emissions emitted over a certification cycle as the threshold value to define the averaging window size;
- iv. evaluation of NO_x after-treatment conversion efficiencies of two different technologies as a function of driving conditions, traffic density, ambient conditions and exhaust gas thermodynamic properties;
- v. quantification of particle number (PN) emissions concentrations with regard to the particle number limits (i.e. 6.0x10¹¹ #/km) set forth by the European Union (EU) in 2013 with the introduction of Euro 5b/b+ emission standards [[REF_Ref382821534 \r \h]];
- vi. evaluation of diesel particulate filter (DPF) filtration efficiency and frequency of regeneration events; and
- vii. quantification of maximum route emissions rates and their respective location along the routes.

2 BACKGROUND

The background information given hereafter will be limited to a discussion of United States Environmental Protection Agency's (US-EPA) Tier 2 and California Air Resources Board's (CARB) LEV-II emissions regulations that are applicable to the two light-duty vehicles (LDV) and one light-duty truck (LDT) whose on-road emissions have been evaluated as part of this study.

The ongoing effort by EPA and CARB to comply with National Ambient Air Quality Standards (NAAQS), particularly in several non-attainment regions, has led to ever_increasingly stringent emissions—regulations on LDV-s_emissions. Theseand are currently regulated under EPA's Tier 2 and California LEV-II emissions regulations. EPA's vehicle classification is based on gross vehicle weight rating (GVWR) and is shown in [REF _Ref377220712 \h]. It has to be noted that medium duty passenger vehicles (MDPV) are regulated under light-duty vehicle emissions regulations.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Vehicle classification based on gross vehicle weight rating (GVWR) [[REF_Ref377498305 \r \h]]

			Gross	s Vehic	le Weig	ht R	ating	; (GV	WR)	[lbs]				
	6,0	00 8,	500 10	,500	14,000	16,	000	19,	500	26,000	3.	000,8	60,	000 I
	LI	ΟV	MDPV ^{c)}										••••	
la l	LI	TC						HDV	/ HDE			,		
Federal	LLDT	HLDT		I	HDDE					MHDE	E		HHE Urba	DDE / n Bus
	LDT 1 & 2*)	LDT 3 & 4 ^{b)}	HDV2b	HDV	3 HE)V4	HI)V5	HDV	76	HDV7	Н	DV8a	HDV8b

a) Light-duty truck (LDT) 1 if loaded vehicle weight (LVW) = 3,750; LDT 2 if LVW > 3,750

The EPA's Tier 2 emission standards that were phased in over a period of four years, beginning in 2004, for LDV/LLDTs, with an extension of two years for HLDTs, were in full effect starting from model year (MY) 2009 for all new passenger cars and light-duty trucks, including pickup trucks, vans, minivans and sport-utility vehicles. The Tier 2 standards were designed to significantly reduce ozone_forming pollution and PM emissions from passenger vehicles regardless of the fuel used and the type of vehicle, namely car, light-duty truck or larger

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b) LDT 3 if adjusted loaded vehicle weight (ALVW) = 5,750; LDT 4 if ALVW > 5,750

c) MDPV vehicles will generally be grouped with and treated as HLDTs in the Tier 2 program

passenger vehicle. The Tier 2 standards were implemented along with the gasoline fuel sulfur standards in order to enable emissions reduction technologies necessary to meet the stringent vehicle emissions standards. The gasoline fuel sulfur standard mandates the refiners and importers to meet a corporate average gasoline sulfur standard of 30 ppm starting from 2006 [[REF_Ref377387706 \rac{1}{2} \h]].

The EPA Tier 2 emissions standard requires each LDV/LDT vehicle manufacturer to meet a corporate average NO_x standard of 0.07g/mile (0.04 g/km) for the fleet of vehicles being sold for a given model year. Furthermore, the Tier 2 emissions standard consists of eight sub-bins, each one with a set of standards to which the manufacturer can certify their vehicles provided the corporate sales weighted average NO_x level over the full useful life of the vehicle (10 years/120,000 miles/193,121 km), for a given MY of Tier 2 vehicles, is less than 0.07g/mile (0.04 g/km). The corporate average emission standards are designed to meet the air quality goals allowing manufacturers the flexibility to certify some models above or below the standard, thereby enabling the use of available emissions reduction technologies in a cost-effective manner as opposed to meeting a single set of standards for all vehicles [[REF _Ref377387706 \text{ r \h}]]. Final phased-in full and intermediate useful life Tier 2 standards are listed in [REF Ref368332978 \h].

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Light-duty vehicle, light-duty truck, and medium-duty passenger vehicle - EPA Tier 2 exhaust emissions standards in [g/miles] [[REF _Ref377387706 \r \h]]

Bin#	Intermed	iate life	(5 years	/ 50,0	100 mi)	Full us	eful life	(10 years	/120,00	0 mi)
Dill#	NMOG*	CO	NO_x	PM	НСНО	NMOG*	CO	NO_x^{\dagger}	PM	НСНО
				Ter	nporary Bi	ns				
11 MDPV°						0.28	7.3	0.90	0.12	0.032
$10^{\mathrm{a,b,d,f}}$	0.125 (0.160)	3.4 (4.4)	0.40	-	0.015 (0.018)	0.156 (0.230)	4.2 (6.4)	0.60	0.08	0.018 (0.027)
gabat	0.075 (0.140)	3.4	0.20	-	0.015	0.090 (0.180)	4.2	0.30	0.06	0.018
				Per	manent Bi	ns		***************************************	***************************************	***************************************
8,,	0.100 (0.125)	3.4	0.14	-	0.015	0.125 (0.156)	4.2	0.20	0.02	0.018
7	0.075	3.4	0.11	-	0.015	0.09	4.2	0.15	0.02	0.018
6	0.075	3.4	0.08	-	0.015	0.09	4.2	0.10	0.01	0.018
5	0.075	3.4	0.05	-	0.015	0.09	4.2	0.07	0.01	0.018
4	-	-	-	-	-	0.07	2.1	0.04	0.01	0.011

3	_	-	-	-	-	0.055	2.1	0.03	0.01	0.011
2	-	-	-		-	0.01	2.1	∪.∪∠	0.01	
1	-	-	-	-	-	0	0	0	0	0

- * for diesel fueled vehicle, NMOG (non-methane organic gases) means NMHC (non-methane hydrocarbons)
- † average manufacturer fleet NO_x standard is 0.07 g/mi for Tier 2 vehicles
- a Bin deleted at end of 2006 model year (2008 for HLDTs)
- b The higher temporary NMOG, CO and HCHO values apply only to HLDTs and MDPVs and expire after 2008
- c An additional temporary bin restricted to MDPVs, expires after model year 2008
- d Optional temporary NMOG standard of 0.195 g/mi (50,000) and 0.280 g/mi (full useful life) applies for qualifying LDT4s and MDPVs only
- e Optional temporary NMOG standard of 0.100 g/mi (50,000) and 0.130 g/mi (full useful life) applies for qualifying LDT2s only
- f=50,000 mile standard optional for diesels certified to bins 9 or 10

All Tier 2 exhaust emissions standards must be met over the FTP-75 chassis dynamometer test cycle. In addition to the above listed emissions standards, Tier 2 vehicles must also satisfy the supplemental FTP (SFTP) standards. The SFTP standards are intended to control emissions from vehicles when operated at high speed and acceleration rates (aggressive driving,) as simulated through the US06 test cycle), as well as when operated under high ambient temperature conditions with vehicle air-conditioning system turned on, (that is being simulated through the SC03 test cycle). The SFTP emissions results are determined using the relationship as-outlined in Equation (1) where individual emissions measured over FTP, US06 and SC03 test cycles are added together with different weighting factors.

$$E_{pollutant} = 0.35 * (FTP) + 0.28 * (US06) + 0.37 * (SC03)$$
 Eq. 1

Manufacturers must comply with 4000 mile and full useful life SFTP standards. The 4000 mile SFTP standards are shown in [REF _Ref377498346 \h].

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: US-EPA 4000 mile SFTP standards in [g/mi] for Tier 2 vehicles [[REF _Ref377387706 \r \h]]

Vehicle Class 17	US NMHC + NO.	06 CO	SC NMHC + NO.	63 CO
LDV/LDT1	0.14	8.0	0.20	2.7
LDT2	0.25	10.5	0.27	3.5
LDT3	0.40	10.5	0.31	3.5
LDT4	0.60	11.8	0.44	4.0

¹⁾ Supplemental exhaust emission standards are applicable to gasoline and diesel-fueled LDV/Ts but are not applicable to MDPVs, alternative fueled LDV/Ts, or flexible fueled LDV/Ts when operated on a fuel other than gasoline or diesel

The full useful life SFTP standards are determined following Equation 2, which is based on Tier 1 SFTP standards, lowered by 35% of the difference between the Tier 2 and Tier 1 exhaust emissions standards. Tier 1 full useful life SFTP standards for different vehicle classes along with CO standards for individual chassis dynamometer test cycles as well as Tier 1 full useful life FTP standards are shown in [REF _Ref377224826 \h] and [REF _Ref377224829 \h], respectively.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: US-EPA Tier 1 full useful life SFTP standards in [g/mi] [[REF _Ref377387706 \r \h]]

	NAMES NO. 10		COper	
Vehicle Class	NMHC + NO. 40	1.506	8003	Weighted
LDV/LDT1	0.91 (0.65)	11.1 (9.0)	3.7 (3.0)	4.2 (3.4)
LDT2	1.37 (1.02)	14.6 (11.6)	4.9 (3.9)	5.5 (4.4)
LDT3	1.44	16.9	5.6	6.4
LDT4	20.9	19.3	6.4	7.3

 $[\]overline{a}$ Weighting for NMHC + NO_x and optional weighting for CO is 0.35*(FTP) + 0.28*(US06) + 0.37*(SC03)

 $\label{lem:table style the lambda} Table [STYLEREF 1 \ style SEQ Table \ * ARABIC \ s 1 \]: US-EPA Tier 1 full useful life FTP standards in [g/mi] [[REF _Ref377387706 \ r \ h]]$

LDV/LDT1	0.31 (0.25)	0.60 (0.40)	4.2 (3.4)	0.10
LDT2	0.40 (0.32)	0.97 (0.70)	5.5 (4.4)	0.10
LDT3	0.46	0.98	6.4	0.10
LDT4	0.56	1.53	7.3	0.12

a) Intermediate life standards are shown in parentheses for diesel LDV/LLDTs opting to calculate intermediate life SFTP standards in lieu of 4,000 mile SFTP standards as permitted

In-use testing of light duty vehicles under the Tier 2 regulation involves testing of vehicles on a chassis dynamometer that have accumulated at least 50,000 miles during in-use operation, to verify compliance with FTP and SFTP emissions standards at intermediate useful life. There has been no regulatory requirement in the United States to verify compliance of Tier 2 vehicles for emissions standards over off-cycle tests such as on road emissions testing with the use of

b) CO standards are stand alone for US06 and SC03 with option for a weighted standard

c) Intermediate life standards are shown in parentheses for diesel LDV/LLDTs opting to calculate intermediate life SFTP standards in lieu of 4,000 mile SFTP standards as permitted.

PEMS equipment, similar to as it's what is being mandated for heavy-duty vehicles via the engine in-use compliance requirements (i.e. NTE emissions). Meanwhile, the European Commission (EC) has established a working group to propose modifications to its current vehicle certification procedures in order to better limit and control off-cycle emissions [[REF _Ref377230031 \r \h]]. Over the course of a two_year evaluation process, different approaches were being assessed with two of them believed to be promising for application in a future light-duty emissions regulation, namely; i) emissions testing with random driving cycle generation in the laboratory, and ii) on-road emissions testing with PEMS equipment [[REF _Ref377230031 \r \h]].

3 METHODOLOGY

The following section of the report will discuss the test vehicles selected for this study, describe the specific test routes and their characteristics, as well as present the emissions sampling setup and instrumentation utilized during this work.

3.1 Test Vehicle Selection

The vehicles tested in this study comprise two MY 2012 and one MY 2013, diesel-fueled passenger cars of European make, and will hereinafter be referred to as 'Vehicle A', 'Vehicle B', and 'Vehicle C' in order to anonymize model₂ and make_-specific information for the purpose of this report. Vehicles A and Vehicle B were equipped with the same 2.0L turbocharged, four cylinder base engine_{.5} Hawwever, they were equipped with two different NO_x reduction technologies. Vehicle A featured a lean NO_x trap (LNT) for NO_x abatement, whereas Vehicle B was fitted with an aqueous urea-based selective catalytic reduction system. Both vehicles had a DPF installed for controlling particulate matter emissions. Vehicle C was fitted with a 3.0L turbocharged in-line six_-cylinder engine in conjunction with an aqueous urea-SCR system and DPF for NO_x and PM control, respectively. The drive-train of both Vehicles A and B comprised 6-speed automatic transmissions with front wheel drive, whereas Vehicle C featured all-wheel drive with a 6-speed automatic transmission.

All three test vehicles were compliant with EPA Tier2-Bin5, as well as California LEV-II ULEV (for *Vehicles A* and *B*) and LEV-II LEV (for *Vehicle C*) emissions standards as per EPA certification documents. *Vehicles A* and *B* are categorized as 'light-duty vehicles' (LDV) whereas *Vehicle C* as 'light-duty truck 4' (LDT4). Even though all three test vehicles were certified under the same emissions limits, they fall into two different categories according to CO₂/CAFE standards. The 2012 EPA/NHTSA fleet-wide average for CO₂ emissions for LDV's is 163 g/km CO₂ compared to 215 g/km CO₂ for LDT4 type vehicles. Actual CO₂ emissions and fuel economy for city, highway, and combined driving conditions, as well as tailpipe CO₂ values as advertised by the EPA for new vehicles sold in the US are given in [REF _Ref367992920 \h] for all three test vehicles.

Vehicle A and Vehicle C were rented from two separate rental agencies and had initial odometer readings of 4,710 miles and 15,031 miles, respectively. Vehicle B had 15,226 miles at start of testing and was acquired from a private owner. Furthermore, all three test vehicles were

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thoroughly checked for possible engine or after-treatment malfunction codes using an ECU scanning tool prior to selecting a vehicle for this on-road measurement campaign, with none of them showing any fault code or other anomalies. The after-treatment system was assumed to be 'de-greened' as all three vehicles have accumulated more than 3,000 to 4,000 miles, and no reduction in catalytic activity due to aging was expected as the total mileage was relatively low (< 15,000 miles) for all test vehicles. More specific details for the three test vehicles are presented in [REF _Ref367992920 \h].

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Test vehicles and engine specifications

Vehicle		A	В	C
Mileage at test start [miles]		4,710	15,226	15,031
Fuel		ULSD	ULSD	ULSD
largane configura	line.	In-line, 4 cyl., 16V In-line, 4 cyl., 16V In-line, 6		In-line, 6-eyl.
Engine displacem	ent (leem)	19682 <u>0</u>		
Engine aspiration		Turbocharged/ Intercooled	Turbocharged/ Intercooled	Turbocharged/ Intercooled
Conspectors		16.5.1	16.5-1	-
Max. engine power (kW)		104 @ 4200 rpm	104 @ 4200 rpm	198
Max engine torqu	ic [Nm]	320 @ 1750 rpm	320 @ 1750 rpm	-
limission after-tre technology	ratment	OC, DPF, LNT	OC, DPF, urea-SCR	OC, DPF, urea-SCR
Drive train		2-wheel drive, front	2-wheel drive, front	4-wheel drive
Applicable	U.S. EPA	T2B5 (LDV)	T2B5 (LDV)	T2B5 (LDV)
emissions limit	CARB	LEV-II ULEV	LEV-II ULEV	LEV-II LEV
EPA Fuel City		29	30	19
Economy Highway		39	40	26
Values [mpg] Combined		33	34	22
EPA CO: Values [g/km] ²		193	186	288

 $^{^{(1)}}$ EPA advertised fuel economy and CO₂ emissions values for new vehicles in the US (www.fueleconomy.gov)

[REF _Ref367993994 \h] lists the individual curb weights, gross vehicle weight ratings (GVWR), and actual test weights while performing the on-road PEMS testing. Actual test weights were calculated as the sum of manufacturer specified vehicle curb weights and physically acquired weights of the payload on a scale. The payload comprised the entire instrumentation and associated equipment, including pressurized gas bottles for the emissions

analyzers, as well as the weight of a driver and passenger of 77kg each. The total payload for *Vehicle C* was approximately 200kg heavier than for *Vehicles A* and *B* due to additional instrumentation as will be explained in more detail in Section [REF _Ref367994598 \r \h]. [REF _Ref367993994 \h] further allows for a comparison between the actual test weight of the three vehicles during PEMS testing and the respective equivalent test weight (ETW) as applied during emissions certification testing on the chassis dynamometer according to 40 CFR paragraph 86.129-00(f)(1).

The diesel fuel used during this study was commercially available ultra low diesel fuel (ULSD) in California. Fuel for *Vehicles A* and *B* originated from the same batch and was purchased from a truck stop in Fontana, CA. A fuel analysis showed a sulfur content of 5ppm (via Microcoulometry, ASTM D3120, see Appendix [REF _Ref382841455 \r \h] for more details). This diesel fuel used for *Vehicles A* and *B* was also used for chassis testing. The fuel used during on-road testing of *Vehicle C* was purchased from the Quick Gas Valero fuel station in Ontario, CA. ULSD used for the California to Washington State trip with *Vehicle B* was purchased exclusively from Shell fuel stations along highway I-5. Specifically, the test vehicle was refueled six times during the entire trip, namely in Kettleman, CA, Redding, CA, Vancouver, WA, Olympia, WA, Medford, OR and finally Gustine, CA.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Test weights for vehicles

Vehicle	Curb Weight ikel	GVWR lkel	Payload	Actual Test Weight Ikgl	Equiv. Test Weight Ikgl
Vehicle A	1550	2010	305	1855	1701
Vehicle B	1570	2110	314	1884	1701
Vehicle C	2370	3001	533	2903	2495

3.2 Vehicle Test Routes

On-road PEMS testing was grouped into two main route categories for this study, with one comprising a set of strictly defined test routes that were used for all test vehicles and the other containing predominantly highway driving solely defined by the departure and final destination, specifically, Los Angeles, CA as the starting point and Seattle, WA as the end point, that was only used in conjunction with *Vehicle B*. Section [REF _Ref368241950 \r \h] will describe the

pre-defined test routes of category one in more detail, whereas Section [REF _Ref368241984 \r \h] will highlight the characteristics of the multi-state driving route between California and Washington State.

3.2.1 Pre-defined Test Routes

Five test routes were defined within the three primary population centers in California, namely, Los Angeles, San Diego, and San Francisco, aimed at reflecting a rich diversity of topological characteristics, driving patterns, as well as ambient conditions, that are expected to be representative of typical vehicle operation within the given areas. The routes can be split into four categories, including i) highway operation, characterized by high speed driving during regular hours and frequent stop/go patterns during rush-hours, ii) urban driving, characterized by low vehicle speeds and frequent stop and go, iii) rural driving, medium vehicle speed operation with occasional stops in the suburbs of the selected metropolitan areas, and finally iv) uphill/downhill driving, characterized by steeper than usual road grades and medium to higher speed vehicle operation. [REF _Ref368243033 \h] summarizes the characteristics of the five defined test routes whose driving patterns are described as follows:

- 1) Route 1: highway driving in Los Angeles
- 2) Route 2: urban driving in downtown Los Angeles
- 3) Route 3: rural and uphill/downhill driving in Los Angeles's foothills
- 4) Route 4: urban driving in downtown San Diego
- 5) Route 5: urban driving in downtown San Francisco

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Comparison of test route and driving characteristics

Route	Route 1 ¹¹	Route 23	Route 3	Route 4 ²	Route 52
Route distance [km]	70.18	25.67	59.09	21.22	26.72
Avg. vehicle speed [km/h]	77.85	24.09	52.27	26.54	24.69
Max. vehicle speed [km/h]	112.65	92.57	112.65	109.87	112.65
Avg. RPA 3) [m/s ²]	0.24	0.27	0.26	0.30	0.33
Characteristic Power [m²/s³]	2.57	2.24	3.93	2.60	2.97
Min. elevation [m a.s.l. 4)]	46.0	42.1	300.1	1.1	1.0
Max. elevation [m a.s.l]	360.1	123.5	1319.7	101.4	190.9
Share [%] (time based)					
- idling (≤2 km/h)	7.0	23.8	13.5	26.8	27.9

- low speed (>2≤50 km/h)	20.5 64.2	23.9 57.0 58.9
- medium speed (≥50≤90 km/h)	14.9 11.2	55.6 12.9 7.5
- high speed (>90 km/h)	57.7 0.8	7.0 3.3 5.6

¹⁾ week-day, non-rush-hour driving conditions

²⁾ typical week-day driving conditions ⁴⁾ a.s.l. - above sea level

Route and driving characteristics provided in [REF _Ref382929788 \h] are representative of typical week-day driving conditions for the urban routes (i.e. Routes 2, 4, and 5), and non-rush-hour, week-day driving conditions for highway driving (i.e. Route 1). Relative positive acceleration (RPA) is a frequently used metric for analysis of route characteristics [[REF _Ref377225805 \r \h], [REF _Ref383178321 \r \h]] and will be described in more detail later in this section (see Eq. 4 and 5). 'Characteristic Power' is a metric derived by Delgado et al. [[REF _Ref383177030 \r \h], [REF _Ref383177088 \r \h]] taking kinematic power and grade changes over the driving route into account, and is representative of the positive mechanical energy supplied per unit mass and unit time. Delgado et al. [[REF _Ref383177030 \r \h], [REF _Ref383177088 \r \h]] described 'Characteristic Power' as outlined in Equation 3 having units [m²/s³ or W/kg] with 'T' being the duration of the route, 'g' the gravitational acceleration (i.e. 9.81m/s²), 'v_i' and 'h_i' being the vehicle speed and altitude at each time step, respectively.

$$P_{ch} = \frac{1}{T} \cdot \sum_{i=2}^{N} \left[\frac{1}{2} \cdot (v_i^2 - v_{i-1}^2) + g \cdot (h_i - h_{i-1}) \right]^+$$
 Eq. 3

For comparison reason with the five defined test routes, [REF _Ref382929788 \h] provides a summary containing the same metrics as shown in [REF _Ref368243033 \h] for a set of chassis dynamometer vehicle certification test cycles that are currently used by the US EPA (FTP-75, US06) and the European Union (NEDC). It can be noticed that the US06 cycle shows similar maximum and average speed patterns as the highway (i.e. Route 1) and uphill/downhill (i.e. Route 3) routes, whereas the FTP-75 closer represents maximum and average speed characteristics of the urban test routes (i.e. Route 2, 4, and 5).

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Comparison of characteristics of light-duty vehicle certification cycles

Cycle	FTP-75	US06	NEDC
Cycle duration [sec]	1877	596	1180
Cycle distance [km]	17.77	12.89	10.93
Avg. vehicle speed [km/h]	34.08	77.84	33.35

³⁾ RPA - relative positive acceleration 4) a.s.l. - a

Max. vehicle speed [km/h]	91.25	129.23	120.00
Avg. RPA 33 [m/s2]	0.23	0.52	0.15
Characteristic Power [m²/s³]	1.65	4.55	1.04
Share [%] (time based)			
- idling (≤2 km/h)	19.6	7.2	24.8
- low speed (>2≤50 km/h)	59.3	18.8	53.9
- medium speed (>50≤90 km/h)	19.5	18.0	14.2
- high speed (>90 km/h)	1.6	56.0	7.0

The topographic map of Route 1 is depicted in [REF _Ref368244263 \h]. Route 1 is \sim 70 kilometers in distance and comprises approximately 95% highway driving between the convention center in Ontario and the main campus of the University of Southern California (USC) South of downtown LA, following interstate I-10 East and highway 110 South till exit 20B (W. Exposition Blvd.). Average vehicle speed during day-time and outside morning or evening rush-hours was \sim 77.8 km/h.

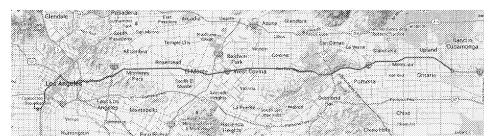


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Topographic map of Route 1, highway driving between Ontario and downtown LA

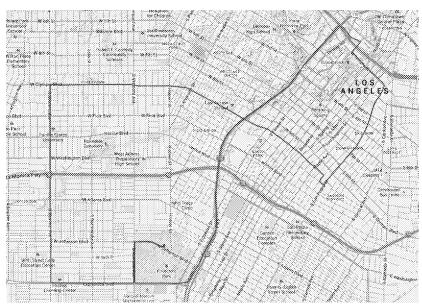


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Topographic map of Route 2, urban driving downtown Los Angeles

[REF _Ref368245088 \h] shows the topographic map of Route 2, representative of urban driving downtown Los Angeles. This route essentially represents the "Los Angeles Route Four" (i.e. LA4) which was ultimately used in developing the original FTP vehicle certification cycle [[REF _Ref377230145 \r \h]], with some minor modifications at locations where the traffic pattern or roads have changed since the FTP's development. The route is ~25.6 km long, which and started and terminated at USC's main campus on Jefferson Blvd. From USC the route followed westwards on W. Exposition Blvd., then North on S. Western Ave. till W. Olympic Blvd. From there it turned eastwards and followed W. Olympic Blvd. till S. San Pedro Street, then North on S. San Pedro St., and again West on W. Temple Street before merging onto highway 110 South leading back to the USC campus (Exit 20B, W. Exposition Blvd.). Even though the route contains ~5.3 km or 20% of highway driving on Hwy 110-S, the average vehicle speed is only marginally affected due to highly dense traffic on this portion of Hwy 110-S with many roads intersecting or merging.

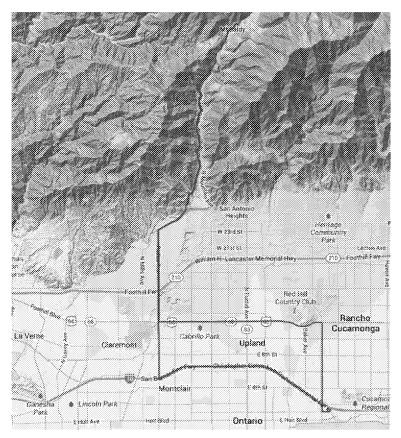


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Topographic map of Route 3, rural-up/downhill driving between Ontario and Mt. Baldy

The topographic map of Route 3, representative of rural and uphill/downhill driving is shown in [REF_Ref368247306 \h]. The route is ~59 kilometers in distance and experiences an elevation change of approximately 1000 meters between the lowest and highest points of the route. The route starts and terminates at the convention center in Ontario, CA and follows Foothill Blvd. eastwards till the intersection with Mt. Baldy Rd. From there the route climbs up a windy road to Mt. Baldy and back. On the return the route follows for ~9km on interstate I-10 East, which represents 15% of the total route's distance. The average vehicle speed for Route 3 is 52.3 km/h.

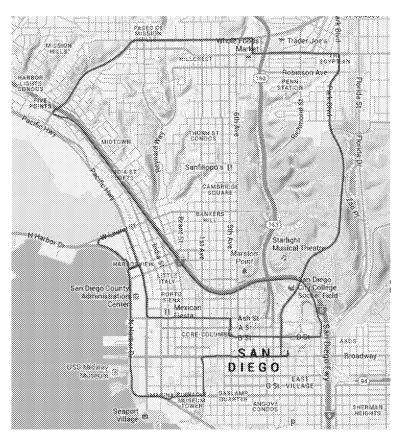


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Topographic map of Route 4, urban driving downtown San Diego

[REF _Ref368248591 \h] depicts the topographic map of the urban driving route, Route 4, in downtown San Diego. Route 4 is slightly shorter when compared to Route 2, approximately 21 km in length; however, <u>it</u> experiences more elevation changes than the downtown LA route. The route starts and terminates at the harbor at sea level (N. Harbor Drive). It first follows along the harbor then leads through downtown before climbing up on Park Blvd. to the Bridgeview and Hillcrest neighborhood. From there the route follows W. Washington St. to San Diego airport where it merges onto interstate I-5 South till Exit B St., and then going back through downtown to the harbor again. Route 4 comprises roughly 20% or 4.2 km of highway driving on interstate I-5 South. However, similar to Route 2, this portion of I-5 is heavily congested throughout the

day, thus not significantly affecting the average vehicle speed of Route 4 which was measured as \sim 26.5 km/h.



Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Topographic map of Route 5, urban driving downtown San Francisco

Finally, the topographic map of Route 5 is shown in [REF _Ref368249719 \h]. Route 5 is located in and around downtown San Francisco and is specifically characterized by faster speed changes of the traffic flow and steep inclines and declines of the road when compared to the two other urban routes in LA and San Diego. In terms of average vehicle speeds Route 5 is similar to Routes 2 and $4\frac{1}{15}$ however, it exhibited highest average relative positive acceleration of all three

urban routes. The route is ~26.7 km in distance and starts as well as terminates in the Marina District on Marina Blvd. From there the route goes southwards to Eureka Valley area and climbs over Diamond Heights neighborhood before merging onto highway 280 North and descending back to downtown and the Financial District. Approximately 28% of the entire route or 7.4 km are driven on highway 280.

REF Ref368328818 \h] presents a comparison of vehicle speed distributions for all five test routes and three regulatory vehicle certification cycles over four distinct vehicle speed bins defined as i) idle, speeds at or below 2 km/h, ii) low speed, speeds higher than 2 km/h and lower or at 50 km/h, iii) medium speed, speeds higher than 50 km/h and lower or at 90 km/h, and finally iv) high speed, speeds higher than 90 km/h. Vehicle speed bins ii, iii and iv can alternatively be described as urban, rural, and highway operation, respectively, following the notation used by Weiss et al. [[REF Ref377225805 \r \h]]. It can be noticed from [REF Ref368328818 \h] that highway driving (i.e. Route 1, week-day non-rush-hour) is similar to the US06 chassis dynamometer schedule as both show the same vehicle speed distribution pattern. A similar conclusion can be drawn between the three urban routes and two certification cycles FTP-75 and NEDC. Route 3, the rural and up/downhill route on the other hand is not well represented by any of the three certification cycles as they all lack significant medium speed operation. At vehicle speeds below 50 km/h Route 3 shows similar speed distributions as the US06 cycle. One observation from [REF Ref368328818 \h] is that the introduction of the US06 test cycle to the US light-duty vehicle certification process has led to a better representation of high-speed vehicle operation as compared to the FTP-75.

It has to be noted that data presented in [REF _Ref368328818 \h] is are representative of week-day, non-rush-hour driving conditions for highway driving (i.e. Route 1) and typical week-day traffic conditions for the urban routes (i.e. Route 2, 4, and 5). Changing traffic densities, for example during morning or evening rush-hours as opposed to regular day-time traffic conditions can lead to significant alterations in driving characteristics for a given test route.

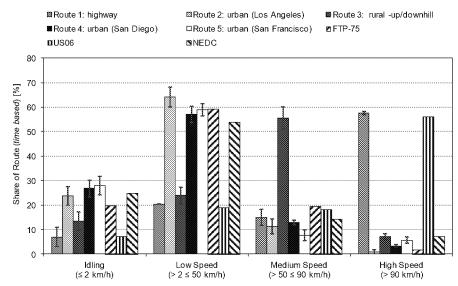


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Comparison of vehicle speed distribution ($time\ based$) over the test routes and certification cycles, red bars represent $\pm 1\sigma$

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Comparison of test route and driving characteristics with low and high traffic densities

Route	Ronte I low	Route I high	Diff	Route 2 low	Route 2 high	Diff [%]
	traffic ⁽⁾	traffic 21	[%]	traffic 3	traffic ⁶	1/91
Route distance [km]	70.18	71.11	-1.3	25.67	25.67	0.0
Avg. vehicle speed [km/h]	77.85	42.41	45.5	37.70	24.09	36.1
Max. vehicle speed [km/h]	112.65	112.65	0.0	110.27	92.57	16.1
Avg. RPA 33 [m/s2]	0.24	0.21	11.3	0.31	0.27	11.8
Characteristic Power [m ² /s ³]	2.57	2.50	2.7	3.27	2.24	31.4
Share [%] (time based)						
- idling (≤2 km/h)	7.0	7.8	-11.9	15.8	23.8	-50.3
- low speed (>2≤50 km/h)	20.5	59.0	-188.1	48.7	64.2	-31.9
- medium speed (>50≤90 km/h)	14.9	19.7	-32.3	29.9	11.2	62.6
- high speed (>90 km/h)	57.7	13.5	76.6	5.6	0.8	85.8

¹⁾ week-day, non-rush-hour driving conditions

[REF _Ref368260676 \h] compares the route characteristics of Route 1 and 2 between low and high traffic densities. In case of Route 2, urban driving downtown LA, the traffic densities during weekdays were usually high with an average vehicle speed of ~24 km/h and frequent

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FP: yes, interesting...

²⁾ week-day, evening-rush-hour driving conditions

³⁾ typical week-day driving conditions 4) weekend (holiday) driving conditions

stop/go patterns. This can be underlined by the fact that both Vehicles A and B were tested on two random and regular working weekdays in the afternoon between 13:00 and 16:00 and both experienced the same route characteristics. On the other hand, the low traffic characteristics for Route 2, shown in [REF _Ref368260676 \h], were measured during testing of Vehicle C which happened to fall on Memorial Day Monday (May 27, 2013) in the afternoon between 14:00 and 18:00. Due to the holiday, downtown traffic was greatly reduced and average vehicle speeds rose by 36% from ~24 to 37.7 km/h. Overall, the share of medium speeds increased by 62% while the idling portion dropped significantly by 50%. Another example of the strong influence of traffic densities onto route characteristics is given for Route 1, the highway operation. [REF Ref368260676 \h] shows a comparison for Vehicle A between low traffic conditions while driving from Ontario to downtown LA during regular daytime traffic (around 11:30), and high traffic densities going from downtown LA towards Ontario (same route, opposite direction) during evening rush-hours (around 16:30) when a large number of people were leaving their offices/workplaces and driving back to their suburban homes. As a result, the average speed dropped by 46% from 77.9 to 42.4 km/h, while the time to cover the same distance nearly doubled from 54min to 1h 41min. [REF Ref368328925 \h] shows how the speed distributions changed and the low speed bin's share increased from 20% to nearly 60% while at the same time the share of speeds above 90 km/h dropped by 77% from 58% to merely 14% of the entire route.

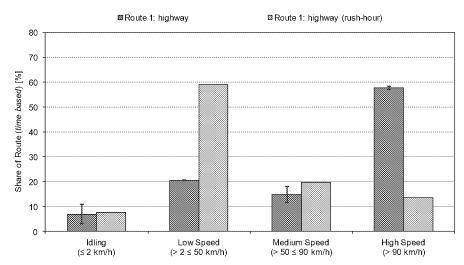


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of vehicle speed distribution (time based) over Route 1 during low traffic and rush-hour, red bars represent $\pm 1\sigma$

[REF _Ref368263023 \h] summarizes the cumulative frequencies of the vehicle speeds for all three test vehicles and Routes 1 through 4 in comparison to three chassis dynamometer certification cycles. It has to be noted that for comparison purposes, vehicle speed data presented herein for chassis dynamometer cycles is based on vehicle speed set-point rather than actually measured data. As already concluded from [REF _Ref368328818 \h] and [REF _Ref368243033 \h] the top left graph in [REF _Ref368263023 \h] confirms again the representativeness of the US06 cycle of highway driving during non-rush-hour vehicle operation. In stark contrast are cumulative frequency pattern for vehicle operation during rush-hours (i.e. high traffic densities) as shown by one *Vehicle A* and one *Vehicle B* test run. Highway speed patterns during rush-hours seem to be close to FTP-75 or NEDC vehicle operation characteristics.

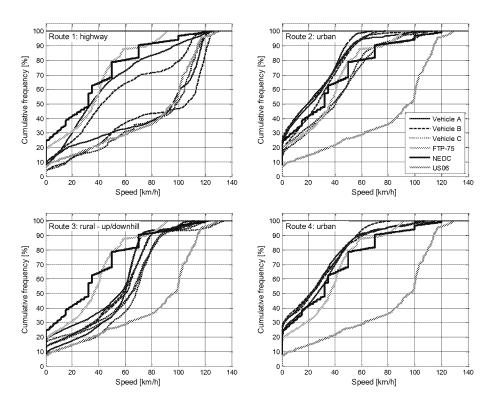


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Vehicle speed distributions of test routes 1 through 4 in comparison to certification test cycles (FTP-75, US06, and NEDC, based on speed set-point data)

Urban driving in downtown LA and San Diego are shown to exhibit cumulative frequencies of vehicle speeds close to the frequencies of FTP-75 and NEDC certification cycles, although mostly slightly on the slower side compared to the certification cycles (top right and bottom right graphs). Route 2 driving for Vehicle C shows a noticeable difference when compared to both *Vehicles A* and *B* (top right graph) as already has been previously discussed. The bottom left graph in [REF _Ref368263023 \h * MERGEFORMAT] shows rural and uphill/downhill driving, emphasizing again its significant contribution to the medium speed range, which is poorly represented by any of the three light-duty certification cycles depicted herein.

The altitude profiles for all five test routes are compared in [REF _Ref368264703 \h] in terms of elevation above sea level (i.e. meter a.s.l.). The majority of urban routes varied between

sea level and 100 meters, with the San Francisco route (Route 5) being the only one exhibiting elevation changes more frequently with a range of ~200 meters from lowest to highest point.

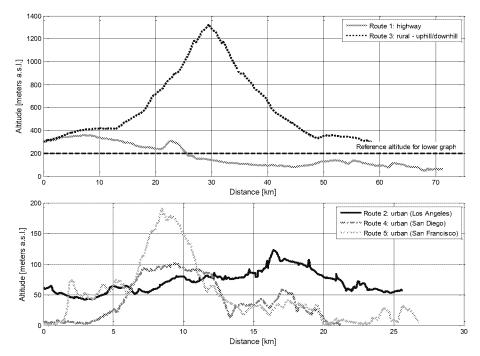


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Altitude profiles of test routes given in meters above sea level (a.s.l.)

The uphill/downhill driving route experienced an elevation change of approximately 1000 meters, starting at about 300 meters a.s.l. with a turning point at 1300 meters a.s.l. The road grade was on the order of 5.5 to 6% over a distance of ~16 km (between distance marker 14 and 30km). The same road grade applied for the downhill portion of the route, as the same road was chosen to drive back from Mt. Baldy. The primary measure of altitude during the course of this study was the GPS signal. However, due to sporadically deteriorating GPS reception, caused by a multitude of factors, including but not limited to heavy cloud overcast, road tunnels and underpasses (e.g. bridges), as well as high buildings in downtown areas, an alternative backup method to calculate altitude was employed by means of measuring changes in barometric pressures as a function of altitude using a high resolution pressure transducer. The latter method

has proven, during previous studies at WVU [[REF _Ref383177030 \r \h], [REF _Ref368339684 \r \h]], to be more accurate for the purpose of calculating road grade changes, however, it is plagued by the requirement to consider local weather conditions as changes in environmental conditions will lead to changing barometric pressures, hence, offset the altitude calculation.

Equation 3 shows a simplified version of the formula used to calculate altitude 'H' as a function of reference temperature ' T_{θ} ' and pressure ' p_{θ} ' at ground level as well as the actually measured barometric pressure ' p_{baro} '. With 'L' being the temperature lapse rate, 0.0065K/m, and g, M, R being the gravitational acceleration, molar mass of dry air and universal gas constant, respectively [[REF _Ref368339684 \r \h]]. Equation 3 is derived from the International Standard Atmosphere (ISA) model which has been formulated by the International Civil Aviation Organization (ICAO) and is based on assuming ideal gas, gravity independence of altitude, hydrostatic equilibrium, and a constant lapse rate [[REF _Ref383177030 \r \h]].

$$H = f(T_0, p_0, p_{baro}) = \left(\frac{T_0}{L}\right) \cdot \left[1 - \left(\frac{p_{baro}}{p_0}\right)^{\left[\frac{R \cdot L}{g \cdot M_{air}}\right]}\right]$$
 Eq. 3

[REF _Ref368267535 \h * MERGEFORMAT] shows a sample of the individual vehicle speed profiles for all five test routes as a function of driving time during week-day, non-rush-hour conditions for highway driving (i.e. Route 1) and typical week-day traffic conditions for the urban routes (i.e. Route 2, 4, and 5).

[REF _Ref383261546 \h] depicts ambient conditions, including temperature, barometric pressure, and relative humidity experienced during the five test routes for *Vehicles A* through *C*. The variation intervals (red bars) represent minimum and maximum values encountered over the test route. An increase in the observed range of barometric pressure (i.e. minimum to maximum value) is indicative of larger elevation changes experienced over a given test route (see [REF Ref368264703 \h] for altitude profiles).

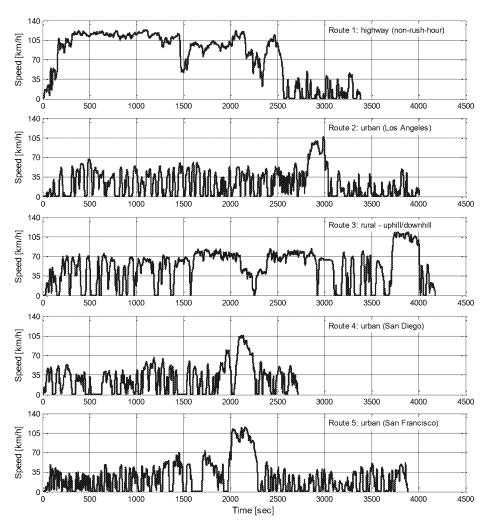


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Characteristic vehicle speed vs. time for five test routes during typical week_day non-rush-hour traffic densities for highway and urban driving

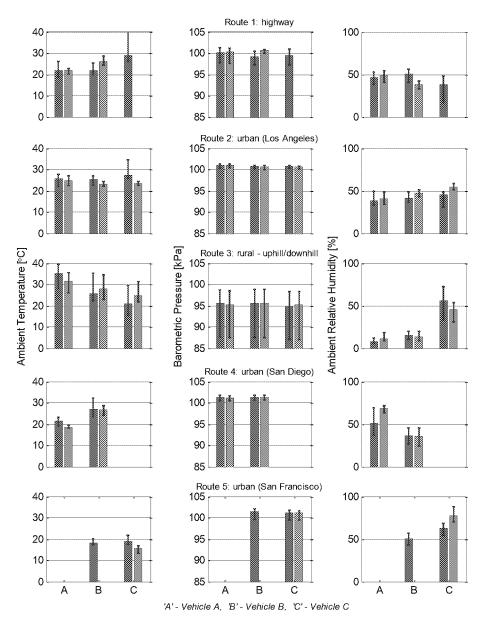


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average ambient conditions (temperature, barometric pressure, and relative humidity) experienced over five test routes for all

three vehicles. Note: variation intervals (red bars) refer to minimum and maximum values experienced over the test route

Relative positive acceleration (RPA) is a frequently used metric [[REF _Ref377225805 \r \h], [REF _Ref383178321 \r \h]] for the analysis of driving patterns and as input parameter to aid in developing chassis dynamometer test cycles representative of real-world driving. The RPA is calculated as the integral of the product of vehicle speed and positive acceleration for each instance in time, over a given 'micro-trip' of the test route under investigation as shown by Equation 4. For this study a 'micro-trip' was defined following the same convention as proposed by Weiss *et al.* [[REF _Ref377225805 \r \h]] as any portion of the test route, where the vehicle speed is equal or larger than 2 km/h for a duration of at least 5 seconds or more. Instantaneous vehicle acceleration was calculated according to Equation 5 by means of differentiating vehicle speed data collected via GPS, and subsequently filtered with negative values being forced to zero.

$$RPA = \frac{\int_0^{t_j} (v_i \cdot a_i) dt}{x_j}$$
 Eq. 4

where: t_j duration of micro-trip j

- x_j distance of micro-trip j
- v_i speed during each time increment i
- a_i instantaneous positive acceleration during each time increment i contained in the micro-trip j

$$a_{i} = \begin{cases} \frac{(v_{2} - v_{1})}{(t_{2} - t_{1})} & \text{if } i = 1\\ \frac{(v_{i+1} - v_{i-1})}{(t_{i+1} - t_{i-1})} & \text{if } 2 \le i \le n - 1\\ \frac{(v_{n} - v_{n-1})}{(t_{n} - t_{n-1})} & \text{if } i = n \end{cases}$$
Eq. 5

[REF _Ref368331107 \h] and [REF _Ref368331111 \h] depict the relative positive accelerations for routes 1 through 4, and 5, respectively, in comparison to RPAs for three chassis dynamometer vehicle certification test cycles (note: using vehicle speed set-point data for calculations). A distinct pattern can be recognized between the highway, rural, and urban test routes. The urban routes show a predominant cluster in the range of 15 to 40 km/h with RPA values between 0.2 and 0.6 m/s 2 , and up to 0.8 m/s 2 for the San Francisco route. The latter was

characterized by more pronounced grade changes (i.e. increased 'hilliness') and 'aggressiveness' of the driving pattern (i.e. increased stop-go). Furthermore, RPA values for the urban routes show similarity to RPA values calculated for the FTP-75 certification cycle. Average RPA values are shown in [REF _Ref368243033 \h].

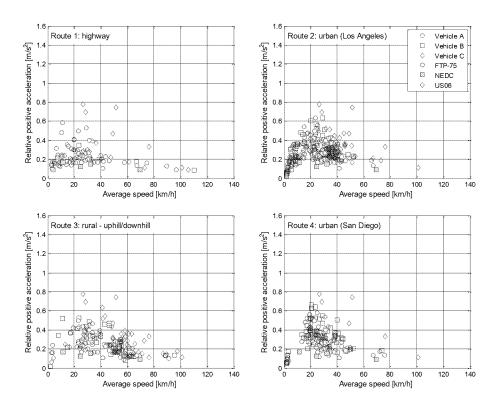


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Relative positive acceleration of subtrips composing test routes 1 through 4 in comparison to certification cycles (FTP-75, US06, and NEDC)

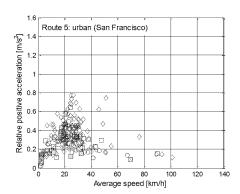


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Relative positive acceleration of subtrips composing test Route 5 in comparison to certification cycles (FTP-75, US06, and NEDC)

Interestingly, the relative positive acceleration values for highway driving, Route 1 (top left graph), were not well represented by the US06 certification cycle even though vehicle speed distributions were in good agreement with each other as previously shown in [REF _Ref368328818 \h] and [REF _Ref368263023 \h]. There are only a few matching RPA values at the upper end of the vehicle speed range (around 100 km/h). However, it has to be noted that the US06 certification cycle was not developed with the intention to be a representative test cycle but rather to address shortcomings of the FTP-75 cycle in representing high-speed driving and increased acceleration behavior (i.e. aggressive driving) [[REF _Ref383359521 \r \h], [REF _Ref383359523 \r \h]], thereby accounting for 'off-cycle' emissions not reflected in the standard FTP-75 certification cycle [[REF _Ref383359523 \r \h]]. The US06 cycle was adopted by the US-EPA in 1997 as part of the 'Supplemental Federal Test Procedure' (SFTP) (see Section [REF _Ref364013048 \r \h]) [[REF _Ref383359521 \r \h]]. The RPA values for the European certification cycle NEDC are well below the majority of RPA values calculated for all five test routes, whereas the US certification cycles (i.e. FTP-75, US06) appears to be more representative of real-world driving for a wide range of vehicle operating conditions for this test program.

3.2.2 Cross-Multi-State Driving Route

Vehicle B was selected to be driven over a total distance of 3968 miles between Los Angeles, CA and Seattle, WA in order to characterize after-treatment performance and emissions rates over an extended time of in-use operation. The route, hereinafter referred to as the 'cross-

multi-state driving route' comprises out/inbound Los Angeles to Seattle driving as well as urban/suburban vehicle operation in Seattle, WA and Sacramento, CA, and is dominated by a majority of 83.5% highway driving at speeds above 90 km/h. The average vehicle speed over the entire route was ~100 km/h with maximum speeds of up to ~140 km/h. [REF _Ref375422594 \h] lists additional characteristics for the cross-multi-state driving route including highway and urban/suburban vehicle operation (i.e. highway, Route 6, and Route 7).

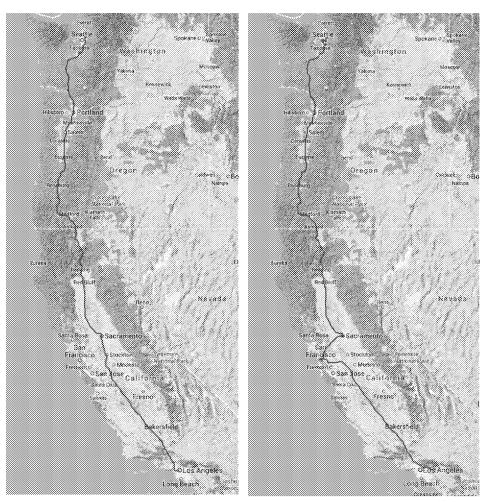
[REF _Ref375422908 \h] shows the topographic maps for the LA to Seattle route on the left following interstate I-5 North as well as the Seattle to LA route on the right. The return route from Seattle to LA included additional urban driving in Seattle, Sacramento and San Francisco (i.e. Route 5). [REF _Ref375423295 \h] and [REF _Ref375423297 \h] depict the topographical maps for the urban/suburban route in Seattle (referred to as 'Route 6') and urban route in Sacramento (referred to as 'Route 7'), respectively. Route 6 was driven in the morning, thus included rush-hour traffic from the surrounding residential suburban towns into downtown Seattle. Furthermore, Seattle is located in a hilly costal area, whereas Sacramento lies in the relatively flat San Joaquin valley.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Overall cross-multi-state route and driving characteristics

Parameters	Value
Route duration [hr]	39.31
Route distance [km]	3968.10
Avg. vehicle speed [km/h]	100.95
Max. vehicle speed [km/h]	120.00
Avg. RPA 13 [m/s2]	0.23
Characteristic Power [m²/s³]	2.63
Min. elevation [m a.s.l. 21]	1.0
Max. elevation [m a.s.l.]	1320.1
Share [%] (time based)	
- idling (≤2 km/h)	3.4
- low speed (>2≤50 km/h)	8.1
- medium speed (>50≤90 km/h)	5.0
- high speed (>90 km/h)	83.5

¹⁾ RPA - relative positive acceleration

²⁾ a.s.l. - above sea level





 $Figure \ [STYLEREF\ 1 \ \]. [SEQ\ Figure\ \ \ \ \ ARABIC\ \ \ \ 1\]: Topographic map of Route\ 6, urban\ and suburban\ driving\ around\ Seattle,\ WA$

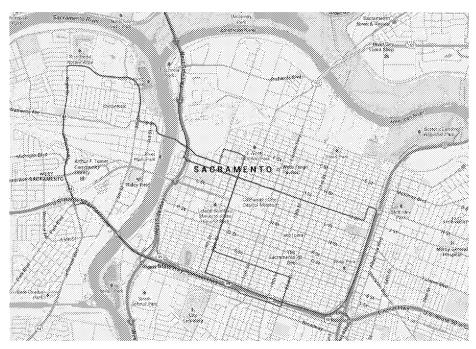


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Topographic map of Route 7, urban driving downtown Sacramento, CA

[REF _Ref377231241 \h] b) depicts the vehicle speed distribution for the entire cross-multi state driving route against standard chassis dynamometer test cycles. It can be noticed that even though 85% of the vehicle speeds are in excess of 90 km/h, and thereby significantly exceeding the high-speed (>90 km/h) contribution in the US06 cycle (i.e. 56%), the shape of the two vehicle speed distributions are comparable. The relative positive acceleration for the cross-multi state driving route is plotted in [REF _Ref377231241 \h] a), with urban/suburban driving (i.e. Seattle and Sacramento) contributing to the high RPA values at lower speeds (towards lower left corner), and highway driving predominantly to the low RPA values at high vehicle speeds (towards right corner). Furthermore, comparing RPA values in [REF _Ref377231241 \h] a) with values presented in [REF _Ref368331107 \h] and [REF _Ref368331111 \h] it is possible to identify the individual contributions of urban/suburban as well as high speed highway driving.

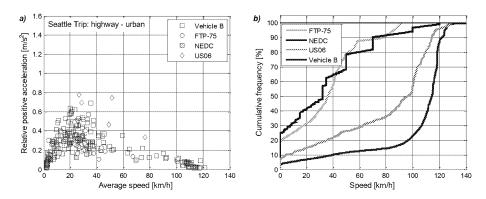


Figure [STYLEREF 1\s]. [SEQ Figure * ARABIC \s 1]: a) Relative positive acceleration of subtrips composing cross-multi-state route in comparison to certification cycles (FTP-75, US06, and NEDC); b) vehicle speed distributions of cross-multi-state route in comparison to certification test cycles

[REF _Ref377232580 \h] a) and [REF _Ref377232580 \h] b) shows the vehicle speed and altitude, respectively, for the entire cross-multi state driving route as a function of distance traveled. From the altitude graph (see [REF _Ref377232580 \h] b)), one can recognize the symmetry of the driving route predominantly following Interstate I-5 North and South. The reduced vehicle speeds at around 1800km and 3100km into the route mark the urban/suburban driving portions in Seattle, WA and Sacramento, CA, respectively. Furthermore, from the vehicle speed trace one can distinguish portions of the route where the vehicle was driven in cruise control mode (i.e. constant vehicle speeds), from parts where vehicle speed was manually governed by the pedal position of the driver.

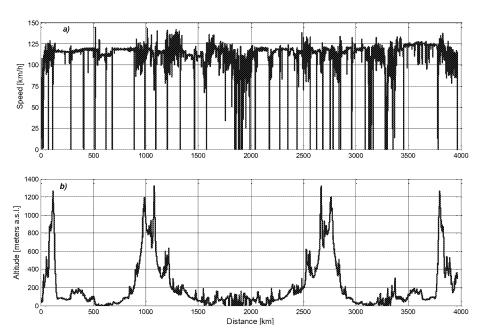


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: a) Characteristic vehicle speed and, b) altitude profile of cross-multi-state route given in meters above sea level (a.s.l.)

Finally, [REF _Ref377233500 \h] lists the individual readiness of the primary instruments and data acquisition components, namely for i) gaseous, ii) particle, and iii) vehicle parameters, that have been utilized to collect data during the cross-multi state driving route. It can be noticed that gaseous and particle matter emissions were collected for ~60% of the entire route, corresponding to approximately 2300km. Instrument operation got primarily limited due to i) cold temperature conditions during late night driving (e.g. sample condensation issues inside analyzer units), and ii) rain fall during portions of the route between Seattle and Sacramento. It has to be noted that instrument readiness was 100% for vehicle testing over the pre-defined test routes (Route 1 to 5).

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Instrumentation readiness during cross-multi state driving route

Instrument	Total time of operation	Fraction of total trip duration	Total distance of operation	Fraction of total trip distance
	[hr]	[%]	[km]	[%]
OBS (gaseous emissions)	23.6	60.1	2352.0	59.3

T*/*T* /		

[REF _Ref368244263 \h] along with [REF _Ref383367995 \h] provide ambient air conditions, including barometric pressure, temperature, and relative humidity encountered during the entire cross-multi-state route as a function of distance traveled. Ambient temperatures ranged from below freezing to ~+30°C with an average temperature of around 13°C as seen from [REF _Ref383367995 \h].

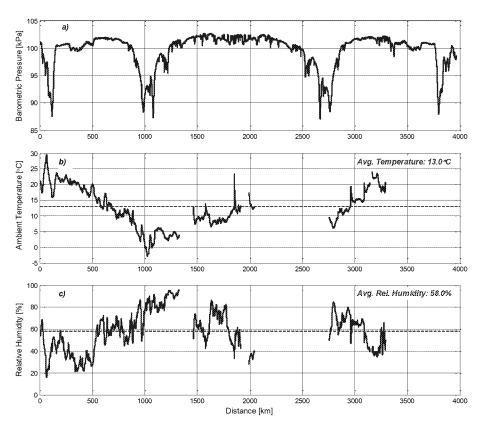


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: a) Barometric pressure, b) ambient temperature, and c) relative humidity experienced during cross-multi-state route as a function of distance traveled (Note: missing data for b) and c) is due to non-operational ambient sensor)

 $\label{lem:conditions} Table \ [STYLEREF 1 \ \]. [SEQ \ Table \ \ \ \ ARABIC \ \ \ 1 \]: Range \ of ambient conditions experienced during cross-multi state route$

Ten	aperature [C]	Baro, Pressure [k	Paj Rei. Hu	midity %
Average	12.97	99.63	5	57.95
Minimum	-2.87	86.97	1	15.84
Maximum	29.65	102.43	g	06.02

3.3 Emissions Testing Procedure and PEMS Equipment

The emissions sampling setup employed during the course of this study comprised three measurement sub-systems as shown in the schematic in [REF _Ref368226689 \h]. Gaseous exhaust emissions were quantified using the on-board measurement system, OBS-2200, from Horiba described in more detail in Section [REF _Ref368226827 \r \h]. Real-time particle number concentration measurements were performed using the Pegasor particle sensor (PPS), model PPS-M from Pegasor Ltd. discussed in Section [REF _Ref368226934 \r \h], while particle mass measurements were made with the OBS-TRPM system from Horiba as described in Section [REF _Ref368229523 \r \h]. The Horiba OBS-2200 PEMS system was chosen for this study as it is an approved device under the US EPA heavy-duty in-use emissions compliance program and complies to the EU 582/2011 in-use emissions measurement requirements as well.

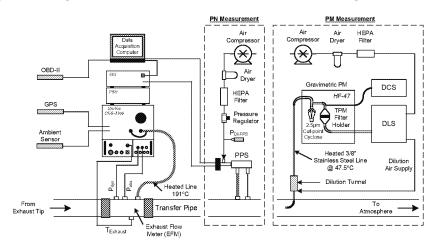


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Schematic of measurement setup, PN measurement for Vehicles A and B, PM measurement for Vehicle C

[REF _Ref368236846 \h] lists all the parameters and emissions constituents collected during on-road testing for this study. Emissions parameters were sampled and stored continuously at 10 Hz frequency, whereas GPS and ECU data were updated at 1 Hz, but stored at the same frequency as emissions data (i.e 10 Hz) by the data acquisition system. An external sensor was used to measure ambient conditions, including temperature, barometric pressure and relative humidity, feeding data directly to the OBS data acquisition software. Vehicle position (i.e. longitude, latitude and altitude) and relative speed were measured by means of a GPS

receiver, allowing for subsequent calculation of instantaneous vehicle acceleration and distance traveled. An additional high, resolution barometric pressure sensor was used to calculate road grade changes and altitude as an alternative to the GPS signal based on Equation 3 as presented in Section [REF _Ref368241950 \r \h].

Engine specific parameters were recorded from publicly broadcasted ECU signals through the vehicles OBD-II port using a commercially available CAN logging software called AutoTap® from B&B Electronics Manufacturing Company Inc. Logged parameters included engine speed and load, intake air mass flow rate and exhaust temperatures. *Vehicle A* broadcasted DPF outlet temperature, whereas *Vehicle B* broadcasted two exhaust temperatures, namely the DPF inlet and SCR inlet temperatures.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Overview of measured parameters and respective instruments/analyzers

Category	Parameter	Measurement Technique	
	THC [ppm]	FID (Horiba OBS-2200)	
	CO [%]	NDIR (Horiba OBS-2200)	
Exhaust gas pollutants	CO ₂ [%]	NDIR (Horiba OBS-2200)	
	NO _x [ppm]	CLD (Horiba OBS-2200)	
	H ₂ O [%]	NDIR (Horiba OBS-2200)	
	Exhaust flow rate [m³/min]	EFM (Horiba OBS-2200)	
Exhaust flow	Exhaust temperature [°C]	EFM, K-type thermocouple	
	Exhaust absolute pressure [kPa]	EFM (Horiba OBS-2200)	
E I DEUDEI	PN concentration [#/cm³]	Pegasor Particle Sensor	
Exhaust PN/PM emissions	PM (gravimetric) [mg]	Horiba OBS-TRPM	
	Ambient temperature [°C]	Temp. Sensor (OBS-2200)	
Ambient conditions	Ambient humidity [%]	Humidity Sensor (OBS-2200)	
	Barometric pressure [kPa]	Pressure Sensor (OBS-2200)	
	Vehicle speed [km/h]	GPS	
****	Vehicle position [°]	GPS	
Vehicle/route characteristics	Vehicle altitude [m a.s.l.]	GPS	
Character istics	Vehicle acceleration [m/s²]	Derived from GPS data	
	Vehicle distance traveled [km]	Derived from GPS data	
	Engine speed [rpm]	ECU OBD-II	
F	Engine load [%]	ECU OBD-II	
Engine characteristics	Engine coolant temperature [°C]	ECU OBD-II	
	Engine intake air flow [kg/min]	ECU OBD-II	

Exhaust temperature [°C] ECU OBD-II

[REF _Ref368238488 \h] gives the combination of measurement sub-systems employed for the individual test vehicles. Gaseous emissions of CO, CO₂, THC, and NO_x were measured for all three vehicles, whereas particle number concentration measurements via the PPS were only performed for *Vehicles A* and *B* and particle mass quantification via the OBS-TRPM only for *Vehicle C*.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Emissions constituent measurement matrix

Component	Vehicle A Vehicle B Vehicle C
Gaseous emissions	$X \qquad X \qquad X$
Particle number (PPS)	X X
Particle mass (OBS-TRPM)	X

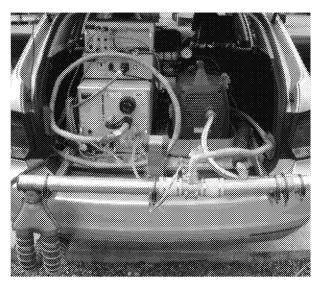


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Vehicle A instrumentation setup

[REF _Ref368238738 \h] through [REF _Ref368238740 \h] depict the experimental setup and instrument arrangement inside the test vehicles, *Vehicle A*, *B*, and *C*, respectively. For onroad testing with both *Vehicles A* and B_{ϵ} a 2kW Honda generator (gasoline fueled) was utilized to supply the necessary electrical power to operate the OBS, PPS and ancillary systems. The power

requirements for the OBS-TRPM however, required the addition of a second 2kW Honda generator to support the power demand for the entire sampling setup during testing of *Vehicle C*. Using a vehicle independent power generator had the advantage of not having to draw any current from the test vehicles power system; hence, no additional load was added to the engine which might have skewed the emissions production rate and therefore the results of this study. On the other hand, it has to be noted that the addition of measurement equipment was increasing the actual vehicle weight, thereby possibly influencing the engine's load demand and resulting emissions rates. The payload of *Vehicles A* and *B* was representative of four adult passengers totaling 300kg when assuming 75kg per individual passenger (i.e. *Vehicle A*: 305kg, *Vehicle B*: 314kg), whereas *Vehicle C*'s payload had to account for additional 230kg (i.e. 533kg).

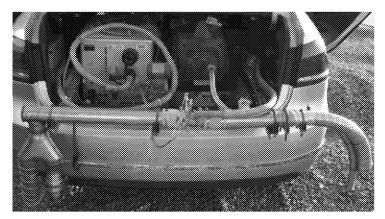


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Vehicle B instrumentation setup

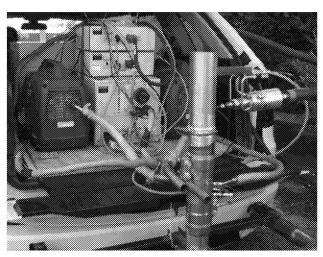


Figure | STYLEREF 1 \s |. | SEQ Figure * ARABIC \s 1 |: Vehicle C instrumentation setup

3.3.1 Gaseous Emissions Sampling - Horiba OBS-2200

Gaseous raw emissions, including CO, NO_x , THC as well as CO_2 were measured on a continuous basis using the Horiba OBS-2200 on-board emissions measurement system which has been specifically developed with regard to PEMS requirements for on-road vehicle emissions testing according to recommendations outlined in CFR, Title 40, Part 1065. The emissions of CO and CO_2 were measured using a non-dispersive infrared (NDIR) spectrometer (heated wet sample), THC using a flame ionization detector (FID) (heated wet sample), and total NO_x using a chemiluminescence detector (CLD) in conjunction with an NO_2 -to-NO converter (heated wet sample). The Horiba OBS system gives the option to either sample in NO_x mode (NO_2 -to-NO converter on) or NO mode (NO_2 -to-NO converter off), however, for the entire duration of this study the instrument was solely operated in NO_x mode (total NO_x measurement). Detailed information regarding the chosen measurement ranges, span values to which the analyzers were calibrated to, as well as analyzer linearity, accuracy and repeatability of the Horiba OBS-2200 system are given in [REF _Ref368007707 \h].

Gaseous emissions were extracted by means of an averaging sample probe through a ½" NPT port installed on the exhaust flow meter adapter that was mounted to the exhaust end pipe. The exhaust sample was directed through a heated line, maintained at a nominal temperature of 191°C using a PID-type controller, to the analyzer inlet port.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Horiba OBS-2200, Gaseous analyzer specifications [[REF _Ref368245840 \r \h]]

omp.	Range	Span	Linearity	Accuracy	Repeatability
CO	0.1 vol.%	0.099%	within ±1.0% of full scale	within ±2.5% of full scale	Zero: within $\pm 1.0\%$ of full scale Span: within $\pm 1.0\%$ of readings
CO ₂	12 vol.%	11.9%	within ±1.0% of full scale	within ±2.5% of full scale	Zero: within $\pm 1.0\%$ of full scale Span: within $\pm 1.0\%$ of readings
NO _x	1600 ppm	1492ppm	within ±1.0% of full scale	within ±2.5% of full scale	Zero: within $\pm 1.0\%$ of full scale Span: within $\pm 1.0\%$ of readings
THC	350 ppm	303ppm	within ±1.0% of full scale	within ±2.5% of full scale	Zero: within $\pm 1.0\%$ of full scale Span: within $\pm 1.0\%$ of readings

The exhaust flow meter (EFM), used in conjunction with the OBS-2200 instrument is a Ppitot-tube type flow meter involving the measurement of dynamic and static pressure heads by means of differential and absolute pressure transducers. The fluid temperature (exhaust gas) is measured via a K-type thermocouple allowing to adjust the exhaust gas flow measurement to EPA defined standard conditions (i.e. 293.15K and 101.325 kPa). Additional to pressure and thermocouple ports the EFM adapter features a port for connecting the exhaust gas sampling probe. An averaging type probe with multiple holes spanning the entire EFM adapter's diameter was used to extract continuous exhaust samples. Depending on the vehicle tested two differently sized EFM units were utilized for this study. An EFM adapter with 2" diameter (ID) was installed for testing *Vehicles A* and *B* as shown in [REF _Ref368217856 \h] and [REF _Ref368218298 \h], respectively, whereas a 3.5" diameter EFM was employed during *Vehicle C* testing as depicted in [REF _Ref368217891 \h].



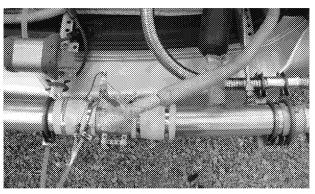


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Exhaust adapter setup for Vehicle A, left: flexible high temperature exhaust hose connecting double vehicle exhaust tip to exhaust transfer pipe, right: 2" exhaust flow meter (EFM)



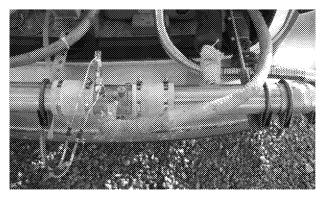
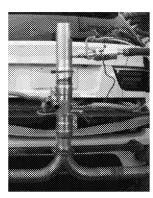


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Exhaust adapter setup for Vehicle B, left: flexible high temperature exhaust hose connecting single vehicle exhaust tip to exhaust transfer pipe, right: 2" exhaust flow meter (EFM)

Prior to vehicle testing, the exhaust flow meter units were verified against a NIST traceable laminar flow element (LFE) installed on a flow bench at WVU's on-campus laboratory (i.e. EERL). A least-square regression analysis between the LFE and the EFM measurements resulted in a coefficient of determination (R^2) of 0.9986 and 0.9989 for the 2" and 3.5" EFM adapter, respectively.



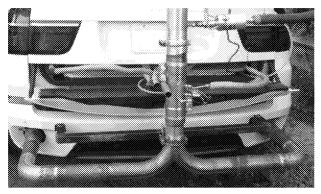


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Exhaust adapter setup for Vehicle C, left: 3.5" exhaust flow meter (EFM), right: joining double vehicle exhaust stack into exhaust transfer pipe

3.3.2 PEMS Particle Mass/Number Measurements

PEMS development for PM quantification (PM-PEMS) during on-road operation has been primarily driven by the heavy-duty diesel sector in recent years. Numerous studies were performed within the US [[REF Ref368146041 \r \h]] and Europe [[REF Ref368146045 \r \h], [REF _Ref368146049 \r \h], and [REF _Ref368146052 \r \h]] aimed at evaluating the sensitivity and accuracy of different PM-PEMS, their comparability to the standard engine certification method (i.e. gravimetric sampling via CVS) as well as the feasibility and practicality of their application in a harsh environment such as on-road emissions measurement. Giechaskiel et al. [[REF _Ref368146057 \r \h]] recently performed a comprehensive study comparing commercially available PM-PEMS and PM sensors to the standard gravimetric PM sampling method used for engine certification and type-approval, with regard to particle mass and number concentration measurements during in-use testing. The authors specifically highlighted the advantage of particle number (PN) measurement approaches, due to their possible applicability to future PN emissions standards as will be introduced in the EURO VI heavy-duty regulation by 2014. Based on the positive performance of the Horiba OBS-TRPM system during the aforementioned studies [[REF _Ref368146041 \r \h], [REF _Ref368146045 \r \h], [REF Ref368146049 \r \h], [REF Ref368146052 \r \h], and [REF Ref368146057 \r \h]] and due to the fact that this system is currently the only commercially available system with approval from the European Union for heavy-duty on-road PM measurement, Horiba's PM-PEMS system was chosen to conduct PM sampling during this study. On the other hand, the Pegasor particle sensor, model PPS-M from Pegasor Ltd., was selected for on-line particle number concentration measurements directly from the raw exhaust stream.

3.3.2.1 Gravimetric PM Measurement with Horiba OBS-TRPM

As described earlier Horiba's OBS-TRPM (On-Board System for Transient PM Mass Measurement) system was selected to perform in-use particle mass quantification. This instrument has been specifically developed for the primary purpose of in-use certification of onroad heavy-duty diesel vehicles, as mandated by the US Environmental Protection Agency (US-EPA) [[REF _Ref368146094 \r \h]] and is designed for use in conjunction with Horiba's OBS-2200 gaseous system. The OBS-TRPM is a combination of a proportional diluted sampling system for gravimetric PM sampling on 47mm filter media and real-time measurements of particle length [mm/cm³] (including soot, sulfates and volatile particles), which can be defined as the product of total number concentration and average particle diameter, by means of a diffusion charging type sensor called Electrical Aerosol Detector (EAD) from TSI Inc. The underlying assumption is that the mass accumulated on the filter is proportional to the PM length parameter as measured by the EAD, therefore, making the OBS-TRPM ultimately capable of calculating a quasi "real-time" PM mass concentration rate. However, the gravimetric sampling component of the OBS-TRPM, requiring physical weighing of the filter media on a microbalance, makes "realtime" PM mass concentration information only available after post-processing of the measured data.

A proportional sample was extracted through a 3/8" stainless steel J-type probe located downstream the OBS exhaust flow meter unit. Proportionality was calculated based on the EFM signal and controlled by a series of fast acting piezo-valves and mass-flow controllers (MFC). Close-coupled to the sampling probe was a dilution unit (i.e. "dilution tunne?") that uniformly introduced HEPA filtered dilution air. A ½" heated stainless steel line connected the dilution unit to the temperature controlled filter holder compartment (called "HF-47", see [REF _Ref368165720 \h]) where the exhaust sample was first directed through a PM_{2.5} cut-point cyclone separator to remove particles bigger than 2.5μm (50% efficiency at cut-point), and then through the filter media holder where PM was retained on 47mm Pallflex® Quartz-fiber filter

(TX40) membranes (Pall Corporation) for subsequent gravimetric analysis. All components, including, dilution tunnel, transfer line and HF-47 filter box were heated in order to maintain the filter-face temperature at constant 47±5°C. A constant slip stream was extracted from the sample flow before entering the filter media holder and routed to the diffusion-charger (i.e. EAD) for quantification of the particle length parameter. Dilution and sample flows for the entire system were controlled by the flow control unit (called "DLS").

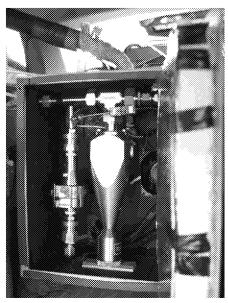


Figure [STYLEREF 1\s].[SEQ Figure * ARABIC\s 1]: Horiba OBS-TRPM heated filter holder box for gravimetric PM quantification, sample is introduced from the top, *left*: 47mm filter holder, *right*: 2.5 cut-point cyclone

All filter media (i.e. TX40 membranes) used during the course of this study were pre and post-weighed at CAFEE's on-campus clean room facility and shipped (overnight) to and back from the vehicle testing location in California. The clean room is environmentally controlled (Class 1000, maintained at 21°C and 50% RH), thus allowing for stable conditions for PM filter media handling, storage and weighting procedures. A Sartorius microbalance with a minimum detection limit of 10 µg and an accuracy of 0.1µg was utilized to pre and post-weigh filter media. The measurement system was operated with in-house developed software to calibrate the scale, perform measurements, as well as to monitor the <u>history of</u> individual filter membranes-history.

3.3.2.2 Real-Time PM Measurement with Pegasor Particle Sensor

Particle number concentration measurements were performed using the Pegasor particle sensor, model PPS-M from Pegasor Ltd. (Finland) [[REF _Ref368146109 \r \h * MERGEFORMAT]] which is capable of performing continuous measurements directly in the exhaust stack and providing a real-time signal with a frequency response of up to 100Hz (see [REF Ref341869523 \h * MERGEFORMAT]). The sensor operates as diffusion-charging (DC) type device and measures PM based on the current induced by the charged particles leaving the sensor. [REF Ref368146221 \h * MERGEFORMAT] shows the PPS as well as the sample gas flow paths. Dry, HEPA filtered dilution air is supplied at about 22psi and subsequently charged by a unipolar corona discharge charger using a tungsten wire at ~2kV and 5µA. The pressurized dilution air, carrying the unipolar ions, then draws raw exhaust gas through an ejector-type diluter into a mixing chamber, where the ions are turbulently mixed with exhaust aerosol particles for diffusion charging. The sample gas flow is controlled by means of a critical flow orifice and is a function of the supplied dilution air pressure. An electrostatic precipitator (ion trap), installed downstream of the mixing chamber and operating at a moderate voltage of approximately 100V, traps excess ions that escaped the charging zone. Finally, the charge of the out-flowing particles is measured using a built-in electrometer. The measured current signal is amplified and filtered by the internal electronic control unit of the sensor and outputted either as a voltage or current value. The sensors output can be subsequently correlated to other aerosol instruments by means of linear regression in order to measure the concentration of the mass, surface or number of the exhaust particles, depending on the chosen reference instrument.

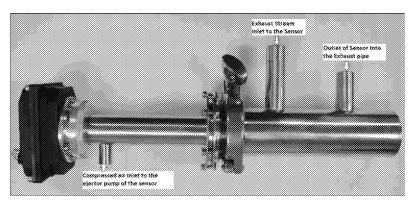


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Pegasor particle sensor, model PPS-M from Pegasor Ltd. (Finland)

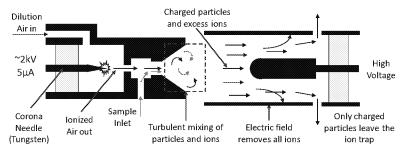


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: PPS measurement principle with sample gas and dilution air flow paths [[REF _Ref368146168 \r \h], [REF _Ref368146171 \r \h]]

Extensive testing of this sensor at the engine testing facility at WVU, has shown the capability of this sensor to accurately measure the total PM concentration in comparison to other standard aerosol instruments such as the Ultrafine Condensation Particle Counter (TSI UCPC, Model 3025), the Engine Exhaust Particle Sizer spectrometer (TSI EEPSTM, Model 3090) as well as the Micro-Soot Sensor (MSS) from AVL (Model 483) [[REF _Ref368146171 \r \h * MERGEFORMAT]]. The sensor was designed as a flow through device and therefore does not involve collection or contact with particles in the exhaust stream, which is especially advantageous for long-term stability and operation without frequent maintenance; hence, best suited for in-use application.

[REF _Ref368146502 \h] shows the positioning of the PPS within the test vehicle. The sensor was enclosed in a compartment (green box seen in [REF _Ref368146502 \h]) that

provided thermal insulation from the surroundings. Additionally, the sensor was wrapped in insulation material and a resistive heater, in conjunction with a PID controller, maintained the sensor core at a nominal 200°C in order to prevent condensation of volatile components within the sensors. A three_-foot heated sampling line (maintained at 200°C) was used to transfer the extracted exhaust sample from the exhaust transfer pipe to the PPS inlet, whereas a non-heated, but thermally insulated stainless steel line was used to direct the sample exiting the PPS back to the exhaust transfer pipe.

Pressurized air supply for the PPS was provided by a small electrical air compressor (Blue Hawk, 0.3hp with 2 gallon reservoir). Prior to the sensor inlet_a the pressurized air was dried and HEPA filtered as can be seen in the top left corner of [REF _Ref368146502 \h]. A manually adjustable pressure control value was used to maintain the dilution air supply pressure at constant 22 psi (~ 1.5bar). As the PPS draws and dilutes the exhaust sample via an ejector type diluter/pump and controls the sample and dilution air flows, and thus, the internal dilution ratio, by means of a critical flow orifice, knowledge of the dilution air pressure is required to calculate particle number concentrations in the exhaust stream. An absolute pressure transducer (Omega, model PX602, range 30psi) was used to continuously measure the dilution air pressure.

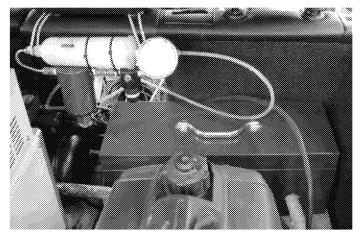


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: PPS setup, the sensor is housed within the green box, *top left*: pressurized, dried and HEPA filtered air supply for PPS

Using the dilution air pressure as input to linear Equation 6 the sample flow rate can be calculated as a function of constant coefficients β_0 and β_1 only. These coefficients depend on the

internal configuration (i.e. orifice dimensions) of the PPS and were evaluated as $\beta_0 \approx 3.668$ and $\beta_1 \approx 0.105$ for the sensor used during the course of this study.

$$\dot{V}_{sample}[slpm] = \beta_1 \cdot P_{Dil}[psi] + \beta_0$$
 Eq. 6

For the purpose of this study the raw sensor signal was calibrated for both particle number concentration in [#/cm³] as well as particle mass concentration in [mg/m³] by means of the linear calibration coefficients developed by Ntziachristos et al. [[REF _Ref368168904 \r \h], [REF _Ref368168906 \r \h]], and given by Equations 7 through 10 with constant $C_1 = 3333.33$.

$$PN\left[\#/cm^{3}\right] = f_{N}(\dot{V}, C_{N-calib}) \cdot PPS_{Signal}[mV]$$
 Eq. 7

$$PM [mg/m^{3}] = f_{M}(\dot{V}, C_{M-calib}) \cdot PPS_{Signal}[mV]$$
 Eq. 8

$$f_N = \frac{288}{\dot{V}_{sample}[slpm]} \cdot C_1$$
 Eq. 9

$$f_M = \frac{6.3 \cdot 10^{-5}}{\dot{V}_{sample}[slpm]} \cdot C_1$$
 Eq. 10

The particle number concentration measurement setup (i.e. PPS) used in this study was designed and configured to follow the spirit of the Particle Measurement Program (PMP) method as mandated by the European Union [[REF _Ref382820874 \r \h], [REF _Ref383388345 \r \h]] for regulatory particle number concentration quantification. The three foot sample transfer line and the PPS sensor itself were heated and maintained at a nominal temperature of 200°C, thereby reducing the probability for volatile and semi-volatile components to condensate and possibly nucleate and form measurement artifacts. Even though the PPS temperature of 200°C is below the recommended temperature for the first stage dilution (150 to 400°C) and evaporation tube (300 to 400°C) it has to be considered that the PMP method is designed to sample from an already diluted, and therefore 'cooled', sample stream from either a constant volume sampling (CVS) or partial dilution system [[REF _Ref383388345 \r \h]] as opposed to the PPS sampling from the raw exhaust at elevated gas temperatures. Particle nucleation phenomena are strongly driven by exhaust gas dilution and cooling which does not occur when the sample is extracted

directly from the exhaust stack (or transfer line). As described earlier, the PPS requires a small amount of pressurized dry air to drive the sample flow via an internal ejector diluter, however, the dilution process is assumed to be rapid and without the necessary residence time required to form artifacts before particle charging and measurement occurs. It is therefore believed that the measurement setup used in this study mainly detects solid particles as required by the PMP method.

The electrostatic precipitator (ion trap) installed downstream the mixing chamber of the PPS allows, depending on the voltage applied, not only to remove excess ions but also to trap particle of a certain mobility diameter. Increasing the voltage on the center electrode leads to a stronger electrical field causing particles to deflect and impact inside the PPS, and thereby escape from being counted. This particle removal mechanism can be utilized towards inducing a lower particle cut-point similar to the 50% counting efficiency for particles of 23nm in an ultrafine particle counter as recommended by the PMP method [[REF Ref383388345 \r \h]].

Based on the above discussion it can be concluded that, even though the PPS method for particle number concentration measurements does not comply with recommendations outlined in the European regulation for PN measurements [[REF _Ref382820874 \r \h], [REF _Ref383388345 \r \h]], it follows the spirit of the PMP method of counting 'only solid particles of size larger than 23nm' (and smaller than 2.5μm). Tikkanen et al. [[REF _Ref383388416 \r \h]] found good agreement between a PPS measuring directly from the exhaust stack and a second PPS, equipped with a catalytic stripper (CS) to remove volatile and semi-volatile particles, sampling from the diluted exhaust gas in a CVS system for both light and heavy-duty engines. Finally, it has to be emphasized again that the PPS does not directly measure particle number concentrations but rather infers PN counts from a charge measurement as opposed to the ultrafine particle counters required by the PMP method [[REF _Ref383388345 \r \h]] that are based on optical counting of individual particles after they were allowed to grow to a detectable size in a saturated Butanol or water environment.

Therefore, the reader is cautioned when directly comparing the particle number concentration results presented in this report (see Results and Discussion, Section [REF_Ref383387177 \r \h * MERGEFORMAT]) with European PN limits (i.e. Euro 5b/b+ [[REF_Ref382821534 \r \h]]) for light-duty diesel vehicles as the measurement method used during

this study differs from the measurement protocol set forth by the European Union [[REF _Ref382820874 \r \h], [REF _Ref383388345 \r \h]]. An additional and more detailed discussion about the PMP method required for PN measurements according to the European regulation is given in Appendix [REF _Ref383387798 \r \h].

3.3.3 PEMS Verification and Pre-test Checks

3.3.3.1 PEMS Verification and Analyzer Checks

All PEMS instruments employed during the course of this study were calibrated, verified and operated according to manufacturer's recommendations and requirements outlined in CFR, Title 40, Part 1065, Subparts D and J [[REF_Ref368330162 \r \h]]. Individual analyzers of the OBS system were calibrated and verified prior to deployment of the instrument to the field at WVU's on-campus laboratory. The following discussion will briefly outline the verification and system checks performed on the OBS-2200 instrument.

As recommended by the manufacturer, "amplifier zero" and "detector gain" adjustments for flame ionization detector and chemiluminescence detector, and "amplifier gain" adjustments for the FID were performed prior to analyzer linearization as these adjustments affect the sensitivity of the FID and CLD analyzers. Following this, analyzer "linearity" verifications were performed for each individual analyzer (i.e. CO, CO₂, THC, and NO_x) by flooding the instruments inlet port with a calibration gas mixture, blended at 10 different ratios equally spaced across the selected measurement range for a given analyzer. A least-squares regression analysis was subsequently performed between the analyzer's response and the theoretical calibration gas blend concentrations and verified to comply with linearization criterions as per 40 CFR §1065.307.

After "linearity" verifications a set of interference checks was performed in order to quantify the amount of interference between the component being measured and any other components that are known to interfere with its measurement and that are ordinarily present in the exhaust gas sample. These include, CO₂ and water (H₂O) quench checks on NO_x, CO₂, propane (C₃H₈), and H₂O interference checks on CO, oxygen (O₂) interference check on THC, as well as CO, C₃H₈, and H₂O interference checks on CO₂. The Horiba OBS-2200 system automated these procedures to help guide the operator through the respective processes with a routine that compares interference results against pre-determined limits based on 40 CFR 1065

Subpart D and J. Additionally, NO_x converter efficiency and THC hang-up checks were performed to ensure proper analyzer response.

The heated sample lines for gaseous (OBS-2200) and PM (OBS-TRPM) samples were checked for any leaks, and for proper control of the heated surfaces. Leak checks were performed via a vacuum-side leak verification (40 CFR §1065.345), using a pressure calibration device, and temperature traces were established with a thermocouple and thermocouple calibrator.

The OBS-TRPM system was verified according to manufacturer recommendations, involving various leak checks and sample flow checks using calibrated reference mass flow meters.

3.3.3.2 PEMS Installation and Testing

After initial installation of the PEMS on the test vehicle and prior to start of each test day, the PEMS was warmed-up and allowed to thermally stabilize for at least one hour. After warm-up and prior to start of each test route "zero" and "span" checks and adjustments were performed for each analyzer, followed by an automated internal system check.

Prior to start of testing, the PEMS equipment was validated by placing all systems in sample mode with the test vehicle's engine turned on and set to idle operation. During this time, each measurement was checked for consistency, using good engineering judgment.

"Zero" and "span" checks and adjustments were performed before and immediately after completion of each test route and analyzer drift values were automatically recorded by the OBS software for subsequent drift correction of measurement results.

3.3.3.3 PEMS Comparison with CVS System

One out of the three test vehicles, specifically the *Vehicle B*, was selected for a cross-correlation evaluation between the OBS-2200 PEMS and laboratory grade instruments while the vehicle was operated over standardized test cycles on a chassis dynamometer at CARB's light-duty constant volume sampling (CVS) test facility in El Monte (CA). This allowed to establish confidence into the measurement results of the PEMS, as well as to identify possible issues with the on-road measurement setup.

The same 2" diameter (ID) EFM adapter as used during on-road testing of *Vehicles A* and *B* (see [REF _Ref368217856 \h] and [REF _Ref368218298 \h]) was installed into the exhaust transfer line leading from the vehicles exhaust tip to the CVS tunnel as shown in [REF _Ref383396803 \h] (see right side of figure). The OBS-2200 PEMS was setup and configured in the same manner as it was used during on-road testing, measuring raw exhaust gas concentrations of CO₂, NO_x, CO, and THC, volumetric exhaust flow, and ambient air conditions inside the test cell. Also, the Pegasor particle sensor was installed downstream the EFM using the same sample extraction configuration as during on-road testing. Upstream of the OBS-2200 sampling location, CARB personnel installed a Semtech-DS PEMS unit from Sensors Inc. along with an exhaust flow meter allowing for additional cross-correlation of between two different PEMS instruments. Furthermore, an AVL SESAM FTIR multi-component measurement system sampling raw exhaust gas as well as an AVL Particle Counter (APC) and an Engine Exhaust Particle Sizer (EEPS®) spectrometer (model 3090) from TSI Inc. quantifying particle number concentrations and size distributions from diluted exhaust (CVS) were being operated during chassis dynamometer testing of *Vehicle B*.

However, this report will only present and discuss cross-correlation analysis performed between regulated exhaust gas constituents measured with the OBS-2200 PEMS and the CVS system, including CO₂, NO_x, CO, and THC.

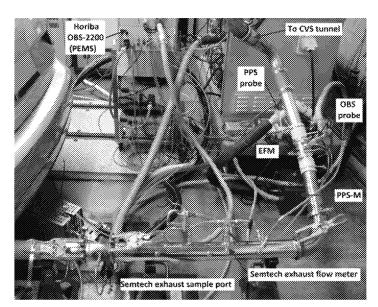


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Experimental setup and exhaust sample extraction during chassis dynamometer testing of Vehicle B at CARB's El Monte, CA, vehicle test facility

Experiments were performed over three certification test cycles, namely the FTP-75, US06, and the European NEDC using the same test fuel as has been used during the on-road emissions testing (see Appendix [REF _Ref382841455 \r \h] for fuel specifications). [REF _Ref377289209 \h] depicts the continuous emissions mass rates of both PEMS and CVS system in [g/s] over the three bags of the FTP-75 cycle, where 'Bag 1' is a cold start and transient phase, 'Bag 2' the stabilized phase followed by a 10min hot soak, and finally 'Bag 3' a hot start and transient phase (same vehicle speed as 'Bag1').

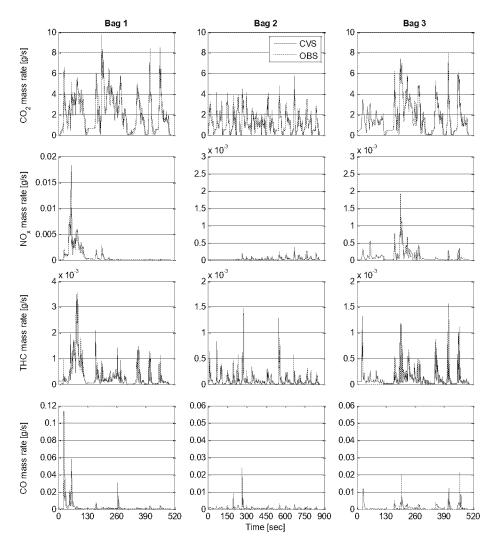


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Emissions rate comparison between CVS laboratory (CARB, El Monte CA) and Horiba OBS-2200 PEMS measurements over the FTP-75 standard chassis dynamometer test cycle

In parallel, [REF _Ref377050494 \h] shows results from a linear regression analysis between emissions rates measured by the CVS system and PEMS with the CVS system being considered the reference method. It has to be noted that for 'Bag 3' data collection with the

PEMS only started after 130 seconds, as visible from the graphs in [REF _Ref377289209 \h]. Therefore, data points for the first 130 seconds of 'Bag 3' were not considered for the linear regression analysis presented in [REF _Ref377050494 \h].

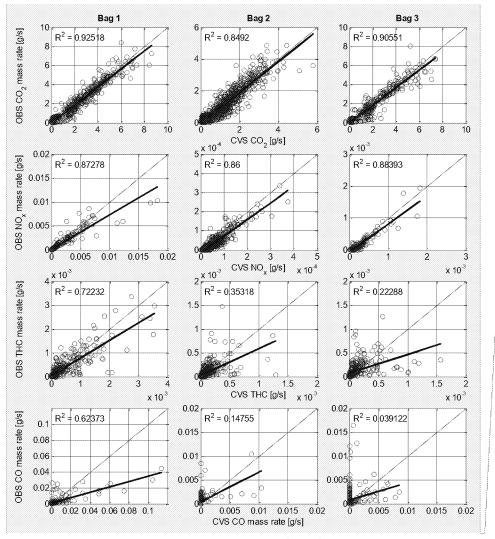


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Linear regression analysis between CVS laboratory (CARB, El Monte CA) and Horiba OBS-2200 PEMS measurements over the FTP-75 standard chassis dynamometer test cycle

Commented [VF7]: I have some reservations about the usefulness of this chart. Looking at Figure 3.32, one can see that the CO2 peaks are being captured better by the PEMS (the top of the spikes is red; CO is also like that but less consistent), but for the other pollutants it is mostly blue at the top (the spikes are more pronounced at the CVS). The spikes being higher at the CVS is contrary to logic (the peaks should be smoothed out as they travel along the raw gas line and the dilution tunnel); I would guess this is an artifact due to the slower response of the FID/CLD (THC/NOx) compared to the NDIR (CO2/CO) [the PEMS has quick-response analyzers for CO/CO2, not so much for THC/NOx, and the smoothing effect of these slow analyzers is greater than the combined smoothing effect of travelling within the CVS setup + response of diluted analyzers]. Now, my point would be that the instantaneous correlation of the signals is not relevant, because the CVS signals are (seriously) affected by variable transport times at the raw gas line and they are not really a good reference for instantaneous emission values (the PEMS may actually be better for that!). So, even after aligning the signals (globally), you are still left with local misalignments that dramatically affect correlation. This is especially true if you have a signal with just a few peaks/features: a small misalignment of 1-3 seconds (which I am pretty sure is there, although it cannot be appreciated at the zoom level of figure 3.32) will give you really bad instantaneous correlation even though overall the red and the blue signals visually match just fine. What's important though is not local or global correlation, but to make sure that the total mass seen by the CVS and the mass seen by the PEMS is more or less the same; i.e., that the area under the red and blue signals of figure 3.32 is similar (for overall mass the CVS is definitely the reference). This is what should be reported (maybe in a table), and not figure 3.32, which seems to suggest e.g. that the PEMS is missing out on 40% of CO emissions, which is clearly not the case. (BTW such a comparison would require a back-correction to compensate for the fraction of the exhaust being removed by the

[Below is a suggested rewrite of the discussion of figures 3.32 and 3.3 that reflects this] $\,$

Commented [VF8]: From this figure you cannot really see whether the PEMS is under or overestimating emissions.

As can be seen from [REF _Ref377050494 \h], the PEMS_shows fairly good overall correlation with the CVS for _s in general, slightly under predicts all emissions constituents measured on an instantaneous basis. However, CO₂ and NO_x show overall fairly good correlations between the two systems over all three bags of the FTP-75. For NO_x emissions, the PEMS fails to adequately capture the full magnitude of some of the emissions spikes during acceleration events (see, e.g., how the largest NO_x spike in figure 3.32 [Bag I] is larger for the CVS).₅ Hhowever, one has to keep the low concentrations in mind when interpreting the data, especially with 'Bag 2' and 'Bag 3' NO_x emissions being up to two orders of magnitude lower than for 'Bag I'. The latter is primarily due to the SCR system that becominges effective in reducing NO_x only after achieving a certain threshold temperature, while not being active during cold-start conditions.

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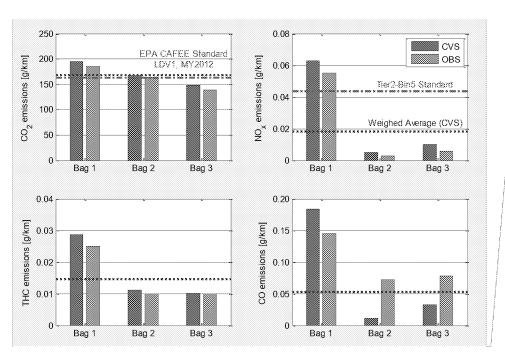


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of integrated emissions rates between CVS laboratory (CARB, El Monte, CA) and Horiba OBS-2200 PEMS for bags 1 through 3 of the FTP-75 standard chassis dynamometer test cycle. Note: red dotted lines represent the weighted emission rates as reported from the CVS laboratory; green dotted lines are US-EPA Tier2-Bin5 standards (@ full useful life)

Total hydrocarbons and CO both exhibit both we emissions rates, as is typical for diesel combustion engines, thus, regression analysis between the two measurement methods shows reduced correlation on an instantaneous basis. Especially CO emissions were observed to be near zero as measured by the CVS system once the after-treatment system was warmed up, while the PEMS captured occasional emissions spikes during acceleration events. The poor correlation for CO and THC may also be due to the comparably high response times of the portable CLD and FID analyzer cells.

Regardless of the instantaneous correlation of the signals (which may also be affected by the variable travel times of exhaust gas within the measurement setup before it reaches the analyzers at the diluted point), it is important to point out that the PEMS follows overall mass emissions with good accuracy for all pollutants. This is shown in [REF Ref385244060 \h], which depicts

Commented [VF9]: WeighTed Average

the distance-specific emissions in [g/km] of regulated emissions as measured by the PEMS and CVS system over the three bags of the FTP-75 chassis dynamometer test cycle. The integrated values for all three bags do correlate to within ~6% for CO₂, ~10% for NO_x, ~10% for THC and ~30% for CO. The dotted red lines indicate the weighted average emissions factors calculated from the CVS results, whereas the dotted green lines represent the US-EPA Tier 2-Bin 5 standards for NO_x, CO, and THC, and the LDV CAFE standard for CO₂, respectively (see [REF Ref385244060 \h]). A significant reduction in emissions factors for criteria pollutants can be noticed between 'Bag 1' versus 'Bag 2 & 3' which is attributed to the change in conversion efficiencies as the after-treatment system is being warmed up after the cold-start. It takes approximately 2 minutes to warm-up the after-treatment system as can be concluded from the drastic drop in emissions rates in [REF Ref377289209 \h]. NO_x, CO, and THC emissions are reduced by 92%, 61% and 94%, respectively, between 'Bag 1' (cold start) and 'Bag 2' (stabilized phase). [REF _Ref377299926 \h] lists the weighted emissions factors for the criteria pollutants and CO2 as calculated from CVS system and PEMS measurements along with the US-EPA Tier2-Bin 5 (at full useful life), and LDV CAFE standards. It can be noticed that weighted NO_x emissions are approximately 60% below the applicable standard. Note that although the CO difference between the CVS and PEMS is large, these measurements are two orders of magnitude lower than the Tier2-Bin5 regulatory limit.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Weighted emissions factors over FTP-75 test cycle measured by CVS system and PEMS vs. US-EPA Tier2-Bin5 standard (at full useful life); along with relative differences

Category	CO ₂ ¹	NO.	THC?	60
	[g/km]	[g/km]	[g/km]	[g/km]
Tier2-Bin5	-163	0.043	0.056	2.610
Weighted CVS	167.69	0.018	0.014	0.053
Weighted PEMS	161.59	0.015	0.013	0.089
Difference	[%]	[%]	[%]	[%]
Tier2-Bin5 vs. CVS	-2.6-	58.0	74.1	98.0
Tier2-Bin5 vs. PEMS	4.4-2	65.9	76.5	96.6
CVS vs. PEMS	3.6	18.8	9,4	-69.8

¹⁾ EPA/NHTSA corporate average fuel economy (CAFE) standard for LDV1 CO₂ is not regulated under Tier 2 standards (model year 2012)

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²⁾ NMOG standards taken for THC limit

Similarly, [REF_Ref385246197 \h] depicts the emissions factors for the criteria pollutants and CO₂ over the two bags of the NEDC, where 'Bag 1' refers to urban driving including cold-start during the first portion and 'Bag 2' to high-speed highway driving conditions during the second portion of the cycle. The significant reduction in NO_x, CO, and THC emissions of 65%, 99%, and 95% between 'Bag 1' and 'Bag 2' is attributed to the fully warmed up after-treatment system during the second portion of the test cycle, thus, leading to improved emissions conversion efficiencies.

Additionally, [REF _Ref385246197 \h] shows a 40% reduction in CO₂ emissions factor between urban and highway driving conditions that translates into an approximately 67% improvement in fuel economy from ~28mpg to ~48mpg, respectively.

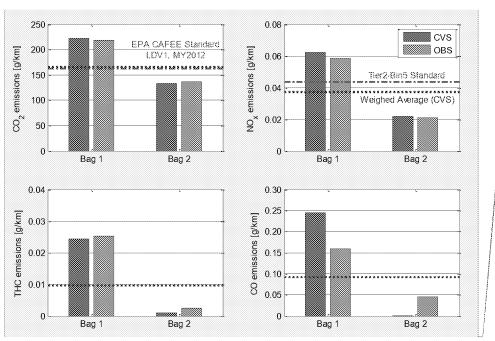


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of integrated emissions rates between CVS laboratory (CARB, El Monte, CA) and Horiba OBS-2200 PEMS over the NEDC standard chassis dynamometer test cycle

[REF _Ref377302614 \h] summarizes the emissions factors over the NEDC for both CVS system and PEMS along with the relative differences. As seen in this table, there is good

Commented [VF11]: WeighTed Average

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NOx figure has a typo

correlation between the CVS and PEMS unit for CO_2 and NO_x while a relatively large variation in THC and CO was observed. The relative error in the THC and CO emissions should be kept in perspective with the relatively low levels as compared to the regulatory emissions limits.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Emissions factors over NEDC as measured by CVS system and PEMS

Category	CO.	NO.	THC	co
	[g/km]	[g/km]	[g/km]	[g/km]
CVS 'Bag I'	222.28	0.063	0.024	0.246
CVS 'Bag 2'	133.09	0.022	0.001	0.001
PEMS 'Bag I'	218.42	0.059	0.025	0.159
PEMS 'Bag 2'	136.73	0.021	0.003	0.045
Total CVS	166.10	0.037	0.010	0.092
Total PEMS	166.96	0.035	0.011	0.087
Difference	[%]	[%]	[%]	[%]
CVS vs. PEMS 'Bag I'	1.7	6.1	-3.5	35.2
CVS vs. PEMS 'Bag 2'	-2.7	4.2	-151.6	-3688.8
CVS vs. PEMS 'Total'	-0.5	5.4	-13.1	5.0

3.4 Vehicle Test Matrix

The test matrix followed during this study is given in [REF_Ref368216064 \h]. Vehicle A was tested over routes 1 through 4, performing two repeats of each route. Vehicle B was tested over routes 1 through 5, and additionally over a total distance of ~3968 km between Los Angeles, CA and Seattle, WA. Testing of Vehicle C involved driving over routes 1 through 3 as well as route 5. Test routes that were repeated twice were driven with alternating drivers in order to make emissions results independent from a specific driver, hence, driving style. All test routes (i.e. Route 1 through 5) for all three vehicles were performed with the engine and aftertreatment system in warmed-up condition.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Vehicle test matrix

Route	Vehicle A	Vehicle B	Vehicle C
Route 1: highway	2	2	1
Route 2: urban (Los Angeles)	2	2	2
Route 3: rural - uphill/downhill	2	2	3
Route 4: urban (San Diego)	2	2	

Route 5: urban (San	
Cross-State Trip CA	

3.5 Data Analysis and Emissions Calculations

All data analysis and data quality assurance as well as emissions calculations presented herein are following recommendations outline in CFR, Title 40, Subpart 1065 D, G, and J [[REF Ref368330162 \r \h]] as well as WVU CAFEE internal and publicly available standard operating procedures (SOP). Drift correction for measured exhaust concentrations, emissions mass rates and distance or work-specific emissions factors are calculated according to CFR, Title 40, Subpart G [[REF Ref368330162 \r \h]], while moving averaging window method (AWM) calculations follow Annex B of the European draft on PEMS measurement for light-duty vehicles as well as guidelines prescribed in the European Regulations No. 582/2011 for in-use emissions from heavy-duty vehicles [[REF Ref382820874 \r \h]]. The integrated emissions results and averaging window emissions factors presented in this report are based on total emissions emitted over a given test route and are not corrected for any exclusion conditions such as exhaust temperature limits, altitude, DPF regeneration events or similar. Also, all averaging windows were considered for calculation and none were invalidated based on the 20% minimum power condition as outlined in the European Regulations No. 582/2011 [[REF Ref382820874 \r \h]]. Additional information about specific emissions calculating procedures applied to data presented in this report is given in Appendix [REF _Ref385265212 \r \h].

4 RESULTS AND DISCUSSION

The results chapter will discuss the average on-road emissions for the criteria pollutants and CO_2 from all three test vehicles in Section [REF _Ref377302874 \r \h] for the pre-defined test routes (see Section [REF _Ref377374861 \r \h]) as well as the cross-multi state driving route (see Section [REF _Ref377374876 \r \h]), followed by an in depth analysis of the NO_x emissions using the averaging window method in Section [REF _Ref377303022 \r \h]. Finally, individual results for particle number concentrations and PM mass will be presented and discussed in Section [REF _Ref377303113 \r \h] of this chapter.

This report is presenting gaseous emissions mass rates in [g/s] and emissions factors in [g/km], while particle number and mass concentrations are reported in [#/cm³] and [mg/m³], respectively, and particle number and mass emissions factors in [#/km] and [mg/km], respectively. Along with distance-specific emissions, dimensionless deviation ratios (DR) are reported for each emissions constituent as a measure of how much the actual on-road emissions are deviating from the regulatory limit. The calculation of deviation ratios is given by Equation 11 and follows the European regulation for emissions from heavy-duty vehicles [[REF_Ref382820874 \r \h]] and recommendations made by Weiss *et al.* [[REF_Ref377225805 \r \h * MERGEFORMAT]], where m_{x_i} and $[s(t_{end}) - s(t_{start})]_i$ are the emissions mass and distance traveled for a given averaging window or test route, respectively. $EF_{x \ stand}$ was selected to be the regulatory limit for the respective pollutant as given by [REF_Ref377378539 \h].

$$DR_i = \frac{m_{x_i}}{[s(t_{end}) - s(t_{start})]_i}$$
 Eq. 11

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Applicable regulatory emissions limits and other relevant vehicle emission reference values; US-EPA Tier2-Bin5 at intermediate useful life (5years/50,000 mi) for NO_x, CO, THC (eq. to NMOG), and PM [[REF _Ref377387706 \r \h]]; EPA advertised CO₂ values for each vehicle [[REF _Ref382820770 \r \h]]; Euro 5b/b+ for PN [[REF _Ref382821534 \r \h]]

NO ₃ [g/km]	CO [g/km]	THC [g/km]	CO ₂ [g/km]	PM [g/km]	PN [#/km]
			193 (Vehicle A)		
0.043	2.610	0.056	186 (Vehicle B)	0.006	$6.0 \mathrm{x} 10^{11}$
			288 (Vehicle C)		

4.1 Average On-Road Emissions of Light-Duty Vehicles

This chapter will present average on-road emissions factors for gaseous, including NO_x, CO, THC, and CO₂ as well as particle number and mass emissions as measured over pre-defined test routes for all three vehicles (see Section [REF _Ref377380777 \r \h * MERGEFORMAT]) and over the cross-multi state driving route for *Vehicle B* (see Section [REF _Ref377380791 \r \h * MERGEFORMAT]). Results presented in this chapter are reported as total emissions over the respective routes and are not corrected for any data exclusion conditions. All three test vehicles exhibited warmed-up engine and after-treatment conditions before being operated over a test route, thus, average emissions results presented in this chapter will be compared to '*Bag-3*' emissions levels as measured over the FTP-75 chassis dynamometer test cycle.

4.1.1 Emissions over Pre-Defined Test Routes

[REF _Ref385260634 \h] along with [REF _Ref385264236 \h] show average NO_x emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively, over the five pre-defined test routes for vehicles A through C. Additionally, [REF _Ref377381723 \h] summarizes the average values and standard deviation (1 σ) computed over two consecutive repetitions of a given test route. In general, NO_x emissions factors are highest for rural-up/downhill and lowest for high-speed highway driving conditions, respectively. All three test vehicles show distinct NO_x emissions patterns, with the LNT equipped *Vehicle A* exhibiting NO_x values 15 to 35, and the urea-SCR equipped *Vehicle B* NO_x values 5 to 20 times the Tier2-Bin5 standard depending on test route. *Vehicle C* was observed to emit NO_x emissions around or below the Tier2-Bin5 standard except during the rural-up/downhill route (Route 3), where emissions averaged 0.41 g/km or ~10 times the Tier2-Bin5 standard.

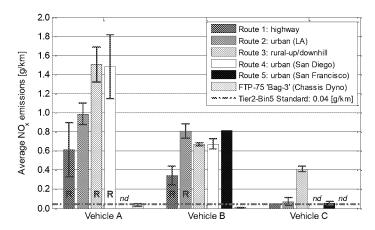


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average NO_x emissions of test vehicles over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; repeat test variation intervals are presented as ±1σ; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

Vehicle A and B are outfitted with the same engine model. Hhowever, they also feature different after-treatment systems allowing to conclude, based on the available data, that the LNT shows deficiencies over the urea-SCR system in efficiently reducing NO_x in-use, especially during highly transient, low-speed urban driving as well as high-load uphill driving. On the other hand, Vehicles B and C are both equipped with a similar after-treatment technology, namely urea-SCR₂₅ however, but show significantly different NO_x emissions factors for the same test routes. This could be caused by i) different after-treatment control strategies, ii) a difference in catalytic substrate between the two vehicles (different SCR type), iii) under-sized SCR catalyst for Vehicle B, or iv) different diesel exhaust fluid (DEF) injection strategy in case of Vehicle B to reduce DEF consumption, hence, increasing DEF re-filling intervals.

It has to be noted that all three vehicles were checked for possible engine or after-treatment malfunction codes using an ECU scanning tool prior to selecting each vehicle for this on-road measurement campaign, with none of them showing any fault code or other anomalies. The after-treatment system was assumed to be 'de-greened' as all three vehicles had we accumulated more than 3,000 to 4,000 miles, and no reduction in catalytic activity due to aging was expected as the total mileage was relatively low (< 15,000 miles) for all test vehicles.

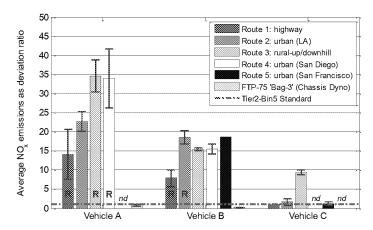


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average NO_x emissions of test vehicles over the five test routes expressed as deviation ratio; repeat test variation intervals are presented as $\pm 1\sigma$, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

Interestingly, NO_x emissions for *Vehicles A* and *B* were below the US-EPA Tier2-Bin5 standard for the weighted average over the FTP-75 during chassis dynamometer testing at CARB's El Monte facility. NO_x emissions were $0.022g/km \pm 0.006g/km (\pm 1\sigma, 2 \text{ repeats})$ and $0.016g/km \pm 0.002g/km (\pm 1\sigma, 3 \text{ repeats})$ for *Vehicle A* and *B*, respectively, during chassis dynamometer testing (i.e. weighted FTP-75 results). This is further confirmation that *Vehicles A* and *B* were operating as intended and did not have any malfunctions.

The LNT equipped *Vehicle A* shows increased variability between two consecutive test runs, especially for Routes 1, 3, and 4. This behavior coincides with DPF regeneration events (see [REF_Ref377465934 \h] through [REF_Ref377465938 \h]) that are occurring during one of the repeats for the above listed routes. NO_x emissions factors increase by 97% (0.41 g/km to 0.81g/km), 19% (1.38g/km to 1.63g/km), and 38% (1.24g/km to 1.72g/km) for Routes 1, 3, and 4, respectively, between test runs with and without DPF regeneration events. It has to be mentioned that the same test run exhibiting the DPF regeneration event for Route 1 also experienced increased stop-and-go traffic conditions during evening rush-hours, thereby confounding the factors leading to the 97% increase in NO_x compared to the test run without DPF regeneration event. Referring to reference [[REF_Ref377811821 \rangle r \h]] presenting a detailed discussion of DPF regeneration as well as LNT D_eNO_x and D_eSO_x regeneration strategies and control mechanisms, it can be noted (from Figure 12 in [[REF_Ref377811821 \rangle r]

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\h]]) that during an ongoing DPF regeneration event no cyclic D_eNO_x regeneration of the LNT occurs. As described by [[REF _Ref377811821 \r \h]], DPF regeneration happens under oxygen surplus conditions ($\lambda > 1$) and is on the order of up to 15min in duration. Therefore, it is speculated that due to a lack of frequent enrichment of the exhaust gas ($\lambda < 1$) while DPF regeneration is ongoing, necessary LNT regeneration is inhibited, and thus, the NO_x storage catalyst becomes saturated with NO_x emissions starting to break through. Indeed, increased NO_x mass rates were observed from continuous data coinciding with DPF regeneration events during Routes 1, 3, and 4.

Furthermore, when comparing THC emissions factors shown in [REF _Ref385260435 \h] with NO_x emissions factors in [REF _Ref385260634 \h] for *Vehicle A*, it can be noticed that highest THC emissions are exhibited during test routes with lowest NO_x emissions, specifically, for Routes 1 and 2. Increased THC values could point towards an increased frequency of rich mode operation, thus, leading to an improved NO_x reduction over the LNT catalyst. However, no conclusive explanation can be presented herein for why this behavior is observed, especially considering the vastly different driving conditions experienced between Routes 1 and 2, with Route 1 being representative of highway and Route 2 of urban driving. Additionally, Route 1 included a test run with a DPF regeneration event which normally leads to increased THC emissions, however, appears to have been masked by the order of magnitude increase in THC emissions (see [REF Ref385260435 \h]) caused by this unexplained event.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average NO_x emissions in [g/km] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle C
Donta le biobassa	ļī	0.614	0.344	0.048
Route 1: highway	σ	0.283	0.096	-
Day Sada diki	ĮΙ	0.989	0.809	0.070
Route 2: urban (LA)	σ	0.114	0.075	0.041
D 4 2 1 /3 1.31	μ	1.505	0.671	0.409
Route 3: rural-up/downhill	σ	0.181	0.016	0.029
D (S D)	μ	1.480	0.675	-
Route 4: urban (San Diego)	σ	0.335	0.057	-
D 5 1 (C F	μ	-	0.815	0.053
Route 5: urban (San Francisco)	σ	-	-	0.021

[REF _Ref385260539 \h] along with [REF _Ref385266351 \h] show average CO emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively, over the five pre-defined test routes for *Vehicles A* through C. Additionally, [REF _Ref377470219 \h] summarizes the average values and standard deviations (1 σ) computed over two consecutive repetitions of a given test route.

In general, CO emissions factors are close to two orders of magnitude lower than the applicable US-EPA Tier2-Bin5 standard for all three vehicles and no particular pattern in CO emissions rates can be found as a function of driving and/or route conditions. For *Vehicles A* and B_a highest CO emissions factors were exhibited during urban driving in Los Angeles (i.e. Route 2), whereas *Vehicle C* showed highest CO for rural-up/downhill driving (i.e. Route 3), which however, is accompanied by a significant variation (of same order than mean value) between repeated test runs. The increased variation in CO emissions factor for *Vehicle B* over Route 2 coincides with a regeneration event during one of the test runs leading to an order of magnitude increase in CO emissions from 0.02g/km to 0.26g/km.

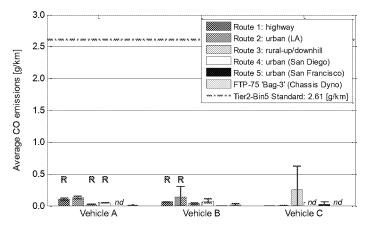


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO emissions of test vehicles over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; repeat test variation intervals are presented as ±1σ; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

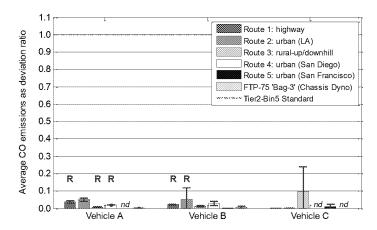


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO emissions of test vehicles over the five test routes expressed as deviation ratio; repeat test variation intervals are presented as ±10, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

[REF _Ref385260435 \h] along with [REF _Ref385268256 \h] show average THC emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively, over the five pre-defined test routes for *Vehicles A* through *C*. Additionally, [REF _Ref377471739 \h] summarizes the average values and standard deviations (1 σ) computed over two consecutive repetitions of a given test route.

Table [STYLEREF 1 \s].[SEQ Table * ARABIC \s 1]: Average CO emissions in [g/km] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route 1: highway	μ	0.100	0.059	0.000
Cource 1. Ingilway	σ	0.019	0.004	-
Route 2: urban (LA)	μ	0.130	0.138	0.004
	σ	0.021	0.169	0.005
Davita 3	ļī	0.018	0.029	0.256
Route 3: rural-up/downhill	σ	0.005	0.010	0.369
Boots & select (See Disco)	μ	0.048	0.076	-
Route 4: urban (San Diego)	σ	0.001	0.033	-
Donto Sandara (Con Francisco)	μ	-	0.007	0.027
Route 5: urban (San Francisco)	σ	-	-	0.038

It has to be noted that chassis dynamometer testing of *Vehicle A* and *B* indicated that 95 - 98% of the total hydrocarbons emitted were measured as methane (CH₄) which is somewhat

surprising for diesel fueled vehicles, however, could be attributed to reactions over the catalytic surface of the oxidation catalyst or the LNT in case of *Vehicle A*. The NMOG Tier2-Bin5 standard was chosen for comparison as it is currently the only applicable standard for hydrocarbons for Tier 2 light-duty vehicles in the US and since NMOG primarily comprises NMHC for diesel and gasoline fueled vehicles. However, in light of the large CH₄/THC ratio observed during chassis dynamometer testing, conclusions between the measured THC emissions during on-road operation and the NMOG standard have to be drawn with caution.

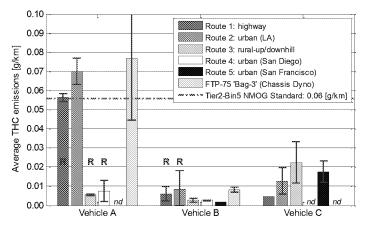


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Average THC emissions of test vehicles over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; repeat test variation intervals are presented as $\pm 1\sigma$; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, 'R' includes DPF regeneration events.

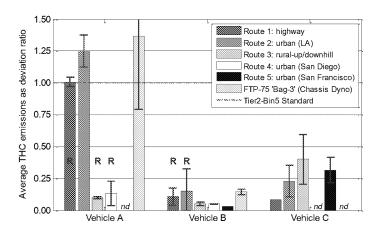


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average THC emissions of test vehicles over the five test routes expressed as deviation ratio; repeat test variation intervals are presented as $\pm 1\sigma$, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

In general, THC emissions factors are well below the US-EPA Tier2-Bin5 NMOG standard for *Vehicles B* and *C* as well as over Routes 3 and 4 for *Vehicle A*. Only for *Vehicle A* and Routes 1 and 2, THC emissions were observed at (i.e. Route 1, highway) or exceeding (i.e. Route 2, urban Los Angeles, by 1.25) the NMOG standard. However, this has already been discussed in more detail along with the average NO_x results above. *Vehicle A* and *B* showed a tendency for increased THC emissions during test runs with DPF regeneration events compared to tests without such events, however, the same has not been observed for *Vehicle C*.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average THC emissions in [g/km] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle C
Route 1: highway	μ	0.056	0.006	0.005
Rothe 1. lighway	σ	0.002	0.004	•
Dart 2 also dist	μ	0.070	0.009	0.013
Route 2: urban (LA)	σ	0.007	0.010	0.007
David 2	μ	0.005	0.003	0.022
Route 3: rural-up/downhill	σ	0.000	0.001	0.011
D / . J /C D)	μ	0.007	0.003	-
Route 4: urban (San Diego)	σ	0.005	0.000	-
Route 5: urban (San Francisco)	и	-	0.002	0.018

σ - - 0.006

[REF _Ref385261019 \h] along with [REF _Ref385268348 \h] show average CO_2 emissions factors and their respective deviation ratio from EPA advertised CO_2 values for each vehicle, respectively, over the five pre-defined test routes for vehicles A through C. Additionally, [REF _Ref377471705 \h] summarizes the average values and standard deviations ($l\sigma$) computed over two consecutive repetitions of a given test route. In general, and as expected, highway driving showed lowest CO_2 , whereas urban/suburban driving conditions lead to highest CO_2 emissions factors.

Since both *Vehicle A* and *B* were equipped with the same engine their CO_2 consumption pattern appear similar in [REF _Ref385261019 \h]. Routes 1 and 2 are characterized by higher average vehicle speeds and reduced amount of stop/go conditions (especially for highway Route 1) which translates into lower vehicle acceleration events and thus, lower CO_2 emissions ultimately leading to improved fuel economy over these routes as shown in [REF _Ref385271012 \h].

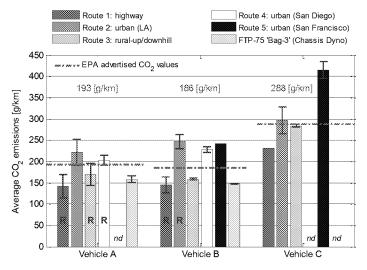


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO₂ emissions of test vehicles over the five test routes compared to EPA advertised CO₂ values for each vehicle; repeat test variation intervals are presented as ±10; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

On the other hand, urban driving conditions lead to increased fuel consumption, hence, more CO₂ emissions as seen for urban routes 2, 4, and 5. Differences between CO₂ emissions factors for *Vehicle A* and *B* could be attributed to varying traffic patterns over a given route, influences of ambient conditions as both vehicles were tested on a different day (however, within the span of two weeks during March), and most importantly variations in driving style as the experiments have been conducted with three different drivers.

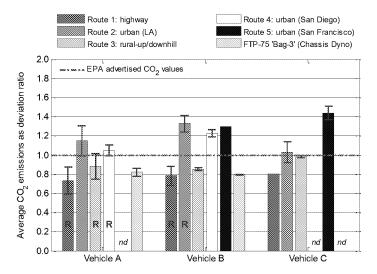


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO_2 emissions of test vehicles over the five test routes expressed as deviation ratio from the EPA advertised CO_2 values; repeat test variation intervals presented as $\pm 1\sigma$, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average CO_2 emissions in [g/km] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle C
Route 1: highway	μ σ	141.9 27.0	145.6 18.8	231.8
Route 2: urban (LA)	μ σ	221.7 30.1	246.9 16.2	296.3 32.1
Route 3: rural-up/downhill	μ σ	169.8 25.6	158.6 2.5	283.6 3.6
Route 4: urban (San Diego)	μ σ	202.3 11.5	228.2 6.8	-

Highway driving (i.e. Route 1) for *Vehicle A* includes non-rush-hour as well as evening rush-hour conditions causing the variability in CO_2 emissions factor seen in [REF_Ref385261019 \h]. During rush-hour conditions, CO_2 emissions increased by ~31% from 123g/km to 161g/km. Furthermore, based on data for *Vehicles A* and *B*, it is observed that CO_2 emissions are generally increased during test runs with DPF regeneration events which could be explained by the oxidation of carbon from the DPF substrate as well additional fuel injected to augment exhaust gas and after-treatment temperatures in order to initiate and sustain DPF regeneration.

Overall, CO₂ emissions from *Vehicles A* and *B* compare well with CO₂ emissions observed during chassis dynamometer testing over the NEDC which consists of a dedicated urban/suburban (i.e. 'Bag 1') and highway (i.e. 'Bag 2') driving portion. The urban/suburban driving portion of the NEDC exhibited 212.3g/km \pm 11.2g/km (\pm 1 σ , 3 tests of which are 2 with *Vehicle A* and 1 with *Vehicle B*), whereas the highway driving resulted in 148.0g/km \pm 12.9g/km (\pm 1 σ , same sample set) of CO₂ on the chassis dynamometer.

Finally, increased variability was observed over the two urban routes in Los Angeles and San Francisco (i.e. Routes 2 and 5) for *Vehicle C*, which can be attributed to differences in driving style between the two drivers, as well as changing traffic patterns between repeated test runs. Furthermore, the topographical differences between Routes 2 and 5 (flat vs. hilly) seem to influence the CO₂ emissions factor to a higher degree for *Vehicle C* as compared to *Vehicle B*. This could be caused by the heavier overall weight of *Vehicle C*, which was ~54% heavier than *Vehicle B*, as well as the larger engine (~52% larger displacement for *Vehicle C*), leading to more aggressive accelerations, especially under the hilly and often larger road grade conditions as experienced over Route 5 (i.e. San Francisco).

[REF _Ref385262873 \h] along with [REF _Ref385268742 \h] show average particulate mass (PM) emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively, over the five pre-defined test routes for *Vehicles A* and *B*. Additionally, [REF _Ref377471709 \h] summarizes the average values and standard deviations (1σ) computed

over two consecutive repetitions of a given test route. It has to be noted that particulate masses reported in [REF _Ref385262873 \h] and [REF _Ref385268742 \h] are not directly measured masses via traditional filter samples, but rather inferred from a charge based real-time particle sensor as described in more detail in Section [REF _Ref368226934 \r \h].

In general, particulate mass emissions were observed to be well below the applicable US-EPA Tier2-Bin5 standard over all test routes for *Vehicles A* and *B* with the exception of Route 3 for *Vehicle A* which exhibited a DPF regeneration event during one of the test runs. Average PM emissions increased by two orders of magnitude from 0.01mg/km to 5.7mg/km between the test run with and without DPF regeneration for Route 3.

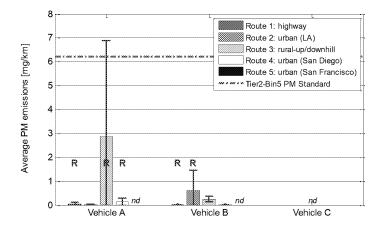


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PM emissions of test vehicles over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; repeat test variation intervals are presented as $\pm 1\sigma$; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, no PM data collected for Vehicle C, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

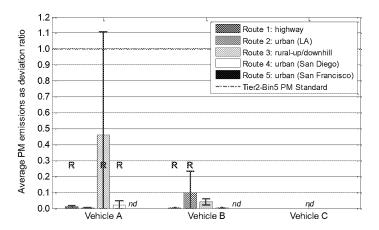


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PM emissions of test vehicles over the five test routes expressed as deviation ratio; uncertainty repeat test variation are presented as ±1σ; Route 1 for Vehicle A includes rush-hour/non rush-hour driving, no PM data collected for Vehicle C, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average PM emissions in [mg/km] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle C
Doorte L. Linksons	μ	0.051	0.007	-
Route 1: highway	σ	0.058	0.001	-
D - 2 1 (14)	μ	0.015	0.613	-
Route 2: urban (LA)	σ	0.012	0.839	-
n /1 1/11	μ	2.858	0.250	-
Route 3: rural-up/downhill	σ	4.023	0.117	-
n	μ	0.137	0.005	-
Route 4: urban (San Diego)	σ	0.160	0.001	-
D	μ	-	-	-
Route 5: urban (San Francisco)	σ	-	-	-

[REF _Ref385262237 \h] along with [REF _Ref385269046 \h] show average particulate number (PN) emissions factors and their respective deviation ratio from the European Euro 5b/b+ standard (i.e. $6x10^{11}$ #/km), respectively, over the five pre-defined test routes for *Vehicles A* and *B*. Additionally, [REF _Ref377482569 \h] summarizes the average along with minimum and maximum values computed over two consecutive repetitions of a given test route. Similarly

to PM emissions, particulate numbers presented herein are inferred from a charge based real-time particle sensor as described in more detail in Chapter [REF Ref368226934 \r \h].

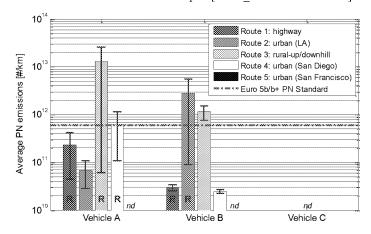


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PN emissions of test vehicles over the five test routes compared to Euro 5b/b+ emissions standard; repeat test variation intervals are presented as minimum/maximum test value; Route 1, Vehicle A includes rush-hour/non rush-hour driving, no PM data collected for Vehicle C, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

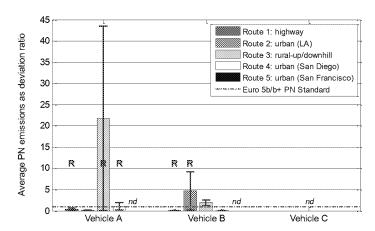


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PN emissions of test vehicles over the five test routes expressed as deviation ratio; repeat test variation intervals are presented as minimum/maximum test value, no PM data collected for Vehicle C, 'R' designates routes including a test with DPF regeneration event, 'nd' - no data available

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average, minimum, and maximum PN emissions in [#/km] of test vehicles over the five test routes; Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle (
	μ	2.32E+11	2.98E+10	-
Route 1: highway	Min	4.43E+10	2.54E+10	-
	Max	4.20E+11	3.41E+10	-
	μ	6.85E+10	2.80E+12	-
Route 2: urban (LA)	Min	2.88E+10	9.05E+10	-
	Max	1.08E+11	5.51E+12	-
	μ	1.31E+13	1.14E+12	-
Route 3: rural-up/downhill	Min	6.24E+10	7.65E+11	-
	Max	2.61E+13	1.52E+12	-
	μ	6.28E+11	2.48E+10	-
Route 4: urban (San Diego)	Min	1.09E+11	2.25E+10	-
	Max	1.15E+12	2.70E+10	-
	μ	-	-	-
Route 5: urban (San Francisco)	Min	-	-	-
	Max	-	-	-

The European Euro 5b/b+ standard has been chosen for comparison as it is currently the only particulate number standard in legislation, and applicable to new vehicles sold within the confines of the European Union [[REF_Ref382821534 \r \h]].

Increased variation in average particulate number emissions was observed for test routes that included DPF regeneration events during one of the route repetitions. DPF regeneration events lead to a one or two order of magnitude increase in PN emissions factors when compared to test runs without DPF regeneration as seen for Routes 1, 3, and 4 as well as Routes 2, and 3 for *Vehicle A* and *B*, respectively. Route 3 for *Vehicle B* exhibited DPF regeneration events during both repeats (see [REF _Ref377484439 \h]) thus, leading to the observed low variability between tests.

In general, average PN emissions factors remain an order of magnitude below the applicable Euro 5b/b+ standard for all routes/tests that did not include DPF regeneration events. However, for routes/tests with DPF regeneration particle number emissions increase rapidly and exceed the Euro 5b/b+ standard in most cases (i.e. Route 3, 4 for *Vehicle A*; Route 2, 3 for *Vehicle B*).

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[REF _Ref385271012 \h] a) and b) present average fuel economy values in units [km/L] and [mpg], respectively, over the five pre-defined test routes for vehicles A through C. Additionally, [REF _Ref377485090 \h] summarizes the average values and standard deviations (1σ) computed over two consecutive repetitions of a given test route.

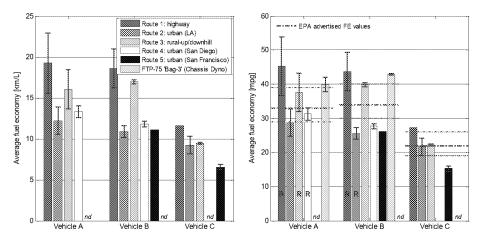


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average fuel economy of test vehicles over the five test routes in km/L and mpg; repeat test variation intervals are presented as ±10;

Route 1 for Vehicle A includes rush-hour/non rush-hour driving

As fuel economy values are derived via carbon balance with CO₂ emissions being the dominant fraction, they essential become a mirror of CO₂ emissions fractions. Therefore, any observations discussed earlier for CO₂ emissions are valid as well for fuel economy results, hence, in general, and as expected, highway driving showed increased fuel economy over urban/suburban driving conditions.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Average fuel economy in [mpg] of test vehicles over the five test routes; σ is standard deviation over two consecutive test runs, Route 1 for Vehicle A includes rush-hour/non rush-hour

Route		Vehicle A	Vehicle B	Vehicle C
Route 1: highway	μ σ	45.3 8.6	43.7 5.7	27.3 -
Route 2: urban (LA)	μ σ	28.7 3.9	25.6 <i>1.7</i>	21.7 2.6
Route 3: rural-up/downhill	μ σ	37.6 5.7	39.9 0.6	22.3 0.3

u 313	27.7
Route 4: urban (San Diego)	# / · /
Route 4, divan (San Diego)	0.8
0 10	V.O -
	262 153
Route 5: urban (San Francisco)	40.4 15.3
Route 3. titoan (San Francisco)	0.0
a -	

Average fuel economy for highway driving with *Vehicles A* and *B* was 45.3 mpg \pm 8.6mpg (\pm σ 1) and 43.7mpg \pm 5.7mpg (\pm σ 1), respectively, and 27.3 mpg (no repetition) for *Vehicle C* which is ~39% lower compared to *Vehicles A* and *B*. On the other hand, urban/suburban driving results in average fuel economies of 30.0mpg \pm 2.9mpg (\pm σ 1) and 26.6 mpg \pm 1.4mpg (\pm σ 1) for *Vehicles A* and *B*, respectively, and 18.5mpg \pm 4.0mpg (\pm σ 1) for *Vehicle C* which is 35% lower compared to *Vehicles A* and *B*. Overall, urban/suburban driving leads to a 32-39% reduction in fuel economy over highway driving.

[REF _Ref377487043 \h] depicts average engine work values and standard deviations (1 σ) in units [kWh] over the five pre-defined test routes for vehicles A through C. The average engine work presented herein is inferred from estimated real-time engine power calculated according to Equation 12, and based on an assumed calorific value for the test fuel and combustion efficiency as well as the real-time fuel consumption derived from a carbon balance using the measured exhaust constituents as input parameter. The calorific value for the diesel fuel was selected as 43,500kJ/kg and the combustion efficiency as 0.35. It can be noticed form [REF _Ref377487043 \h] that the engine of *Vehicle C* produces more work as compared to *Vehicles A* and *B* which can be explained by the overall heavier vehicle and larger engine for *Vehicle C*.

$$\dot{P}(t) = Calori_{fuel} \cdot F\dot{u}el_{CB}(t) \cdot \eta_{comb} \cdot \frac{1}{1000}$$
 Eq. 12

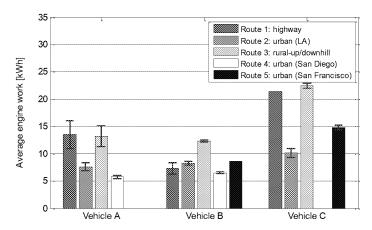


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average engine work of test vehicles over the five test routes, calculated from carbon balance and combustion efficiency; repeat test variation intervals are presented as ±1σ; Route 1 for Vehicle A includes rush-hour/non rush-hour driving

4.1.2 Emissions over Cross-Multi-State Driving Route

This section will report averaged emissions factors for gaseous and particulate matter emissions from *Vehicle B* over the cross-multi state driving route. Each figure in this section will present averaged emissions factors for route portions between Los Angeles and Seattle that comprise predominantly highway driving with the addition of two routes representative of urban/suburban driving in Seattle, WA and Sacramento, CA. Additionally, average values and standard deviations (1σ) computed separately for highway and urban/suburban portions of the route as well as the grand average over the entire cross-multi state driving route are included to the right of each individual graph.

[REF _Ref377492996 \h] along with [REF _Ref377493001 \h] show average NO_x emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively. Over the entire route_x NO_x emissions factors were on average 0.26g/km ± 0.21 g/km ($\pm 1\sigma$) or approx. 6 times exceeding the US-EPA Tier2-Bin5 standard. NO_x emissions factors for urban/suburban driving portions were observed at twice the level of highway-only route portions with 0.52g/km ± 0.27 g/km versus 0.24g/km ± 0.19 g/km NO_x, respectively. For highway driving average_x NO_x emissions factors were close to NO_x emissions observed during Route 1 (i.e. highway) driving (i.e. 0.344g/km ± 0.096 g/km), considering the large variation in NO_x emissions

over the highway portions of the cross-multi state route. Urban driving in Seattle (i.e. Route 6) exhibits NO_x emissions factors at a similar level as seen for the pre-defined urban Routes 2, 4 and 5 shown in [REF _Ref385260634 \h]. On the other hand, urban/highway driving in Sacramento (i.e. Route 7) shows greatly reduced NO_x emissions compared to other urban routes, which is primarily due to the large share of highway driving contained in this route segment (> 60% by distance), thus, causing the large variability seen for total urban/suburban average NO_x emissions factor.

However, more interestingly is the large variation in NO_x emissions factors over highway driving and in particular portions of the route where NO_x emissions were observed below the US-EPA Tier2-Bin5 standard. In order to provide a possible explanation, [REF _Ref377492996 \h] needs to be interpreted in light of the vehicle speed and altitude graphs for the cross-multi state driving route shown in [REF _Ref377232580 \h] a) and b), respectively. Increased NO_x emissions during route portions 1 and 2 as well as 8 through 11 (see [REF _Ref377492996 \h]) coincide with up/downhill driving conditions while crossing mountain ranges near Los Angeles and in Northern California/Southern Oregon, respectively, with elevation changes of up to 1200 meters. On the other hand, NO_x emissions at or below the US-EPA Tier2-Bin5 standard (see route portions 3 through 6 in [REF _Ref377492996 \h]) were observed while traveling northbound on Interstate 5 through the San Joaquin Valley characterized by low or negligible changes in altitude (i.e. near zero road grade), and with the vehicle operated in cruise-control mode at approximately 120km/h.

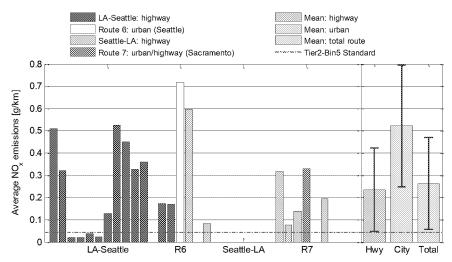


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average NO_x emissions of test vehicle over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard; repeat test variations are presented as $\pm 1\sigma$

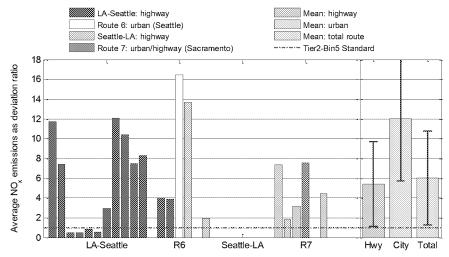


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average NO_x emissions of test vehicle over cross-multi-state driving route portions expressed as deviation ratio; repeat test variations are presented as $\pm 1\sigma$

[REF _Ref377499372 \h] along with [REF _Ref377499377 \h] show average CO emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard,

respectively. In general, and as expected, CO emissions were observed at two orders of magnitude below the applicable standard and no specific pattern could be identified from the results.

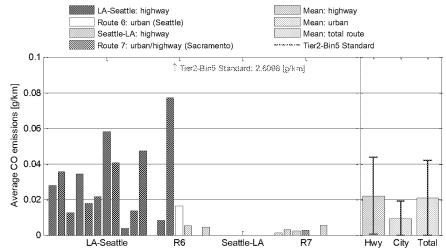


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO emissions of test vehicle over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard; repeat test variations are presented as $\pm 1\sigma$

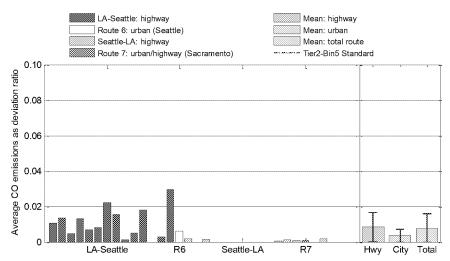


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO emissions of test vehicle over cross-multi-state driving route portions expressed as deviation ratio; repeat test variations are presented as $\pm 1\sigma$

Similarly, [REF _Ref377499676 \h] along with [REF _Ref377499679 \h] show average THC emissions factors and their respective deviation ratio from the US-EPA Tier2-Bin5 standard, respectively, which were well below the applicable emissions standard.

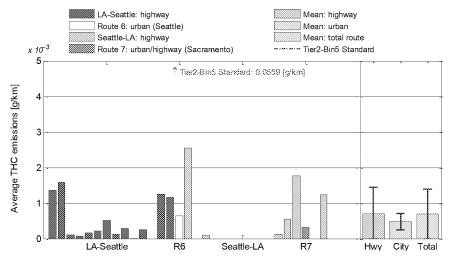


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average THC emissions of test vehicle over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard; repeat test variations are presented as $\pm 1\sigma$

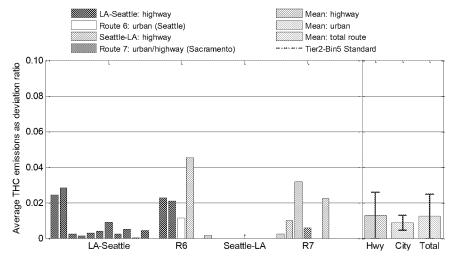


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Average THC emissions of test vehicle over cross-multi-state driving route portions expressed as deviation ratio; repeat test variations are presented as $\pm 1\sigma$

[REF _Ref377638344 \h] along with [REF _Ref377638349 \h] show average CO_2 emissions factors and their respective deviation ratio from the EPA/NHTSA— CO_2 /CAFE

standardEPA advertised CO2 value for Vehicle B for LDV/PC's (i.e. 186 63g/km), respectively, over the individual sub-portions of the cross-multi state driving route.

As already has been observed for the pre-defined test routes (see [REF_Ref385261019 \h]) CO₂ emissions are in general lowest for highway driving, whereas urban/suburban driving conditions lead to increased CO₂ emissions factors (155g/km ±14.4g/km vs. 178g/km ±19.9g/km). It has to be noted again that the second urban route presented in [REF_Ref377638344 \h] (i.e. Route 7) includes a proportionally large amount of highway driving and, thus, skews the CO₂ emissions factor for this route towards a lower value as was typically experienced for *Vehicle B* over urban driving conditions (e.g. see Route 2, 4, 5, and 6). On average, CO₂ emissions are 5% below the EPA/NHTSA CO₂/CAFE standard for LDV/PC's during highway operation. Increased CO₂ emissions as observed for route portions 7 and 8 coincide with larger elevation changes and therefore steeper road grades as can be seen from [REF_Ref377232580 \h] thus, resulting in increased engine load demand and thereby emitting more CO₂ on a distance-specific basis.

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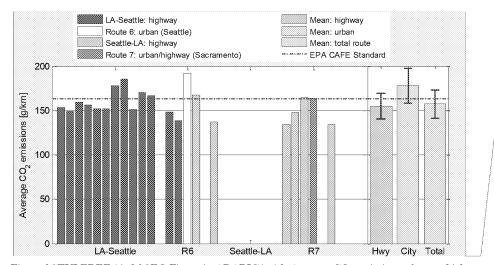


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO₂ emissions of test vehicle over cross-multi-state driving route portions compared to 2012 EPA/NHTSA fleet-wide average CO₂ emissions standard (passenger car); repeat test variations are presented as ±1σ

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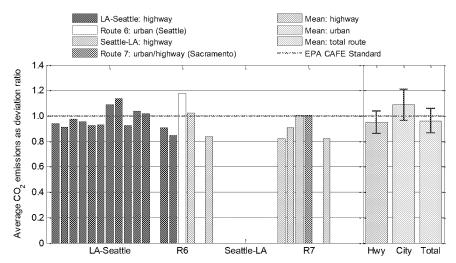


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average CO_2 emissions of test vehicle over cross-multi-state driving route portions expressed as deviation ratio; repeat test variations are presented as $\pm 1\sigma$

[REF _Ref377641796 \h] shows average particulate matter mass emissions factors whereas [REF _Ref377642068 \h] presents average particulate matter number emissions factors along with the respective regulatory standards, specifically, US-EPA Tier2-Bin5 for PM and Euro 5b/b+ for PN. It has to be noted again that both PM and PN emissions are inferred from real-time particle charge measurements using the Pegasor particle sensor.

In general, PM emissions are on the order of $0.01 \text{mg/km} \pm 0.005 \text{mg/km}$ ($\pm 1\sigma$), thereby nearly 100% (99.89%) below the US-EPA Tier2-Bin5 standard. From [REF _Ref377641796 \h] three portions of the cross-multi state driving route, namely, portions 2, 7, and 13 stand out showing distinctly different PM emissions levels as compared to all other route portions. This is due to DPF regeneration events occurring during these three route portions leading to a nearly 700 fold increase in PM emissions to $4.55 \text{mg/km} \pm 0.003 \text{mg/km}$ ($\pm 1\sigma$). However, even during DPF regeneration events PM emissions levels remain ~27% below the regulatory standard of 6.2 mg/km (i.e. US-EPA Tier2-Bin5), owing to the diesel particulate filters ability to retain particulate matter mass emissions with high efficiency from the exhaust gas stream.

[REF _Ref377642068 \h] shows a similar picture for particulate number emissions factors with PN levels typically on the order of 3.01×10^{10} #/km (min: 2.03×10^{9} #/km /max:

9.12x10¹⁰#/km) during both highway and urban/suburban driving conditions. However, during DPF regeneration events as observed during route portions 2, 7, and 13 PN emissions factors increase by 2 to 3 orders of magnitude to 2.08×10^{13} #/km $\pm 1.36 \times 10^{10}$ #/km ($\pm 1\sigma$, including only PN for portions 7 and 13), thereby, exceeding the Euro 5b/b+ PN standard by more than an order of magnitude (factor 35).

Previous studies [[REF _Ref377669768 \r \h] and [REF _Ref377669770 \r \h]] have shown that particle number concentrations downstream the PM trap can momentarily increase during, and within a limited time period after, experiencing a regeneration event. During regeneration of a wall-flow type DPF the 'cake-layer,' as referred to the soot layer deposited on top of the filter substrate and responsible for the high particle retention efficiency of wall-flow type DPF's (>99%), is partially oxidized, thus, momentarily reducing the filtration efficiency of the DPF [[REF _Ref377669768 \r \h]]. Within a usually short, but ultimately depending on engine load, period after the regeneration event the 'cake-layer' will be built up again and the DPF will resume its maximum filtration efficiency.

A more detailed discussion of DPF regeneration events and the frequency of their occurrence as observed for *Vehicle B* is presented in Section [REF Ref377670012 \r \h].

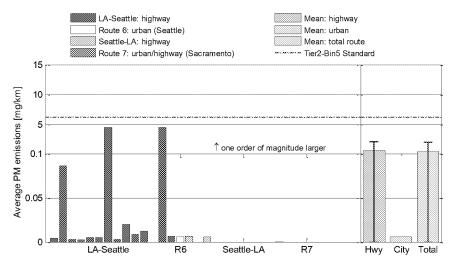


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PM emissions of test vehicle over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard; repeat test variations are presented as $\pm 1\sigma$

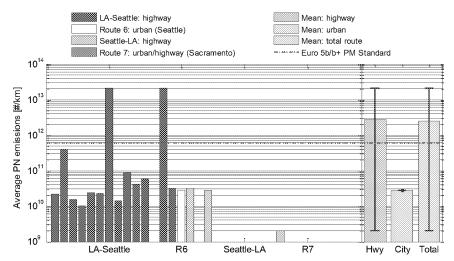


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average PN emissions of test vehicle over cross-multi-state driving route portions compared to Euro 5b/b+ emissions standard; repeat test variations are presented as minimum/maximum test value, total city emissions are only based on Route 6 (R6)

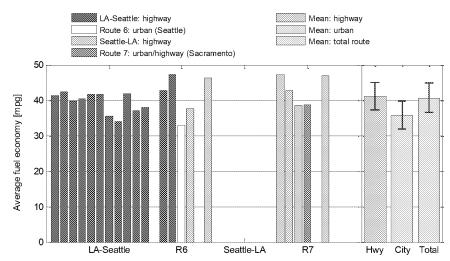


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Average fuel economy of test vehicle over cross-multi-state driving route portions expressed as mpg; repeat test variations are presented as $\pm 1\sigma$

Finally, [REF_Ref377669850 \h] shows average fuel economy values in units of [mpg] for the entire cross-multi state driving route. On average, fuel economy was 41.2mpg ±3.9mpg (±1σ) during highway driving conditions, spanning from 33.98mpg to 47.2mpg during route portions 8 and 26, respectively. Lowest fuel economy coincides with uphill driving, whereas highest fuel economy values were observed during downhill slopes while crossing the mountain ranges in Northern California/Southern Oregon (see [REF_Ref377232580 \h] for altitude reference). Furthermore, urban/suburban driving (i.e. Route 6) has been shown to result in ~20% reduced fuel economy over highway driving.

4.2 On-Road NO_x Emissions

This chapter will present NO_x emissions calculated based on the averaging window method over pre-defined test routes for all three vehicles (see Section [REF _Ref377671154 \r \h]) and over the cross-multi state driving route for *Vehicle B* (see Section [REF _Ref377671162 \r \h]).

The averaging windows were calculated following recommendations outlined in the European regulation [[REF _Ref382820874 \r \h]] with the total mass of CO_2 in [g], emitted

over a given vehicle certification chassis dynamometer cycle chosen as the reference criterion to determine window size. Two reference cycles were chosen, namely, FTP-75 and NEDC as actual CO₂ emissions data was available for both these cycles from *Vehicle A* and *B*, collected during chassis dynamometer testing at CARB's El Monte facility. [REF _Ref377672521 \h] lists the respective CO₂ mass emissions emitted over the reference cycles. No actual CO₂ emissions data were available for *Vehicle C*, therefore, CO₂ values were instead taken from EPA certification documents for the FTP-75 cycle.

Additionally, averaging window based NO_x emissions will be presented as deviation ratios from the US-EPA Tier2-Bin5 standard for NO_x (i.e. 0.043g/km) as described by Equation 11.

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Window size criterion for AWM; total CO₂ mass over FTP-75 and NEDC (evaluated at CARB El Monte chassis dynamometer laboratory for Vehicle A and B; taken from EPA certification document for Vehicle C)

Vehicle	O: over FTP-75	CO ₂ over NEDC
	[g]	[8]
Vehicle A	2921.9	1938.6
Vehicle B	2944.8	1841.8
Vehicle C	5042.5	5042.5 1)

¹⁾ CO₂ mass value for FTP-75 according to EPA certification documents from

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http://www.epa.gov/otaq/crttst.htm

4.2.1 NO_x Emissions over Pre-Defined Test Routes

Cumulative frequency plots for averaging window NO_x emissions in [g/km] and deviation ratios from the regulatory standard are presented for *Vehicle A* in [REF _Ref377674181 \h] along with [REF _Ref377674182 \h], for *Vehicle B* in [REF _Ref377674373 \h] along with [REF _Ref377674374 \h], and finally for *Vehicle C* in [REF _Ref376978669 \h] along with [REF _Ref377052760 \h], respectively. Total CO₂ emitted over the NEDC was chosen as reference value for calculating AWM-NO_x emissions results presented in the above mentioned figures. Overall, the LNT equipped *Vehicle A* shows the highest, while the urea-SCR after-treatment based *Vehicle C* the lowest NO_x emissions.

In general, highway driving (i.e. Route 1) shows lowest NO_x emissions whereas rural-up/downhill driving conditions (i.e. Route 3) contribute to the largest amounts of NO_x observed. For *Vehicles A* and *B*, about 30-40% of the NO_x emissions emitted during Route 3 are below levels observed for urban driving and close to what was seen for highway conditions. Contrarily,

Vehicle C emitted significantly more NO_x during the rural-up/downhill route as compared to any of the other urban or highway routes (see [REF _Ref376978669 \h]), with about 50% of the emissions released exceeding ~10 times the UA-EPA Tier2-Bin5 standard. This agrees well with route average NO_x emissions presented earlier in [REF _Ref385260634 \h] and [REF _Ref385264236 \h]. However, when comparing results for Route 3 between Vehicles C and B (see [REF _Ref376978669 \h] vs. [REF _Ref377674373 \h]), close similarities in shape and magnitude can be noticed for the cumulative frequencies. The large increase in NO_x emissions observed during the rural-up/downhill driving over other test routes could be attributed to the fact that the emissions presented herein are normalized for distance traveled rather total work produced by the engine. This impacts results from heavier vehicles (Vehicle C was ~54% heavier than Vehicles A and B) with larger and more powerful engines while operating over routes comprising increased altitude changes since proportionally more work needs to be done by the engine to move the vehicle uphill over a finite increment of distance.

The impact of DPF regenerations onto NO_x emissions is especially pronounced for Vehicle A, visible as significant differences in cumulative frequency graphs between repetitions of routes with and without regeneration event (i.e. Route 1, 3, and 4). It has to be noted that this observation might be confounded for Route 1 as the test exhibiting the DPF regeneration event was also experiencing heavy evening rush-hour traffic conditions, thereby additionally affecting NO_x emissions. However, owing the increased difference between both test runs for Route 1, as compared to the differences seen between test runs for Route 3 and 4, it could be justified as a combined effect of DPF regeneration and increased stop-go conditions due to rush-hour traffic. REF Ref377821633 \h] shows a direct comparison of continuous averaging window NO_x emission over Route 3 between two repeats, one with (i.e. Test 1) an the other without (i.e. Test 2) DPF regeneration event. The location of the regeneration event can be identified from the PN concentration and exhaust gas temperature (measured at the exhaust tailpipe outlet) graphs in the lower part of [REF Ref377821633 \h], with the duration of the event observed to be on the order of 14min and thereby in agreement with [[REF Ref377811821 \r \h]]. During regeneration events averaging window NO_x emissions are found to nearly double from ~3g/km to ~5.5g/km for Route 3 for example (see [REF Ref377821633 \h]). Similar behavior was observed for Routes 1 and 4 for Vehicle A between tests with and without DPF regeneration. A possible explanation for the observed increase in NO_x emissions during DPF regeneration events for the LNT equipped *Vehicle A* was given earlier in Section [REF _Ref377374861 \r \h]. This distinct impact of DPF regenerations onto NO_x emissions was not observed for the other test vehicles.

In general for *Vehicle A*, 50% of NO_x emissions over all test routes were exceeding the US-EPA Tier2-Bin5 standard by a factor of 20 to 40 as seen from [REF _Ref377674182 \h], with none of the routes exhibiting NO_x emissions at levels below the regulatory standard. On the other hand, for *Vehicle B* 50% of the NO_x emissions were observed to exceed the US-EPA Tier2-Bin5 standard by 5 to 20 times for the majority of the test routes. One repeat of Route 1 exhibited lower NO_x emissions with 5% of total accumulated averaging window NO_x observed to fall below the standard.

Finally, as seen from [REF _Ref376978669 \h] and [REF _Ref377052760 \h] *Vehicle C* presents a vastly different averaging window NO_x emissions pattern compared to *Vehicles A* and *B*, with the majority of the highway and urban/suburban driving routes exhibiting 80 to 90% of NO_x emissions below the US-EPA Tier2-Bin5 standard. [REF _Ref377824324 \h] and [REF _Ref377824326 \h] provide a zoomed in view of the x-axis for [REF _Ref376978669 \h] and [REF _Ref377052760 \h], respectively. A significant variability in magnitude of NO_x emissions between repetitions of the urban routes (i.e. Routes 2 and 5) can be noticed from [REF _Ref377824324 \h]. Possible explanations for the observed test-to-test variability include changing traffic patterns and driving style as test drivers were changed between repeats of a given test route. Indeed, one of the tests for Route 5 was ~16min shorter and encountered more aggressive vehicle accelerations, possibly partially causing the observed increase in NO_x emissions.

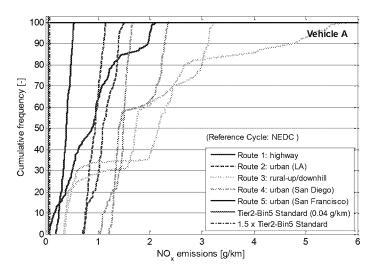


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle A over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; AWM reference metric is CO₂ emissions over NEDC; Route 1 includes rush-hour/non rush-hour driving

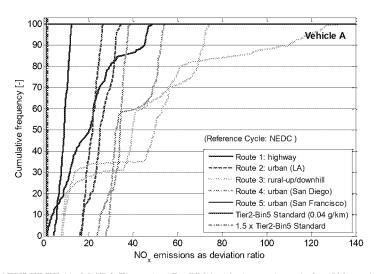


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle A over the five test routes expressed as deviation ratio; AWM reference metric is CO₂ emissions over NEDC; Route 1 includes rush-hour/non rush-hour driving

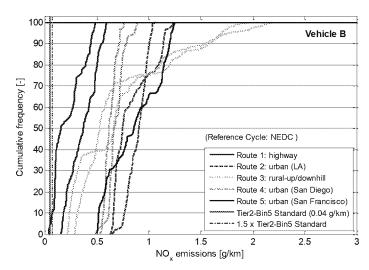


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle B over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; AWM reference metric is CO_2 emissions over NEDC

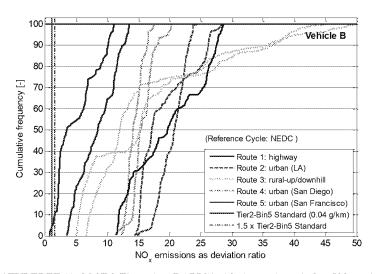


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle B over the five test routes expressed as deviation ratio; AWM reference metric is CO₂ emissions over NEDC

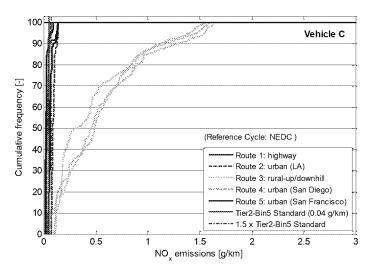


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO $_x$ emissions for Vehicle C over the five test routes compared to US-EPA Tier2-Bin5 emissions standard; AWM reference metric is CO_2 emissions over NEDC

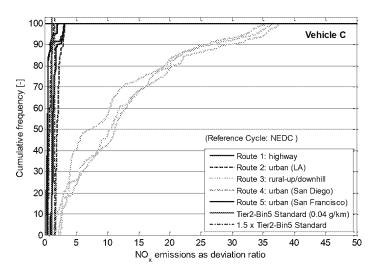


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle C over the five test routes expressed as deviation ratio; AWM reference metric is CO_2 emissions over NEDC

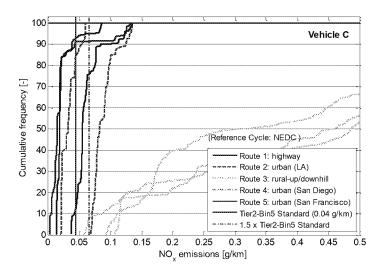


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Zoomed x-axis of [REF _Ref376978669 \h] showing averaging window NO_x emissions for Vehicle C over the five test routes compared to US-EPA Tier2-Bin5 emissions standard

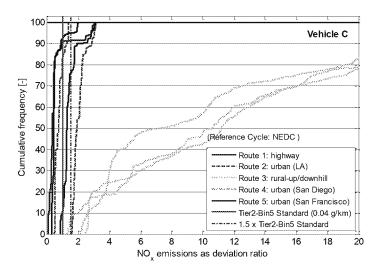


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Zoomed x-axis of [REF _Ref377052760 \h] showing averaging window NO $_x$ emissions for Vehicle C over the five test routes expressed as deviation ratio

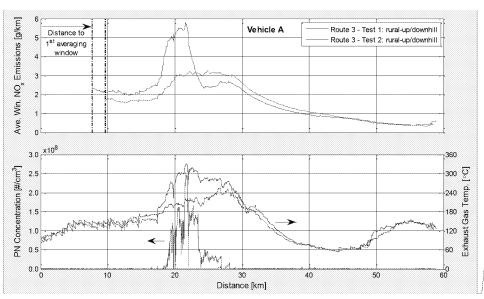


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: a) Continuous averaging window NO_x emissions, and b) particle number concentrations and exhaust gas temperatures (at exhaust tip) vs. distance for Route 3; test 1 with and test 2without DPF regeneration

[REF _Ref377826827 \h] through [REF _Ref377826884 \h] depict cumulative frequencies for averaging window NO_x emissions along with their deviation ratios from the US-EPA Tier2-Bin5 NO_x standard over the five pre-defined test routes, similarly to [REF _Ref377674181 \h] through [REF _Ref377824326 \h], however, with mass of CO_2 emitted over the FTP-75 cycle selected as window size threshold value (see [REF _Ref377672521 \h]).

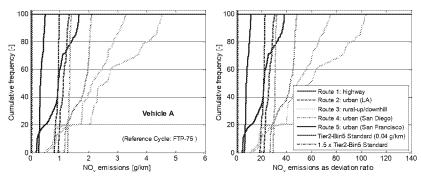


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle A over the five test routes compared to US-EPA Tier2-Bin5 emissions standard (*left*) and

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expressed as deviation ratio (*right*); AWM reference metric is CO₂ emissions over FTP-75; Route 1 includes rush-hour/non rush-hour driving

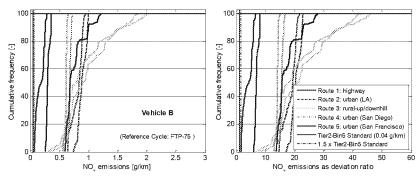


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle B over the five test routes compared to US-EPA Tier2-Bin5 emissions standard (*left*) and expressed as deviation ratio (*right*); AWM reference metric is CO₂ emissions over FTP-75

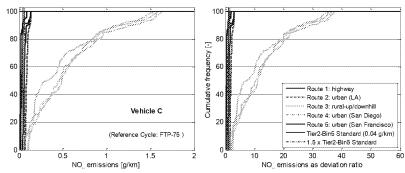


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle C over the five test routes compared to US-EPA Tier2-Bin5 emissions standard (*left*) and expressed as deviation ratio (*right*); AWM reference metric is CO₂ emissions over FTP-75

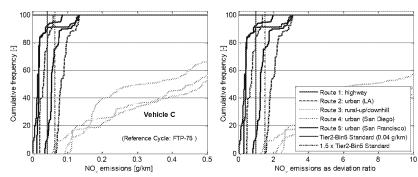


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Zoomed x-axis of [REF_Ref377052788 \h] showing averaging window NO_x emissions for Vehicle C over the five test routes compared to US-EPA Tier2-Bin5 emissions standard (*left*) and expressed as deviation ratio (*right*)

[REF _Ref377827838 \h] presents frequency distributions of exhaust gas temperatures for *Vehicles A* and *B* over two repeats of test Routes 1 through 4. These temperature distributions reflect exhaust gas temperatures measured by vehicle sensors (broadcasted via ECU CAN) downstream the DPF and upstream the deNO_x after-treatment devices for *Vehicle A* and *B*, respectively.

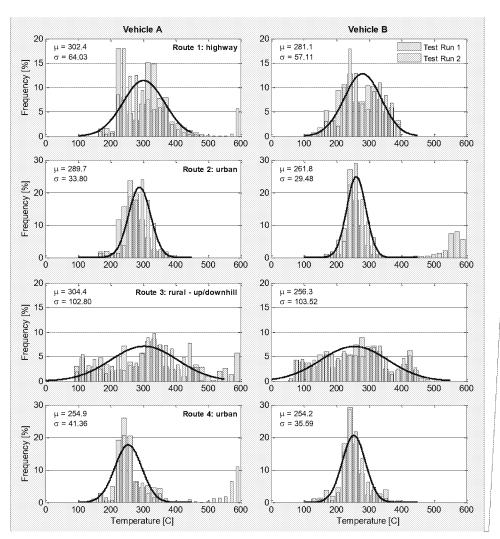


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Frequency distributions of exhaust gas temperatures at downstream DPF location for Vehicle A and B over Routes 1 through 4 with two repeats; data fitted by normal distribution (not including data for high temperature excursions during DPF regeneration events)

Each temperature dataset is fitted by a normal distribution curve (bold dark line) which does not include any data points from the high temperature excursions observed for Vehicle A, Routes 1, 3, and 4 as well as for Vehicle B, Route 2 (see [REF _Ref377827838 \h]). A distinct

Commented [FP19]: Figure 4-39 suggest that for Vehicle B, there was only one test route with DPF regen event only for Route 2, while figure 4-1 to 4-13 shows "R" on Route 1 also.

temperature distribution pattern can be noticed as a function of different driving conditions, namely, highway (i.e. Route 1), urban/suburban (i.e. Routes 2, 4), and rural-up/downhill (i.e. Route 3). Urban/suburban driving was found to exhibit narrow temperature distributions centered (μ) around 255 to 280°C with a spread (σ) of 30 to 40°C, whereas highway driving conditions led to increased mean exhaust temperatures ($\mu = 280$ to 300°C) owing to the elevated engine loads associated with high-speed driving, as well as a distinctively wider spread of the temperature distribution ($\sigma = 57$ to 64°C). On the other hand, rural-up/downhill driving was observed to exhibit a relatively large range of varying exhaust gas temperatures with the majority of values falling between 100 and 500°C ($\mu = 255$ to 300°C, $\sigma \approx 103$ °C). This is due to the particular characteristics of the test route (i.e. Route 3) that follows on the exact same street up and downhill to a turning point, leading to i) high exhaust temperature conditions during the uphill portion caused by increased engine load demand, and ii) low exhaust temperature conditions during the downhill portion where the vehicle predominantly coasts with fueling cutoff, thereby, effectively transforming the engine to an 'air-pump,' pumping intake air at ambient temperatures through the engine and after-treatment system cooling its components (e.g. catalysts) down.

Route 1 - test 2, Route 3 - test 1, Route 4 - test 2 for *Vehicle A* as well as Route 2 - test 1 for *Vehicle B* show a distinct second mode in the upper temperature range centered around 600°C. The observed increase in exhaust gas temperature is due to DPF regeneration events occurring during some of the test runs, where elevated temperatures are required to initiate the periodic soot oxidation from the surface of the filter substrate.

4.2.2 NO_x Emissions over Cross-Multi-State Driving Route

This section presents cumulative frequency plots for averaging window NO_x emissions in [REF _Ref377064175 \h] (Zoom-in to x-axis shown in [REF _Ref377832844 \h]) along with deviation ratios from the US-EPA Tier2-Bin5 standard for NO_x (at full useful life) in [REF _Ref377832562 \h] for *Vehicle B* over individual portions of the cross-multi state driving route with total CO_2 emitted over the NEDC (see [REF _Ref377672521 \h]) chosen as reference value for calculating averaging window size.

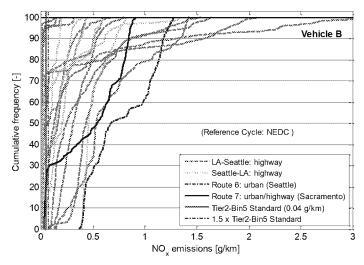


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle B over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard; AWM reference metric is CO_2 emissions over NEDC

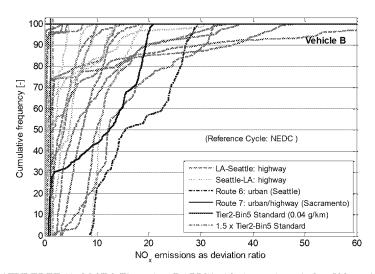


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Averaging window NO_x emissions for Vehicle B over cross-multi-state driving route portions expressed as deviation ratio; AWM reference metric is CO_2 emissions over NEDC

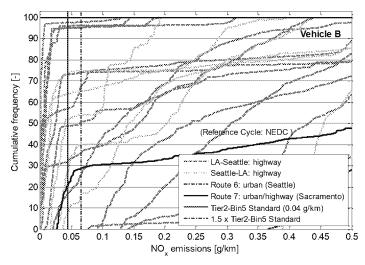


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Zoomed x-axis of [REF_Ref377064175 \h] showing averaging window NO_x emissions for Vehicle B over cross-multi-state driving route portions compared to US-EPA Tier2-Bin5 emissions standard

Overall, cumulative frequencies of averaging window NO_x emissions over the majority of individual portions of the cross-multi state driving route agree with results seen from the predefined test routes (see [REF _Ref377674373 \h]) for *Vehicle B*. It can be noticed that 50% of NO_x emissions during urban/suburban driving conditions (i.e. Routes 6 and 7) exceed the applicable standard by more than a factor of 10, similar to what was observed over urban Routes 2, 4, and 5. Route 7 exhibits a distinct change in NO_x emissions as can be seen from [REF _Ref377832844 \h] (dark filled line). This is due to a significant portion of highway driving (> 60% by distance) contained in this route which accounts for ~20% of NO_x emissions to be below the US-EPA Tier2-Bin5 standard whereas the smaller portion of the route (< 40% by distance) accounts for significantly increased NO_x levels with 50% of the emissions deviating by 10 to 20 times from the standard.

On the other hand, [REF _Ref377832844 \h] also shows that under particular conditions, *Vehicle B* was observed to emit-have NO_x emissions well below the US-EPA Tier2-Bin5 level, specifically with route portions 3, 4, 5, and 6 exhibiting ~95% of NO_x emissions below the regulatory standard.

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It is worthy to mention that DPF regeneration events did not seem to noticeably affect NO_x emissions from the urea-SCR based *Vehicle B* in the same manner as they were observed to influence NO_x emissions rates from the LNT equipped *Vehicle A*.

4.3 On-Road Particle Number and Mass Emissions

This section will present and discuss particulate number and mass emissions concentrations over the pre-defined test routes for *Vehicles A* and *B* in Section [REF _Ref377835442 \r \h] as well as over the cross-multi state driving route for *Vehicle B* in Section [REF _Ref377835457 \r \h]. It has to be noted that all PN and PM emissions concentrations presented herein are inferred from real-time particle measurements using a charge-type particle sensor (i.e. Pegasor particle sensor).

4.3.1 PN Emissions over Pre-Defined Test Routes

[REF _Ref377465934 \h] through [REF _Ref377465938 \h] present comparisons of raw particle number concentrations in units [#/cm³] between two consecutive test runs for Routes 1 through 4 and *Vehicles A* and *B* plotted against driving distance. It has to be noted that for the purpose of this comparison PN concentrations reflect raw particle concentrations in the exhaust stream per unit volume (i.e. cm³) and not total number of particles released from the engine which one could obtain by multiplying average PN concentration into total exhaust flow. Exhaust gas temperatures, as measured at the exhaust sample extraction point (i.e. at outlet of exhaust tip), are plotted along with PN concentrations to aid in identifying possible DPF regeneration events. To the right side of each continuous PN concentration and exhaust temperature graph is a bar chart providing PN emissions factors in [#/km] for each individual test (i.e. repetition of a given route) corresponding to PN results already presented in [REF Ref385262237 \h] during Section [REF Ref377374861 \rangle r \h].

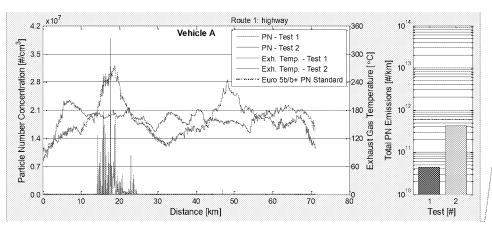


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 1 for Vehicle A, DPF regeneration event during test 2

[REF _Ref377465934 \h] and [REF _Ref377836643 \h] present PN emissions concentrations during highway driving (i.e. Route 1) for *Vehicles A* and *B*, respectively. *Vehicle A* can be noticed to have experienced a moderate DPF regeneration event between 15 and 25km into the test route leading to an order of magnitude increase in PN emissions factor for test 2 as compared to test 1. However, the observed regeneration event did not cause PN emission to exceed the Euro 5b/b+ PN standard. No DPF regeneration event is seen for *Vehicle B* during highway operation over Route 1.

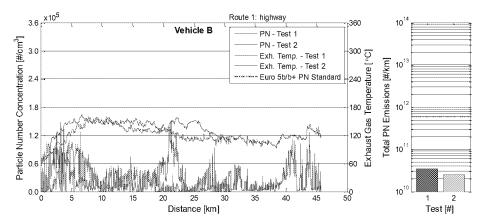


Figure [STYLEREF 1\s].[SEQ Figure * ARABIC\s 1]: Comparison of particle number concentrations between two tests of Route 1 for Vehicle B, No DPF regeneration event observed

Commented [FP22]: Please increase line thickness for PN and

Commented [FP23]: I think we figures 4-1 to 4-13 require to fix the "R" for Route 1.

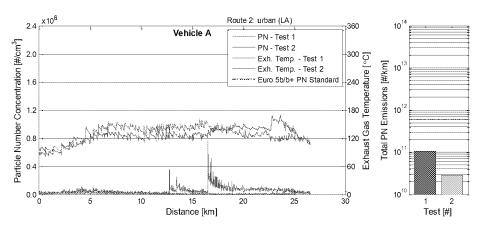


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 2 for Vehicle A, No DPF regeneration event observed

[REF _Ref377837211 \h] and [REF _Ref377837216 \h] show PN emissions concentrations during Route 2 for *Vehicles A* and *B*, respectively. Contrary to Route 1, during Route 2 driving *Vehicle B* exhibits a DPF regeneration event during the second half of the first test run as recognizable from either the significantly increased PN concentrations (> 2 orders of magnitude) or the increase in exhaust gas temperature by a factor of 2 when compared to test run 2 which lacks a regeneration event. Furthermore, the DPF regeneration event resulted in the PN emissions factor exceeding the applicable PN standard by an order of magnitude (i.e. $5.51 \times 10^{12} \text{ m/s}$ km vs. $6.0 \times 10^{11} \text{ m/s}$ km).

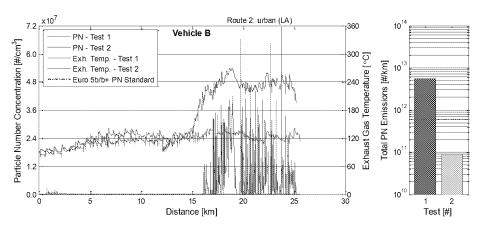


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 2 for Vehicle B, DPF regeneration event during test 1

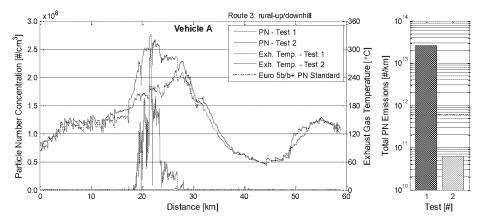


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 3 for Vehicle A, DPF regeneration event during test 1

[REF _Ref377837955 \h] and [REF _Ref377484439 \h] show PN emissions concentrations during Route 3 for *Vehicles A* and *B*, respectively, with DPF regenerations noticed for both vehicles. *Vehicle A* exhibited a regeneration event during the uphill portion of the first test run (at 18 to 27km) with the PN standard being exceeded by two orders of magnitude $(2.61 \times 10^{13} \text{#/km})$, whereas *Vehicle B* showed repeatable signs of moderate regeneration events at the same location for both test runs. Also, PN emissions factors for

Vehicle B are exceeding the Euro 5b/b+ PN standard during both consecutive test runs of Route 3.

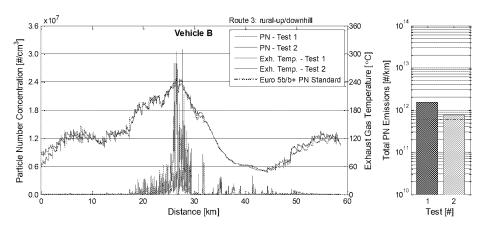


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 3 for Vehicle B, DPF regeneration event during both tests

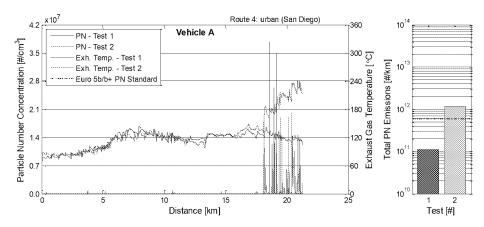


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 4 for Vehicle A, DPF regeneration event during test 2

Finally, [REF _Ref377838597 \h] and [REF _Ref377465938 \h] show PN emissions concentrations during Route 4 for *Vehicles A* and *B*, respectively. While *Vehicle B* does not experience any DPF regeneration event with PN emissions factors remaining well below the regulatory standard, *Vehicle A* exhibits the onset of a regeneration event towards the end of the

second repetition leading to PN emissions one order of magnitude greater than observed for the test run without event.

Additionally, it is interesting to notice that while there was no DPF regeneration event occurring exhaust gas temperatures for both vehicles show a strong similarity. This can be explained by the fact that both *Vehicles A* and *B* are equipped with an identical engine that most likely is programmed with same or at least nearly same base calibration parameters. Also, the actual vehicle test weight only differed by 29kg between *Vehicle A* and *B* leading to similar load conditions for both engines during testing.

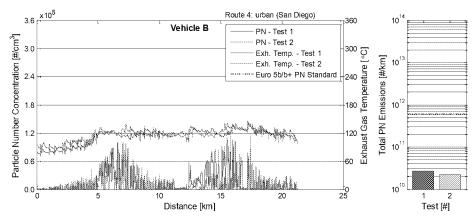


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Comparison of particle number concentrations between two tests of Route 4 for Vehicle B, No DPF regeneration event observed

4.3.2 PM and PN Emissions over Cross-Multi-State Driving Route

This section presents raw particulate number and mass emissions concentrations in the exhaust stream in [REF _Ref377893598 \h] and [REF _Ref377893600 \h], respectively, for *Vehicle B* over the entire cross-multi state driving route. Four distinct DPF regeneration events can be noticed in [REF _Ref377893598 \h] from predominant particulate number concentration (blue line) spikes that increase by four orders of magnitude to 1.4×10^8 #/cm³ over the typical concentration level of 2×10^4 #/cm³. These events of drastic increase in particulate number concentrations are accompanied, as expected, by excursions in exhaust gas temperatures as thermal conditions of after-treatment and exhaust stream are increased in order to initiate soot oxidation on the DPF substrate. Exhaust gas temperatures were observed to increase from typical

levels throughout the route of $\sim 320^{\circ}\text{C}$ to $\sim 560^{\circ}\text{C}$ during the DPF regeneration events. It has to be noted that temperatures depicted in [REF _Ref377893598 \h] and [REF _Ref377893600 \h] were measured at post SCR location by an on-board temperature sensor, acquired via ECU CAN interrogation.

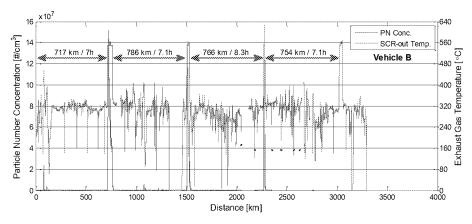


Figure [STYLEREF 1 \s].[SEQ Figure * ARABIC \s 1]: Particle number concentration and exhaust gas temperature at SCR outlet location of test vehicle over cross-multi-state driving route;

Note: PN concentration spikes indicate DPF regeneration events

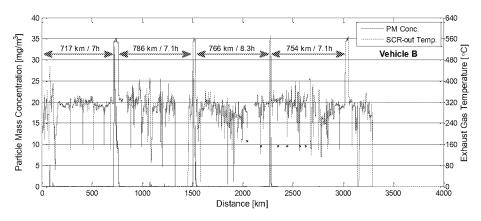


Figure [STYLEREF 1 \s]. [SEQ Figure * ARABIC \s 1]: Particle mass concentration and exhaust gas temperature at SCR outlet location of test vehicle over cross-multi-state driving route; Note: PN concentration spikes indicate DPF regeneration events

Even though four distinct exhaust gas temperature excursions can be noticed from [REF _Ref377893598 \h], thus indicating four DPF regeneration events throughout the entire route, only three particulate number concentration spikes are observed. This is due to the fact that the real-time particle sensor was not operational after ~2600km as the electrical air compressor providing pressurized air to the sensor had failed. However, even though lacking actual particle measurements, but solely based on the preceding data it can be concluded with the necessary confidence that the temperature excursion around 3023km is indicative of a DPF regeneration event.

It is interesting to notice from [REF _Ref377893598 \h] that DPF regeneration events are nearly equally spaced both on a spatial (i.e. distance traveled) and temporal (i.e. duration between event) basis as can be seen from [REF _Ref377896942 \h]. On average the vehicle traveled approximately 756km ±29km (±1 σ) between individual regeneration events which was observed to correspond to \sim 7.07hours \pm 0.06hours (\pm 1 σ , not including third event) on a temporal basis. Even though the distance traveled between events 2 and 3 is of similar length than for other events, the time required was observed to be ~17% longer (7.07hours vs. 8.3hours). A possible explanation for this difference is that the route between regeneration events 2 and 3 included low vehicle speed urban/suburban driving in and around Seattle, WA, leading to increased travel time to accumulate ~756km. Overall, these results ultimately lead to conclude that DPF regeneration intervals are predominantly distance based which agrees with descriptions given for after-treatment control strategies for Vehicle A in [[REF Ref377811821 \r \h]] (see from Figure 12 in [[REF Ref377811821 \r \h]]) which are most likely similar to Vehicle B as well as the same engine and DPF configurations are used in both vehicles. Furthermore, the observed average duration of a DPF regeneration event was_15min ±6min (±1σ) as seen from [REF _Ref377896942 \h], thereby in agreement with system descriptions provided in [[REF Ref377811821 \r \h]].

Table [STYLEREF 1 \s]. [SEQ Table * ARABIC \s 1]: Distance and time based DPF regeneration frequencies and duration for Vehicle B over cross-multi state driving route

	istance to vent [km]	Distance based fregen [km]	Time to event [hr]	Time based fogen [hr]	Duration [min]
1	717	717	7.0	7.0	22.4
2	1,503	786	14.1	7.1	15.2
3	2,269	766	22.3	8.3	7.5

[REF _Ref364015491]

5 CONCLUSIONS

Three light-duty diesel vehicles of European make, equipped with two different NO_x abatement technologies, namely lean-NO_x trap and urea-based selective catalytic reduction system, and certified to US-EPA Tier2-Bin5 and CARB LEV-II ULEV (CA) emissions standards were operated over a variety of pre-defined test routes exhibiting diverse driving conditions pertinent to major US population centers located in the state of California. Additionally, one vehicle, specifically *Vehicle B*, was driven over an extended distance of nearly 4000km predominantly composed of highway driving conditions between California and Washington State. Gaseous emissions of NO_x, CO, THC and CO₂ were measured using the OBS-2200 PEMS from Horiba Ltd., while particulate number and mass concentrations were inferred from real-time particle charge measurements employing a Pegasor particle sensor.

In summary, real-world NO_x emissions were found to exceed the US-EPA Tier2-Bin5 standard (at full useful life) by a factor of 15 to 35 for the LNT equipped Vehicle A, by a factor of 5 to 20 for the urea-SCR fitted Vehicle B (same engine as Vehicle A) and at or below the standard for Vehicle C with exception of rural-up/downhill driving conditions, over five predefined test routes. Generally, NO_N emissions were observed to be highest for rural-up/downhill and lowest for high-speed highway driving conditions with relatively flat terrain. Interestingly, NO_x emissions factors for Vehicles A and B were below the US-EPA Tier2-Bin5 standard for the weighted average over the FTP-75 cycle during chassis dynamometer testing at CARB's El Monte facility, with $0.022g/km \pm 0.006g/km (\pm 1\sigma, 2 \text{ repeats})$ and $0.016g/km \pm 0.002g/km (\pm 1\sigma, 3$ repeats), respectively. Additionally, increased variability between consecutive test runs was observed for Vehicle A coinciding with DPF regeneration events, leading to an increase in NOx emissions by 97% (0.41 g/km to 0.81g/km), 19% (1.38g/km to 1.63g/km), and 38% (1.24g/km to 1.72g/km) for Routes 1, 3, and 4, respectively, between test runs with and without DPF regeneration events. This was speculated to be due to an extended duration of lean exhaust conditions and a lack of frequent enrichment of the exhaust gas ($\lambda < 1$) while DPF regeneration was ongoing, leading to an inhibition of necessary LNT regeneration (DeNOx), and thus, causing the NO_x storage catalyst to become saturated with NO_x emissions that ultimately started to break through. The probability of this explanation is additionally supported by a detailed description of the after-treatment control strategy for Vehicle A presented elsewhere [[REF Ref377811821 \r \h]].

Commented [VF24]: distance-specific NOx

NO_x emissions emitted byof Vehicle B over the cross-multi state driving route, comprising predominantly highway driving, were observed to be on average $0.26g/km \pm 0.21g/km (\pm 1\sigma)$ or approximately 6 times exceeding the US-EPA Tier2-Bin5 standard. However, most interestingly NO_x emissions were found to be below the regulatory standard for portions of the route characterized by low or negligible changes in altitude (i.e. near zero road grade), and with the vehicle operated in cruise-control mode at approximately 120km/h while traveling northbound on Interstate 5 through the San Joaquin Valley (see route portions 3 through 6 in [REF_Ref377492996 \h]).

In general, CO and THC emissions were observed to be well below the regulatory level for all three test vehicles and driving conditions, with exception of Routes 1 and 2 for *Vehicle A* where THC emissions were seen to exceed the regulatory level by a small margin (< factor 1.25). Highest THC emissions for *Vehicle A* coincided with lowest NO_x emissions however, no conclusive explanation can be presented herein for why this behavior was observed.

As expected, highway driving showed lowest CO2, whereas urban/suburban driving conditions lead to highest CO₂ emissions factors for all vehicles. Since both Vehicles A and B were equipped with the same engine and similar test weights (i.e. 1855kg vs. 1884kg), comparable CO₂ consumption patterns were observed in agreement with results obtained during chassis dynamometer testing over the NEDC for urban/suburban and highway driving portions. It has to be noted that the equivalent vehicle test weight during chassis dynamometer testing was 1701kg for both Vehicles A and B, or ~8% lower compared to vehicle weights during on-road PEMS testing. Finally, CO₂ emissions factors for Vehicle C were observed to exceed the EPA/NHTSA CO2/CAFE standard for the applicable LDT4 vehicle category with an actual vehicle test weight of 2903kg. The equivalent test weight for CO₂ emissions evaluation as per EPA procedure is 2495kg, or ~14% lower compared to the actual vehicle weight during on-road PEMS testing. Average fuel economy for highway driving with Vehicles A and B was 45.3 mpg ±8.6mpg (±σ1) and 43.7mpg ±5.7mpg (±σ1), respectively, and 27.3 mpg (no repetition) for Vehicle C which is ~39% lower compared to Vehicles A and B. On the other hand, urban/suburban driving results in average fuel economies of 30.0mpg ±2.9mpg (±σ1) and 26.6 mpg ± 1.4 mpg ($\pm \sigma 1$) for Vehicles A and B, respectively, and 18.5mpg ± 4.0 mpg ($\pm \sigma 1$) for Vehicle C which is 35% lower compared to Vehicles A and B. Overall, urban/suburban driving leads to a 32-39% reduction in fuel economy over highway driving.

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Particulate matter mass emissions, inferred from PPS measurements, were observed below the US-EPA Tier2-Bin5 standard for *Vehicles A* and *B*. On the other hand, particulate number emissions were found to exceed the Euro 5b/b+ PN standard during DPF regeneration events increasing by 2 to 3 orders of magnitude over emissions levels measured during none-regeneration events. It is noted that PN is not regulated in the United States. During the multistate driving route, DPF regeneration frequency for *Vehicle B* was established to be predominantly based on distance traveled, occurring after every 756km \pm 29km (\pm 1 σ), corresponding to ~7.07hours \pm 0.06hours for highway driving conditions.

It is noted that only three vehicles were tested as part of this measurement campaign with each vehicle being a different after-treatment technology or vehicle manufacturer; conclusions drawn from the data presented herein are confined to these three vehicles. The limited data set does not necessarily permit drawing more generalized conclusions for a specific vehicle category or after-treatment technology.

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7 APPENDIX

7.1 Exhaust Emissions Calculations with Horiba OBS-2200

7.1.1 Time alignment of real-time emissions concentrations

The individual emissions concentrations are shifted to account for transport delays from the sampling plane (reference point) to the analyzer cells through the heated transfer line, heated filter and internal plumbing of the OBS. This is done in order to time-align the concentration values with the respective exhaust flow rates for calculation of time-specific mass emissions rates. Exhaust concentration alignment is automatically performed by the OBS software, hence; the emissions concentrations reported in the data sets (csv-files) are already time-aligned. Transport delay times (T₅₀) are calculated from spike-recovery tests during the calibration and initial setup of the OBS instrument. The csv-files report the delay times in column 'E' in the file header.

7.1.2 Drift correction of real-time emissions concentrations

Drift corrections of the emissions concentrations are performed in order to account for possible analyzer drift over the measurement period. Prior to data collection over a test route, 'pre-zero' and 'pre-span' adjustments are performed for each analyzer. Upon completion of a test route, 'post-zero' and 'post-span' values are automatically collected by the OBS software for each analyzer. If the duration of a test route exceeds one hour (i.e. 3600 seconds), the OBS will automatically interrupt data collection for a period of 30 seconds to perform a 'post-zero' and 'post-span' check as well as make zero/span adjustments for each analyzer before continuing with data collection. Zero-drift and span-drift values are reported in columns 'P and 'P, respectively of the csv-file. Using these values, the OBS software automatically performs a drift correction of the real-time emissions concentration values upon completion of data collection (e.g. end of test route) using Equation (1).

7.1.3 Averaging Window Method (AWM)

In this method emission rates are integrated along with one of the listed criteria from time $t = 0.0 \ sec$ until the chosen criteria has reached a target value. The target values are normally derived from standardized test cycles used in certifying engine families in test cell. The time interval between $t_{start} = 0.0 \ sec$ to $t_{end} = x.x \ sec$ where the integrated value of the chosen criteria

is equal to its target is called a window, and for a moving window method the process is repeated with a new starting time being $t_{start} = 0.0 + 1.0 \text{ sec}$ until a new window is achieved. Emissions rates of regulated pollutants are integrated for the above criteria windows, and have to meet the set in-use emissions standards. The criteria windows are valid only if the average engine power for each window is greater than or equal to 20% of maximum engine power. Similarly for an in-use test to be valid there should be at least 50% of criteria windows should be valid. If there are no 50% valid criteria windows in an in-use test then the window validity condition is reduced as low as 15% of maximum engine power in increments of 1% of average power.

Commented [FP26]: we probably need a sentence explaining that in this project all the windows were accounted for

7.2 Particle Number Measurement with European PMP Method

Streamlined with the introduction of PN limits (i.e. Euro 5b/b+ [[REF _Ref382821534 \r \h]]), the European Union adopted a new methodology aimed at standardizing the measurement of total particle number concentrations by only counting solid particles having a diameter between 23nm and 2.5µm and that are thermally treated in order to reduce the volatile fraction, thus reducing measurement artifacts and variability [[REF _Ref383388345 \r \h]]. This method has been previously developed under the Particle Measurement Program (PMP) of the United Nation's Economic Commissions for Europe - Group of Experts on Pollution and Energy (UN-ECE-GRPE) [[REF _Ref383388676 \r \h], [REF _Ref383388677 \r \h], and [REF _Ref383388678 \r \h]] leading to the following operational definition of particle numbers: 'measurement of solid particles having a diameter between 23nm and 2.5µm and are of sufficiently low volatility to survive a residence time of 0.2sec at 300°C' [[REF _Ref383388698 \r \h]].

The sampling system comprises a volatile particle remover (VPR) and an ultrafine particle counter optimized for a 50% counting efficiency for 23nm size particles. The VPR is designed to remove the volatile and semi-volatile fractions in the exhaust sample, thereby aiming at suppressing particle nucleation and the formation of artifacts in the sample stream. A first stage hot dilution (at 150 to 400°C and dilution ratio of 10) is used to reduce particle concentration in the sample before being directed into the evaporation tube (operated at 300 to 400°C) where the volatile and semi-volatile components are being transferred to a gaseous state. It follows a second cold dilution stage (dilution ratio between 10 to 15) to i) rapidly lowering the partial

pressures of the gaseous components aimed at preventing their re-condensation, and ii) lowering the sample temperature to below 35°C prior to entering the particle counting device. The Pegasor particle sensor for example has the advantage of not having a very limited range requirement for sample inlet temperatures (up to ~800°C), thus allowing for direct measurement of raw exhaust gases and thereby ultimately reducing the magnitude of size dependent particle losses as occurring in the VPR.

However, the PMP approach for particle number measurements has come under scrutiny as recent studies have on one hand observed significant semi-volatile particles downstream the VPR [[REF _Ref383388732 \r \h], [REF _Ref383388736 \r \h]], and on the other hand measured increased concentrations of particles below the size of 23nm being emitted from DPF equipped vehicles. These ultrafine particles are believed to comprise sulfuric acid and assumed to be emitted from catalytic oxidation of sulfur from lubrication oil [[REF _Ref383388742 \r \h], [REF _Ref383388745 \r \h], and [REF _Ref383388748 \r \h]]. Johnson et al. [[REF _Ref383388698 \r \h]] evaluated the European PMP methodology during on-road vehicle testing and observed a significant portion of particles in the size range below 20nm even though the sample stream was thermally treated according to PMP requirements, thus questioning the applicability of the 23nm lower cut-point for particle measurements, as mandated by the European PMP regulation.

7.3 ULSD Fuel Analysis for Vehicles A and B



Certificate of Analysis Lab Number V7012631A

Francisco Posada Sanchez The International Council on Clean Transportation 1225 "I" Street NW, Suite 900 Arlington VA 20005

03/12/13

Page 1

Client Code: THEICF Sample Date : 02/25/13

Berguin ID: LABV7012631

Description : Commercial Grade Diesel Feel Oil Type : Diesel Fuel (GN_130)

Unit Type: Diesel Fact (GN_DF001)

Test Performed	Proc-Rev	Result
Suifur by Microconlometry ASTM D3126	3120-3.1	i mg/kg
Density @ LSC ASTM D4052	4052-1.7	0.8355 g/ml.
Biosliesel Blend as FAME by FTIR HL-1141A	1141A-1.1	0.32 vol. %
Aromatic Centent & PAH by SFC ASTM D5186	5186-1.0	
Mono-Aromatics ASTM D5186		13.9 % wi
Polynaclear Aromatic Hydrocarbons, PAH ASTM D5186		1.7 % wt
Total Aromatics ASTM D5186		15.6 % wt
Witimatic Analysis	5291-E.0	
Carbon ASTM D5291		86.16 mass %
Hydrogen ASTM D529		13.67 mass %

REVISED REPORT supersedes lab θ V7012631 and includes additional test results.

Data is reported per offent specified testing request.

Fourier Transform Infrared Analysis (FTIR) of the fact sample submitted shows the percent of Fatty Acid Methyl Ester (FAME) component in the -1750 cm-1 wavenumber region. FAME is the major indicator for Biodiesel. The FTIR was calibrated based on standards prepared by blending Diesel with B100 Soy Biodiesel. Aromatic Content & PAH by SFC and Ultimate Analysis was subbed out.

> Respectfully Submitted, SGS Herguth Laboratories, Inc.

> > Allendaria.

co: Francisco Passala Sanchez

Bobby R Lica, Evaluations Manager

P.O. Nomber: POSTED CASH

These medits are suberlied person to our outer Terro, Conditions and Liebzbiers and Liebzbiers and Extractor, Princip Princy No responsible or lackly is assumed in the momen in which these conditions us used to interpreted. IDI Componente Plane, Vallejis, CA 94564-8968 * Toll-Tree Phane I-988-645-5227 * Plan I-787-554-0108 * was alterjush norm

ISO 9001:2008 and ISO/IEC 17025:2005 Certified

3656008-85 (Rev. \$600001)